Dissect an ML algorithm for potential forms of interactivity

Krzysztof Gajos



HARVARD School of Engineering and Applied Sciences

Dissect interactivity for potential ML algorithm

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Hall of Fame? Hall of Shame?

CueTIP

A Mixed-Initiative Interface for Correcting Handwriting Recognition Errors

> Michael Shilman, Desney S. Tan, Patrice Simard

> > © 2006 Microsoft

http://research.microsoft.com/en-us/um/people/desney/publications/UIST2006-CueTIP.mov

Today's Mantra

- Pick appropriate interaction for the task
- Understand the semantics of the interaction
- Develop/pick an algorithm that uses available information correctly and efficiently

Supple Project: Automatically Generating User Interfaces

DESIGN

Design by Genius

Specification



Design by Exploration





Properties

Adaptation to Devices

Classroom			
Light Bank	A/V Controls	Vent	
Left	Projector		
Light Level	Power: On	Classroom	
Off << 7 >>		Light Bank A/V Controls Ve	ent
Center	Computer 1	C	lassroon 🐺 👷 ┥< 10:03 🗴
Light Level		Projector /u	ght Bank A/V Controls +
On << 7 >>	Computer 2	Power: Input:	
Off		Computer 1	ojector
Right			Power Input
Light	Video		Computer 1
On << 7 >>			Computer2
Off	Screen: Lowered	Revert to Defaults Submit	Video
O Classroom	OLight Bank	SELECT	Screen
Light Bank	Light: <un> 6 evel: <7></un>		
A/V Controls	Center	A/V Controls	Vent
Power: <on></on>	Light: <on> +</on>	Center Right Projector	Off ■▲
		✓ Light	ower
		Level Input Com	iputer 1
			⊖ Med
		Sector Se	creen 🔘 High

Folders	Messages	
New Rename De	lete Expunge New Reply Forwa	ard Delete Move
Junk-E-Mail	05.02 12:53 PM Lucy Dunne <lucy.dunne@an< td=""><td>mail.com> [Announcements] ISWC 2008: Ca</td></lucy.dunne@an<>	mail.com> [Announcements] ISWC 2008: Ca
Unerwünscht	01.02 08:30 AM uwgradevents@u.washington	n.edu [UWgradevents] Career Events for Gra
Unbekannt2	31.01 05:20 PM Varshavsky Alex <walex@cs< td=""><td>.toronto.edu> Pervasive 2008 Late Breakin</td></walex@cs<>	.toronto.edu> Pervasive 2008 Late Breakin
Deleted Messages	31.01 05:02 PM Varshavsky Alex <walex@cs.< td=""><td>.toronto.edu> Pervasive 2008 Late Breakin</td></walex@cs.<>	.toronto.edu> Pervasive 2008 Late Breakin
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astmail	Details	
	Senders: khai@cc.gatech.edu	
D + 1	Date: Mon Feb 21 12:07:11 PST 2005	
Details	Recipients: announcements@ubicomp.org	
Account Details	Subject: [Announcements] PERVASIVE 2005: Extended Workshop Dea	dlines, Ad
	Content	
	<text charset="us-ascii" plain:=""></text>	
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web.de IMAP	**********ADVANCE PROGRAM / REGISTRATION****************	
Reply Address: supple@web.de	The advance program of PERVASIVE 2005 is now online	
suppregneside	http://www.pervasive.ifi.lmu.de/program.html	
From Address: supple@web.de		
	http://www.pop/asive.ifi.lmu.de/registration.html	
	Registration for a workshop only is available	
	Registration for a workshop only is available.	
	*********WORKSHOP DEADLINES EXTENDED******************	
Add Account Remove Acco	Some Pervasive 2005 workshops have extended their	
	deadlines for another week. Please take advantage of the	
	opportunity to present your research results in one of	
	the following workshops:	
	W2:International Workshop on Software Techniques for Embedded	
	and Pervasive Systems (STEPS), 2005	
	(deadline extended to March 1st)	
	http://www.pervasive.ifi.lmu.de/workshop.html#W2	
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Configurati	W3:PerGames 2005: Second International Workshop on Pervasive	
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Design as Optimization

- How to enumerate the design space?
- How to evaluate solution quality?
- How to find the optimal solution efficiently?

Design as Optimization

- How to enumerate the design space?
- How to evaluate solution quality?
- How to find the optimal solution efficiently?

Evaluating Solution Quality











Factoring Cost Function

Cost of a particular rendering of a functional specification S

cost(rend(S)) =

 $\sum_{e \in S} \operatorname{cost}(rend(e))$

Sum over all elements of the functional specification Cost of a rendering of an element *e*

Factoring Cost Function

$$\cot(rend(S)) = \sum_{e \in S} \cot(rend(e))$$

 $cost(rend(e)) = \sum_{k=1}^{K} u_k f_k(rend(e))$ A weight A factor reflecting presence, absence or intensity of some property

Container factor weight: 0.0 Tab Pane factor weight: 100.0 Popup factor weight: 1.0 Spinner for integers factor weight: 5.0 Spinner (domain size) factor weight: 49.5238 Spinner for non-integers factor weight: 6.0 Slider factor weight: 45.7143 Progress bar factor weight: 0.0 Checkbox factor weight: 0.0 Radio button factor weight: 0.5 Horizontal radio button factor weight: 10.0 Radio button (>=4 values) factor weight: 0.0 Dadia huttan (N-0, valuas) fastar vusieht. 7/ 2057

How Good Is This Interface?



How Good Is This Movie?



The construction of preferences for crux and sentinel product attributes

Erin Faith MacDonald^a*, Richard Gonzalez^b and Panos Papalambros^a



Here or There Preference Judgments for Relevance

Ben Carterette¹, Paul N. Bennett², David Maxwell Chickering³, and Susan T. Dumais²

¹ University of Massachusetts Amherst
 ² Microsoft Research
 ³ Microsoft Live Labs

Abstract. Information retrieval systems have traditionally been evaluated over absolute judgments of relevance: each document is judged for relevance on its own, independent of other documents that may be on topic. We hypothesize that preference judgments of the form "document A is more relevant than document B" are easier for assessors to make than absolute judgments, and provide evidence for our hypothesis through a study with assessors. We then investigate methods to evaluate search engines using preference judgments. Furthermore, we show that by using inferences and clever selection of pairs to judge, we need not compare all pairs of documents in order to apply evaluation methods.

1 Introduction



The notion of volorspace can be menovalized to a model goals of abgelite

Preference Statements Through Example Critiquing

Stereo	
Power Volume 4	🗌 X-Bass
Tape CD Tur	ner
Mode	< Play
Tape 1	(Play >)
O Tape 2	Stop
Reverse	Pause
Dolby Noise Reduction	<< >>>

Preference Statements Through Example Critiquing



Result of a Critique

Stereo			
Power Volume 4	🗌 X-Bass		
Tape CD Tur	ner		
Mode	< Play		
Tape 1	(Play >)		
O Tape 2	Stop		
Reverse	Pause		
Dolby Noise Reduction	<< >>>		

Stereo	
Volume	Tape CD Tuner Mode
	 Tape 1 Tape 2
	Reverse Dolby Noise Reduction
	< Play Play > Stop Pause << >>
🗌 X-Bass	

before

after

Result of a Critique Provides feedback to the system

Stereo	Stereo	
Power Volume 4 💽 🗆 X-Bass	✓ P	Power Tape CD Tuner
Tape CD Tuner Mode < Play ① Tape 1 Play > ② Tape 2 Stop □ Reverse Pause □ Dolby Noise Reduction <<	Volun	me Mode Tape 1 Tape 2 Reverse Dolby Noise Reduction < Play Play > Stop Pause
	□ ×-	(-Bass

before

after

Active Elicitation via Pairwise Comparisons

In general, how do you prefer Level to be displayed?				
Option A		Option B		
Level 7		Level		
	Your c	choice:		
O Option A O Neither		Option B		
Submit				

In isolation, sliders are preferred



But in some contexts combo boxes may be better

Classroom		
Light Bank	A/V Controls	Vent
Left	Projector	
🗹 Light	Power	 Off
Level 7 Center Center Light Level 7 Right Level 7 Light Level 7	Input Computer 1 Computer2 Video Screen	O Low

Light I	Bank	A/V Controls	Vent
Left			
🗹 Light	Leve		
	_		
Center			
🗹 Light	Leve		
0	_	(
Right			
🗹 Light	Level		
	_		

Situated Feedback with Active Elicitation

<u></u>	In general, how	do you prefei	r Classroom to be displayed?	
Option A			Option B	
Classroom			Classroom	
Light Bank	A/V Controls	Vent	Light Bank A/V Controls Vent	
☑ Light	Power	• Off	Light Level	
Level 7 Center Light Level 7 Right Light Level 7 T	Input Computer 1 Computer2 Video	O Low O Med	Center Center Light Light Right Light Light Level Light	
		Your c	hoice:	
Option A	Option A O Neither O Option B			
Submit				

The Semantics of the Interactions





$$\sum_{e \in S} \sum_{k=1}^{K} u_k f_k(rend_1(e)) \ge \sum_{e \in S} \sum_{k=1}^{K} u_k f_k(rend_2(e))$$

Formalizing the Learning Problem

Set up an optimization problem that maximizes:

$$margin - \sum_{i} slack_{i}$$

Subject to the constraints:

$$\sum_{e \in S} \sum_{k=1}^{K} u_k f_k(\operatorname{rend}_1(e)) - \sum_{e \in S} \sum_{k=1}^{K} u_k f_k(\operatorname{rend}_2(e)) \ge margin - slack_i$$

 $u_k \ge 0$

 $u_k \leq C$

Results

R

$\bigcirc \bigcirc \bigcirc \bigcirc$	Factored Cost Query			
In general, how do you prefer Track to be displayed?				
Optio	n A	Option B		
Track 1		Track 1		
Your choice:				
Option A	💿 Neithe	r 🔘 Option B		
Submit				



Classroom Light Bank Left Light Level 7	A/V Controls Projector Projector Power Input Computer 1 Computer2 Video	0		Result	S	
after 5 interactions	Light Bank Left Cen Light On Cen Light Cen Light Level 7 Cen Light Level 7 Lev A/V Controls Projector Power On Cen Input Ven	t Computer	Right Light On Level 7 Classroom Light Bank A/V Co Left Center	ontrols Vent Right Light		
	afte intera	er 15 actions	after 20 interactions	Classroom Light Bank Left I Light Level 7 Center Light Level 7 Right Light Level 7 I Light Level 7	A/V Controls Projector Power Input Computer 1 Computer2 Video Video	Vent Off Low Med



Classroom						
Light Banl	k A/V Co	ontrols Ve	nt			
Left		Center		Right		
Light	Level	Light	Level	Light	Level	
	0		0		0	
	1		1	On	1	
On	2	On	2		2	
	3		3		3	
	4		4		4	
	5		5		5	
	6		6	Off	6	
	7		7		7	
Off	8	Off	8		8	
	9		9		9	
	10		10		10	

Print						
Printer						
Name Canon Photo 💌	Print to File					
Status: Idle						
Type: Ink jet	Manual Duplex					
Where: Printer room						
Page range	Copies					
All	Number of copies 1					
🔾 Current Page						
Pages	Collate					
Print Content	Zoom					
Print what Document	Print what 1 page					
Print All pages in range	Scale to paper size No Scaling					
Dk	Ca Print Printer Name Name Status: Idle Canon Photo Page range Copies Epson Stylus Print what Scale to paper size HP Deskjet Type: Ink jet 2 pages Lexmark Inkjet Vhere: Printer room 6 pages Kerox Phaser Where: Printer room 6 pages Print to File: false Manual Duplex: false 16 pages					
	Ok Cancel					

Learning a Distance Metric from Relative Comparisons

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Department of Computer Science Cornell University Ithaca, NY 14853 {schultz,tj}@cs.cornell.edu

Abstract

This paper presents a method for learning a distance metric from relative comparison such as "A is closer to B than A is to C". Taking a Support Vector Machine (SVM) approach, we develop an algorithm that provides a flexible way of describing qualitative training data as a set of constraints. We show that such constraints lead to a convex quadratic programming problem that can be solved by adapting standard methods for SVM training. We empirically evaluate the performance and the modelling flexibility of the algorithm on a collection of text documents.

1 Introduction

Distance metrics are an essential component in many applications ranging from supervised

Semantics of bookmark / like / plus / star

Concerns in UI Design

- Perceptual effort
- Cognitive effort
- Motor effort
- Aesthetics



Adapting to Motor Abilities

cost(



= time

Collect Motor Performance Data



What we get in the wild

What we want



Deliberate, targeted movements

Deliberate, targeted movement?



Data from a Fositiae expaniplest











Data from a formal experiment







Data from in situ observations Mix of unlabeled +ve and -ve examples

Data from a formal experiment





classifier

[Elkan & Noto, KDD'08]

Data from in situ observations Mix of unlabeled +ve and -ve examples

Positive Examples

You can take a quick break now



classifier

[Elkan & Noto, KDD'08]

Unlabeled Examples

Learning Classifiers from Only Positive and Unlabeled Data

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ABSTRACT

The input to an algorithm that learns a binary classifier normally consists of two sets of examples, where one set consists of positive examples of the concept to be learned, and the other set consists of negative examples. However, it is often the case that the available training data are an incomplete set of positive examples, and a set of unlabeled examples, some of which are positive and some of which are negative. The problem solved in this paper is how to learn a standard binary classifier given a nontraditional training set of this nature.

Under the assumption that the labeled examples are selected randomly from the positive examples, we show that a classifier trained on positive and unlabeled examples predicts probabilities that differ by only a constant factor from the true conditional probabilities of being positive. We show how to use this result in two different ways to learn a classifier from a nontraditional training set. We then apply these two new methods to solve a real-world problem: identifying protein records that should be included in an incomplete specialized molecular biology database. Our experiments in this domain show that models trained using the new methods perform better than the current state-of-the-art biased SVM method for learning from positive and unlabeled examples.

1. INTRODUCTION

The input to an algorithm that learns a binary classifier consists normally of two sets of examples. One set is positive examples x such that the label y = 1, and the other set is negative examples x such that y = 0. However, suppose the available input consists of just an incomplete set of positive examples, and a set of unlabeled examples, some of which are positive and some of which are negative. The problem we solve in this paper is how to learn a traditional binary classifier given a nontraditional training set of this nature.

Learning a classifier from positive and unlabeled data, as opposed to from positive and negative data, is a problem of great importance. Most research on training classifiers, in data mining and in machine learning assumes the availability of explicit negative examples. However, in many real-world domains, the concept of a negative example is not natural. For example, over 1000 specialized databases exist in molecular biology [7]. Each of these defines a set of positive examples, namely the set of genes or proteins included in the database. In each case, it would be useful to learn a classifier that can recognize additional genes or proteins that should be included. But in each case, the database does not contain any explicit set of examples that should not be included, and it is unnatural to ask a human expert to identify such a set. Consider the database that we are associated with which is called TCDR [15] This database contains

Results



Pick appropriate interaction for the task

Which is better?







Pick appropriate interaction for the task

Understand the semantics of the interaction



Which is better?



Positive Examples

Unlabeled Examples

- Pick appropriate interaction for the task
- Understand the semantics of the interaction
- Develop/pick an algorithm that uses available information correctly and efficiently

Maximize:

$$margin - \sum_{i} slack_i$$

Subject to the constraints:

$$\sum_{e \in S} \sum_{k=1}^{K} u_k f_k(\operatorname{rend}_1(e)) - \sum_{e \in S} \sum_{k=1}^{K} u_k f_k(\operatorname{rend}_2(e)) \ge \operatorname{margin} - \operatorname{slack}_k u_k \ge 0$$
$$u_k \le C$$



- Pick appropriate interaction for the task
- Understand the semantics of the interaction
- Develop/pick an algorithm that uses available information correctly and efficiently

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