
Computational Physics

Numerical Differentiation

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Approximating a Derivative

GOAL: Given a set of tabulated values (x_i, y_i) , construct an approximation to the derivative of the function $y(x)$.

RECALL:

$$\begin{aligned}\frac{dy}{dx} &= \lim_{h \rightarrow 0} \frac{y(x+h) - y(x)}{h} \quad x-h \quad x \quad x+h \\ &= \lim_{h \rightarrow 0} \frac{y(x) - y(x-h)}{h} \\ &= \lim_{h \rightarrow 0} \frac{y(x+h) - y(x-h)}{2h}\end{aligned}$$

Thus, possible numerical approximation to the derivative are

$$\begin{aligned}\frac{dy}{dx} &\approx \frac{y_{i+1} - y_i}{h} \\ &\approx \frac{y_i - y_{i-1}}{h} \\ &\approx \frac{y_{i+1} - y_{i-1}}{2h}\end{aligned}$$

where $x_{i+1} - x_i = h$

But,

- What is the error we make by using the numerical approximation?
- What is the best choice?
- Which is grid point location where a given numerical approximation applies?
- How to construct more accurate approximations?
- How about higher derivatives?

The tool that we are going to use to answers all of these questions is Taylor series expansions.

$$y(x-x_0) = y_0 + (x-x_0)y'_0 + \frac{(x-x_0)^2}{2!}y''_0 + \frac{(x-x_0)^3}{3!}y'''_0 + \frac{(x-x_0)^4}{4!}y^{(4)}_0 + \dots$$

Approximating the First Order Derivative

GOAL: Find the numerical approximation to the first order derivative of $y(x)$ at x_i using information at the neighboring points $\{x_{i-2}, x_{i-1}, x_i, x_{i+1}, x_{i+2}\}$

From

$$y(x-x_0) = y_0 + (x-x_0)y'_0 + \frac{(x-x_0)^2}{2!}y''_0 + \frac{(x-x_0)^3}{3!}y^{(3)}_0 + \frac{(x-x_0)^4}{4!}y^{(4)}_0 + \dots$$

rewrite using $x_{i+1} - x_i = h$

$$\begin{aligned} y_{i+1} &= y_i + hy'_i + \frac{h^2}{2!}y''_i + \frac{h^3}{3!}y^{(3)}_i + \frac{h^4}{4!}y^{(4)}_i + \dots \\ y_{i-1} &= y_i - hy'_i + \frac{h^2}{2!}y''_i - \frac{h^3}{3!}y^{(3)}_i + \frac{h^4}{4!}y^{(4)}_i + \dots \\ y_{i+2} &= y_i + (2h)y'_i + \frac{(2h)^2}{2!}y''_i + \frac{(2h)^3}{3!}y^{(3)}_i + \frac{(2h)^4}{4!}y^{(4)}_i + \dots \\ y_{i-2} &= y_i - (2h)y'_i + \frac{(2h)^2}{2!}y''_i - \frac{(2h)^3}{3!}y^{(3)}_i + \frac{(2h)^4}{4!}y^{(4)}_i + \dots \end{aligned}$$

$$x - x_0 = h$$

$$y = y_0 + hy'_0 + \frac{h^2}{2!} y''_0 + \frac{h^3}{3!} y'''_0 + \dots$$

$$y_0 \rightarrow y_i$$

$$y \rightarrow y_{i+1}$$

$$y_{i+1} = y_i + hy'_i + \frac{h^2}{2!} y''_i + \frac{h^3}{3!} y'''_i + \dots$$

$$y'_i = \frac{y_{i+1} - y_i}{h} - \frac{h}{2} y''_i - \frac{h^2}{6} y'''_i - \dots$$

$$y'_i = \frac{y_{i+1} - y_i}{h} - \frac{h}{2!} y''_i - \frac{h^2}{3!} y'''_i + \dots$$

$$y'_i \approx \frac{y_{i+1} - y_i}{h} + \varepsilon_i + \dots$$

$$\varepsilon_i = -\frac{h}{2!} y''_i \quad \text{leading truncation error}$$

$\varepsilon \propto O(h)$ 1st order accurate

FINITE DIFFERENCE

One possibility is then to use

$$y_{i+1} = y_i + h \textcolor{blue}{y'_i} + \frac{h^2}{2!} y''_i + \frac{h^3}{3!} y^{(3)}_i + \frac{h^4}{4!} y^{(4)}_i + \dots$$

solving for $\textcolor{blue}{y'_i}$

$$\textcolor{blue}{y'_i} = \frac{y_{i+1} - y_i}{h} - \frac{h}{2!} y''_i - \frac{h^2}{3!} y^{(3)}_i - \frac{h^3}{4!} y^{(4)}_i + \dots$$

Notice that at this stage there are no approximations yet since we have kept the infinite sum. It is when we approximate

$$y'_i \approx \frac{y_{i+1} - y_i}{h}$$

when an error is introduced.

Therefore, from

$$y'_i = \frac{y_{i+1} - y_i}{h} - \frac{h}{2!} y''_i - \frac{h^2}{3!} y^{(3)}_i - \frac{h^3}{4!} y^{(4)}_i + \dots$$

we have that

$$\left[\frac{dy}{dx} \right]_i = \left[\frac{\Delta y}{\Delta x} \right]_i + \varepsilon_i + \dots$$

where

$$\left[\frac{\Delta y}{\Delta x} \right]_i = \frac{y_{i+1} - y_i}{h}$$

is the **finite difference approximation** to y'_i and

$$\varepsilon_i = -\frac{h}{2!} y''_i$$

is the **leading truncation error**. Notice that in this case $\varepsilon \propto \mathcal{O}(h)$. That is, the approximation is **first** order accurate.

$$y = y_0 + hy'_0 + \frac{h^2}{2!} y''_0 + \frac{h^3}{3!} y'''_0 + \frac{h^4}{4!} y^{(4)}_0 + \dots$$

$$y_{i-1} = y_i + hy'_i + \frac{h^2}{2!} y''_i + \dots$$

If we use the point x_{i-1} instead, we get

$$y'_i = \frac{y_i - y_{i-1}}{h} + \frac{h}{2!} y''_i - \frac{h^2}{3!} y^{(3)}_i + \frac{h^3}{4!} y^{(4)}_i + \dots$$

thus

$$\left[\frac{dy}{dx} \right]_i = \left[\frac{\Delta y}{\Delta x} \right]_i + \mathcal{E}_i + \dots$$

with

$$\left[\frac{\Delta y}{\Delta x} \right]_i = \frac{y_i - y_{i-1}}{h}$$

and

$$\mathcal{E}_i = \frac{h}{2!} y''_i$$

The error again is $\mathcal{E} \propto \mathcal{O}(h)$.

Finally, if we use both the point and x_{i+1} and x_{i-1} , we have from

$$\begin{aligned} y_{i+1} &= y_i + h y'_i + \frac{h^2}{2!} y''_i + \frac{h^3}{3!} y_i^{(3)} + \frac{h^4}{4!} y_i^{(4)} + \dots \\ y_{i-1} &= y_i - h y'_i + \frac{h^2}{2!} y''_i - \frac{h^3}{3!} y_i^{(3)} + \frac{h^4}{4!} y_i^{(4)} + \dots \end{aligned}$$

that

$$y_{i+1} - y_{i-1} = 2 h y'_i + \cancel{\left(2 \frac{h^3}{3!} y_i^{(3)} \right)} + \dots \quad \xrightarrow{2h} \frac{y_{i+1} - y_{i-1}}{2h} = \frac{dy}{dx} \Big|_i$$

thus

$$\left[\frac{dy}{dx} \right]_i = \left[\frac{\Delta y}{\Delta x} \right]_i + \mathcal{E}_i + \dots$$

with

$$\left[\frac{\Delta y}{\Delta x} \right]_i = \frac{y_{i+1} - y_{i-1}}{2h}$$

and

$$\mathcal{E}_i = \frac{h^2}{3!} y_i^{(3)}$$

The error in this case is $\mathcal{E} \propto \mathcal{O}(h^2)$, i.e. second order accurate.

Approximating the Second Order Derivative

From

$$\begin{aligned}y_{i+1} &= y_i + h y'_i + \frac{h^2}{2!} y''_i + \frac{h^3}{3!} y^{(3)}_i + \frac{h^4}{4!} y^{(4)}_i + \dots \\y_{i-1} &= y_i - h y'_i + \frac{h^2}{2!} y''_i - \frac{h^3}{3!} y^{(3)}_i + \frac{h^4}{4!} y^{(4)}_i + \dots\end{aligned}$$

one has that

$$y_{i+1} + y_{i-1} = 2y_i + 2\frac{h^2}{2!} y''_i + 2\frac{h^4}{4!} y^{(4)}_i + \dots$$

then

$$\begin{aligned}\frac{y_{i+1} - 2y_i + y_{i-1}}{h^2} &= y''_i + \frac{h^2}{12} y^{(4)}_i + \dots \\y''_i &= \frac{y_{i+1} - 2y_i + y_{i-1}}{h^2} + \frac{h^2}{12} y^{(4)}_i + \dots\end{aligned}$$

Then

$$\left[\frac{d^2y}{dx^2} \right]_i = \left[\frac{\Delta^2 y}{\Delta x^2} \right]_i + \mathcal{E}_i + \dots$$

where

$$\left[\frac{\Delta^2 y}{\Delta x^2} \right]_i = \frac{y_{i+1} - 2y_i + y_{i-1}}{h^2}$$

and

$$\mathcal{E}_i = \frac{h^2}{12} y_i^{(4)}$$

the approximation is **second order accurate**.

The approximations that we have constructed so far were found with an **educated guess**. We need a general procedure that does not involve “guessing.”

Consider again the first order derivative. Suppose we are looking for a finite difference approximation at the grid point x_i that involves only information at the grid points x_i and x_{i+1} . That is, we are looking for an expression of the form

$$\left[\frac{\Delta y}{\Delta x} \right]_i = a_1 y_{i+1} + a_0 y_i$$

such that

$$\left[\frac{dy}{dx} \right]_i = \left[\frac{\Delta y}{\Delta x} \right]_i + \varepsilon_i$$

with a_0 and a_1 unknown coefficients to be determined.

Substitute in

$$\left[\frac{\Delta y}{\Delta x} \right]_i = a_1 y_{i+1} + a_0 y_i$$

the Taylor expansion of y_{i+1} around x_i . That is,

$$y_{i+1} = y_i + h y'_i + \frac{h^2}{2!} y''_i + \frac{h^3}{3!} y^{(3)}_i + \dots$$

Then

$$\begin{aligned} \left[\frac{\Delta y}{\Delta x} \right]_i &= a_1 \left[y_i + h y'_i + \frac{h^2}{2!} y''_i + \frac{h^3}{3!} y^{(3)}_i + \dots \right] + a_0 y_i \\ \left[\frac{dy}{dx} \right]_i - \mathcal{E}_i &= (a_1 + a_0) y_i + a_1 h y'_i + a_1 \left[\frac{h^2}{2!} y''_i + \frac{h^3}{3!} y^{(3)}_i + \dots \right] \\ y'_i - \mathcal{E}_i &= (a_1 + a_0) y_i + a_1 h y'_i + a_1 \left[\frac{h^2}{2!} y''_i + \frac{h^3}{3!} y^{(3)}_i + \dots \right] \\ 0 &= (a_1 + a_0) y_i + (a_1 h - 1) y'_i + \mathcal{E}_i + a_1 \left[\frac{h^2}{2!} y''_i + \frac{h^3}{3!} y^{(3)}_i + \dots \right] \end{aligned}$$

Since

$$0 = (a_1 + a_0)y_i + (a_1 h - 1)y'_i + \mathcal{E}_i + a_1 \left[\frac{h^2}{2!} y''_i + \frac{h^3}{3!} y'''_i + \dots \right]$$

is valid for an arbitrary function $y(x)$, then the only way this expression is satisfied if

$$\begin{aligned} 0 &= a_1 + a_0 \\ 0 &= a_1 h - 1 \\ 0 &= \mathcal{E}_i + a_1 \left[\frac{h^2}{2!} y''_i + \frac{h^3}{3!} y'''_i + \dots \right] \end{aligned}$$

which yields

$$\begin{aligned} a_0 &= -1/h \\ a_1 &= 1/h \\ \mathcal{E}_i &= -\frac{h}{2!} y''_i + \dots \end{aligned}$$

which is the results we derived before

$$\left[\frac{\Delta y}{\Delta x} \right]_i = \frac{y_{i+1} - y_i}{h}$$

Finite Difference Approximations: First Derivative

FD Approximation	Truncation Error	Convergence
$\frac{y_{i+1} - y_{i-1}}{2h}$	$\frac{1}{6}h^2 y^{(3)}$	Second
$\frac{y_{i+1} - y_i}{h}$	$-\frac{1}{2}h y^{(2)}$	First
$\frac{y_i - y_{i-1}}{h}$	$\frac{1}{2}h y^{(2)}$	First
$\frac{-3y_i + 4y_{i+1} - y_{i+2}}{2h}$	$\frac{1}{3}h^2 y^{(3)}$	Second
$\frac{y_{i-2} - 8y_{i-1} + 8y_{i+1} - y_{i+2}}{12h}$	$\frac{1}{30}h^4 y^{(5)}$	Forth

Finite Difference Approximations: Second Derivative

y || |

FD Approximation	Truncation Error	Convergence
$\frac{y_{i+1} - 2y_i + y_{i-1}}{h^2}$	$\frac{1}{12} h^2 y^{(4)}$	Second
$\frac{y_i - 2y_{i+1} + y_{i+2}}{h^2}$	$h y^{(3)}$	First
$\frac{-y_{i-2} + 16y_{i-1} - 30y_i + 16y_{i+1} - y_{i+2}}{12h}$	$\frac{1}{90} h^4 y^{(6)}$	Forth

Discretization

- * solve a continuum system approximately using discretization
- * continuum function might depend on t , $0 \leq t \leq t_{\max}$
 - o # of t 's
- ↳ discrete function will be defined finite # of times
 t^n , $n=1, 2, \dots, N$ ∵ finite # of t 's
- * Reduce ∞ DOF to finite because computational resources are finite
 - can then solve them computationally
- * Replace differential equations with algebraic eqn.
 - can then solve them computationally
- * We will focus on finite differencing (not finite element, spectral)

+

$$\frac{df(x)}{dx} = f'(x) = \lim_{h \rightarrow 0} \frac{f(x+h) - f(x)}{h} \quad h = \Delta x$$

Continuum

FDA

Steps for solving DE using FDA

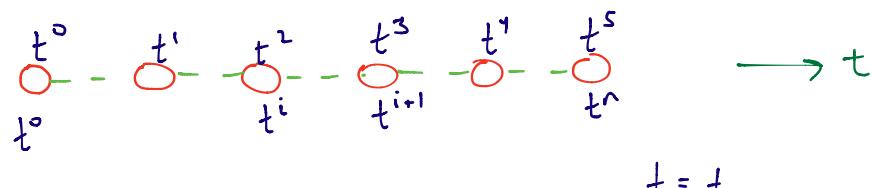
1. formulate precise + complete mathematical description
 - * specify independent variables t, x, \dots
 - * specify domain in terms of those variables
 $0 \leq t \leq t_{\max}$
 $0 \leq l \leq 100$
 - * write down dependent variable $y(u), f(x), \dots$
 - * write down equations
 - * specify boundary conditions

DO THIS NOW FOR $f(x) = \sin(x)$

what b.c. make sense!

* ex. single particle Newton's 2nd Law

$$m a(t) = m \frac{d^2 x(t)}{dt^2} = F_{\text{Applied}}(t)$$

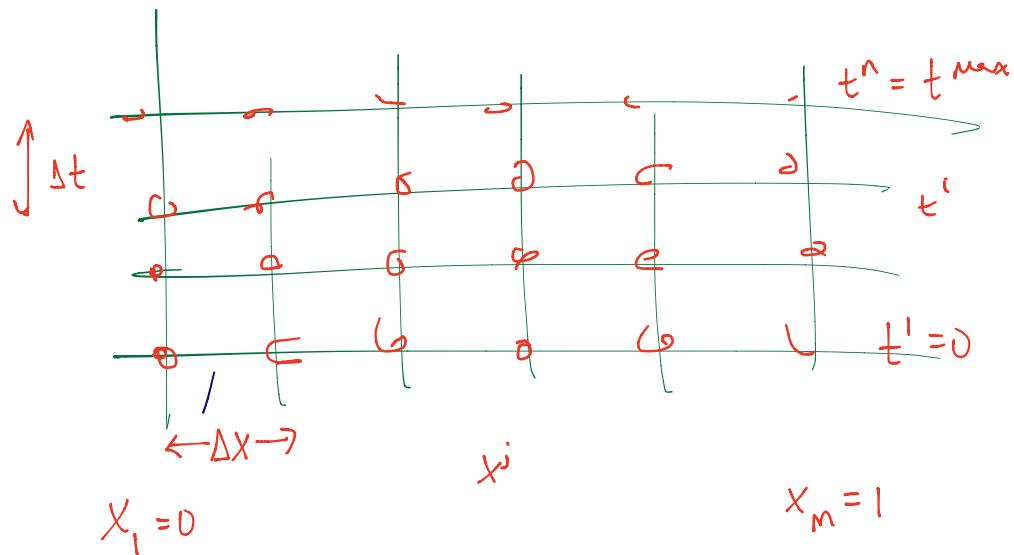
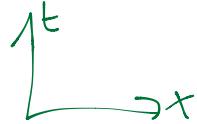


Uniform mesh $t^{i+1} = t^i + \Delta t = t^i + h$

particles located at $x^i = x(t^i)$

EOM determine $x^i \rightarrow x^{i+1} \rightarrow \dots$

FDA mesh



2. Define grid, assume uniform, $\Delta t, \Delta x, \dots$
mesh spaces control accuracy of FDA
assume $h \rightarrow 0 \rightarrow$ continuum solution
i.e. converge

3. replace derivatives w/ FDA

4. solve this new set of algebraic eqns.

5. convergence test + error analysis

repeat using every thing the same BUT \textcircled{h}

is it converging?

errors behaving as predicted?

CODE

take 1st and 2nd derivatives of $\sin(x)$; prove you

get the correct answer

Richardson Extrapolation

Consider the case of the **center finite difference** approximation to the second derivative. That is, $y_i'' = D_2(h)_i + \mathcal{E}_i(h)$ where

$$D_2(h)_i = \frac{y_{i+1} - 2y_i + y_{i-1}}{h^2}$$

and

$$\begin{aligned}\mathcal{E}(h) &= \frac{1}{12}h^2 y^{(4)} + \mathcal{O}(h^4) + \mathcal{O}(h^6) + \mathcal{O}(h^8) \dots \\ &= C_2 h^2 + C_4 h^4 + C_6 h^6 + \dots\end{aligned}$$

Evaluate the derivative approximation with h and $h/2$; that is,

$$\begin{aligned}y'' &= D_2(h) + C_2 h^2 + C_4 h^4 + \dots \\y'' &= D_2(h/2) + C_2 \left(\frac{h}{2}\right)^2 + C_4 \left(\frac{h}{2}\right)^4 + \dots\end{aligned}$$

Multiply the second equation by 4 and subtract the first equation.

$$\begin{aligned}3y'' &= 4D_2(h/2) - D_2(h) + 4C_4 \left(\frac{h}{2}\right)^4 - C_4 h^4 + \dots \\y'' &= \frac{1}{3} [4D_2(h/2) - D_2(h)] - \frac{3}{4} C_4 h^4 + \dots\end{aligned}$$

Thus, we have then

$$y'' = D_4(h) + \bar{C}_4 h^4 + \bar{C}_6 h^6 + \dots$$

where now the approximation is given by (notice is 4th order)

$$D_4(h) = \frac{1}{3} [4D_2(h/2) - D_2(h)]$$

Richardson Extrapolation

Consider the case of the **center finite difference** approximation to the second derivative. That is, $y_i'' = D_2(h)_i + \mathcal{E}_i(h)$ where

$$D_2(h)_i = \frac{y_{i+1} - 2y_i + y_{i-1}}{h^2}$$

and

$$\begin{aligned}\mathcal{E}(h) &= \frac{1}{12}h^2y^{(4)} + \mathcal{O}(h^4) + \mathcal{O}(h^6) + \mathcal{O}(h^8)\dots \\ &= C_2h^2 + C_4h^4 + C_6h^6 + \dots\end{aligned}$$

$$y'' = 4D_2\left(\frac{h}{2}\right) + \frac{4C_2 h^2}{4} + C_4 \left(\frac{h}{2}\right)^4$$

$$-y'' = -D_2(h) - C_2 h^2 - C_4 h^4$$

$$3y'' = 4D_2\left(\frac{h}{2}\right) - D_2(h) + 4C_4 \left(\frac{h}{2}\right)^4 - C_4 h^4 \dots$$

$$y'' = \frac{1}{3} \left[4D_2\left(\frac{h}{2}\right) - D_2(h) \right] - \frac{3}{4} C_4 h^4 \text{ improved!}$$

$$\text{but } D_2(h) = \frac{y_{i+1} - 2y_i + y_{i-1}}{h^2}$$

$$y'' = \frac{1}{3} \left[16 \frac{y_{i+1} - 2y_i + y_{i-1}}{h^2} - \frac{y_{i+1} - 2y_i + y_{i-1}}{h^2} \right] - \frac{3}{4} C_4 h^4$$

Using your code, implement
 forward
 backward
 center differencing y'

$u(x) = \sin \pi x$ \rightarrow smooth \therefore can predict truncation error
 $u'(x) = \pi \cos \pi x$ using Taylor serie

$$-1 \leq x \leq 1 \quad \Delta x = \frac{2}{N}; \quad x_i = i \Delta x /$$

$$\varepsilon_i = \tilde{u}'(x_i) - u(x_i)$$

FDA - analytical derivatives

measure how ε change as $N \uparrow$

$$\text{rms } \|\varepsilon\|_2 = \Delta x \left(\sum_{i=0}^N \varepsilon_i^2 \right)^{1/2}$$

$$\|\varepsilon\|_\infty = \max_{0 \leq i \leq N} (\varepsilon_i) \quad N = 1024$$

