

Computational Physics

Partial Differential Equations

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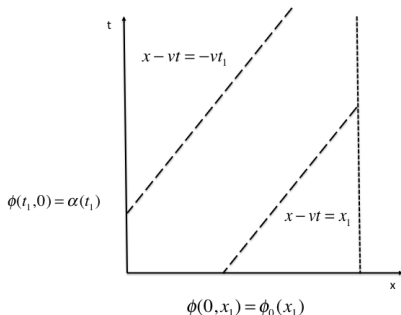
Advection or Convection Equation

- Let's consider the 1D case

$$\partial_t \phi + v \partial_x \phi = 0$$

with $v = \text{const} > 0$, $t \geq 0$ and $x \in [0, 1]$

- Initial data: $\phi(0, x) = \phi_0(x)$
- Boundary conditions:
 $\phi(t, 0) = \alpha(t)$ and
 $\phi(t, 1) = \beta(t)$
- Solutions to this equation have the form
 $\phi(t, x) = \phi(x - vt)$
- Therefore, the solution $\phi(t, x)$ is **constant** along the lines $x - vt = \text{const}$ called **characteristics**



Forward-Time Center-Space (FTCS) Discretization

- Let's consider the following discretization of the differential operators

$$\begin{aligned}\partial_t \phi_i^n &= \frac{\phi_i^{n+1} - \phi_i^n}{\Delta t} + O(\Delta t) \\ \partial_x \phi_i^n &= \frac{\phi_{i+1}^n - \phi_{i-1}^n}{2 \Delta x} + O(\Delta x^2)\end{aligned}$$

where we have used the notation $\phi_i^n \equiv \phi(t^n, x_i)$

- Therefore, the finite difference approximation to $\partial_t \phi + v \partial_x \phi = 0$ is

$$\frac{(\bar{\phi}_i^{n+1} - \bar{\phi}_i^n)}{\Delta t} + v \frac{(\bar{\phi}_{i+1}^n - \bar{\phi}_{i-1}^n)}{2 \Delta x} = 0$$

- Notice that we are making a distinction between the solution $\phi(t, x)$ to the **continuum** equation and $\bar{\phi}_i^n$ the solution to the **discrete** equation.

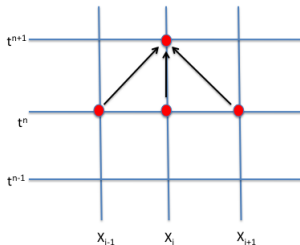
Solving

$$\frac{(\bar{\phi}_i^{n+1} - \bar{\phi}_i^n)}{\Delta t} + v \frac{(\bar{\phi}_{i+1}^n - \bar{\phi}_{i-1}^n)}{2 \Delta x} = 0$$

for $\bar{\phi}_i^{n+1}$, one gets the following relationship to **update** the solution

$$\bar{\phi}_i^{n+1} = \bar{\phi}_i^n - \frac{1}{2} C (\bar{\phi}_{i+1}^n - \bar{\phi}_{i-1}^n)$$

where $C \equiv \Delta t v / \Delta x$



- The tendency for any perturbation in the numerical solution to decay.
- That is, given a discretization scheme, we need to evaluate the degree to which errors introduced at any stage of the computation will grow or decay.
- We are then concerned with the behavior of the solution error

$$\epsilon_i^n = \phi_i^n - \bar{\phi}_i^n$$

- Substitution of $\bar{\phi}_i^n = \phi_i^n - \epsilon_i^n$ into

$$\bar{\phi}_i^{n+1} = \bar{\phi}_i^n - \frac{1}{2}C (\bar{\phi}_{i+1}^n - \bar{\phi}_{i-1}^n)$$

yields

$$\phi_i^{n+1} - \epsilon_i^{n+1} = \phi_i^n - \epsilon_i^n - \frac{1}{2}C (\phi_{i+1}^n - \epsilon_{i+1}^n - \phi_{i-1}^n + \epsilon_{i-1}^n)$$

- Substitute the following Taylor expansions

$$\phi_i^{n+1} = \phi_i^n + \Delta t \partial_t \phi_i^n + O(\Delta t^2)$$

$$\phi_{i\pm 1}^n = \phi_i^n \pm \Delta x \partial_x \phi_i^n + O(\Delta x^2)$$

- Then

$$\begin{aligned} \phi_i^n + \Delta t \partial_t \phi_i^n - \epsilon_i^{n+1} &= \phi_i^n - \epsilon_i^n \\ -\frac{1}{2}C (\phi_i^n + \Delta x \partial_x \phi_i^n - \epsilon_{i+1}^n - \phi_i^n + \Delta x \partial_x \phi_i^n + \epsilon_{i-1}^n) \end{aligned}$$

or

$$\begin{aligned} \Delta t \partial_t \phi_i^n - \epsilon_i^{n+1} &= -\epsilon_i^n - \frac{1}{2}C (2 \Delta x \partial_x \phi_i^n - \epsilon_{i+1}^n + \epsilon_{i-1}^n) \\ \epsilon_i^{n+1} &= \epsilon_i^n - \frac{1}{2}C (\epsilon_{i+1}^n - \epsilon_{i-1}^n) + \Delta t \partial_t \phi_i^n - C \Delta x \partial_x \phi_i^n \\ \epsilon_i^{n+1} &= \epsilon_i^n - \frac{1}{2}C (\epsilon_{i+1}^n - \epsilon_{i-1}^n) + \Delta t (\partial_t \phi_i^n - v \partial_x \phi_i^n) \\ \epsilon_i^{n+1} &= \epsilon_i^n - \frac{1}{2}C (\epsilon_{i+1}^n - \epsilon_{i-1}^n) \end{aligned}$$

- That is, the solution error satisfies also the discrete finite differences approximation

$$\epsilon_i^{n+1} = \epsilon_i^n - \frac{1}{2} C (\epsilon_{i+1}^n - \epsilon_{i-1}^n)$$

- **Von Neumann stability analysis:** Assume that the errors satisfy a “separation-of-variables” of the form

$$\epsilon_i^n = \xi^n e^{l x_j} = \xi^n e^{l k \Delta x j}$$

where $l = \sqrt{-1}$, $k = 2\pi/\lambda$ and ξ is a complex amplitude. The n in ξ^n is understood to be a power.

- The condition of stability is $|\xi| \leq 1$ for all k .

Substitution of $\epsilon_i^n = \xi^n e^{I k \Delta x i}$ into the finite difference equation yields

$$\xi^{n+1} e^{I k \Delta x i} = \xi^n e^{I k \Delta x i} - \frac{1}{2} C \left(\xi^n e^{I k \Delta x (i+1)} - \xi^n e^{I k \Delta x (i-1)} \right)$$

$$\xi^{n+1} = \xi^n - \frac{1}{2} C \left(\xi^n e^{I k \Delta x} - \xi^n e^{-I k \Delta x} \right)$$

$$\xi = 1 - \frac{1}{2} C \left(e^{I k \Delta x} - e^{-I k \Delta x} \right)$$

$$\xi = 1 - \frac{1}{2} C 2 I \sin(k \Delta x)$$

$$\xi = 1 - I C \sin(k \Delta x)$$

$$|\xi|^2 = 1 + C^2 \sin^2(k \Delta x)$$

Therefore FTCS discretization applied to the advection equation is **unstable**.

Forward-Time Forward-Space (FTFS) Discretization

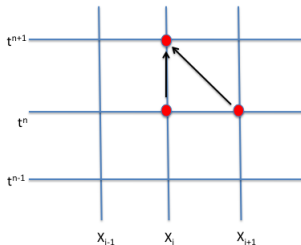
Approximate the advection equation as

$$\frac{(\bar{\phi}_i^{n+1} - \bar{\phi}_i^n)}{\Delta t} + v \frac{(\bar{\phi}_{i+1}^n - \bar{\phi}_i^n)}{\Delta x} = 0$$

thus

$$\bar{\phi}_i^{n+1} = \bar{\phi}_i^n - C (\bar{\phi}_{i+1}^n - \bar{\phi}_i^n)$$

where $C \equiv \Delta t v / \Delta x$



Substitute $\epsilon_i^n = \xi^n e^{ik \Delta x i}$ into

$$\epsilon_i^{n+1} = (1 + C)\epsilon_i^n - C\epsilon_{i+1}^n$$

$$\xi^{n+1} e^{ik \Delta x i} = (1 + C)\xi^n e^{ik \Delta x i} - C\xi^n e^{ik \Delta x (i+1)}$$

$$\xi^{n+1} = (1 + C)\xi^n - C\xi^n e^{ik \Delta x}$$

$$\xi = (1 + C) - C e^{ik \Delta x}$$

$$|\xi|^2 = \left[(1 + C) - C e^{ik \Delta x} \right] \left[(1 + C) - C e^{-ik \Delta x} \right]$$

$$|\xi|^2 = (1 + C)^2 + C^2 - (1 + C)C(e^{ik \Delta x} + e^{-ik \Delta x})$$

$$|\xi|^2 = (1 + C)^2 + C^2 - 2(1 + C)C \cos(k \Delta x)$$

$$|\xi|^2 = 1 + 2(1 + C)C [1 - \cos(k \Delta x)] \geq 1$$

the method is **unstable**

Forward-Time Backward-Space (FTFS) Discretization

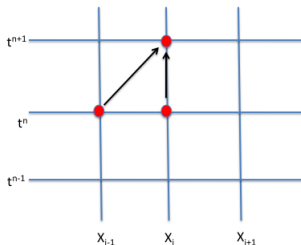
Approximate the advection equation as

$$\frac{(\bar{\phi}_i^{n+1} - \bar{\phi}_i^n)}{\Delta t} + v \frac{(\bar{\phi}_i^n - \bar{\phi}_{i-1}^n)}{\Delta x} = 0$$

thus

$$\bar{\phi}_i^{n+1} = \bar{\phi}_i^n - C (\bar{\phi}_i^n - \bar{\phi}_{i-1}^n)$$

where $C \equiv \Delta t v / \Delta x$



Substitute $\epsilon_i^n = \xi^n e^{I k \Delta x i}$ into

$$\epsilon_i^{n+1} = (1 - C)\epsilon_i^n + C\epsilon_{i-1}^n$$

$$\xi^{n+1} e^{I k \Delta x i} = (1 - C)\xi^n e^{I k \Delta x i} + C\xi^n e^{I k \Delta x (i-1)}$$

$$\xi^{n+1} = (1 - C)\xi^n + C\xi^n e^{-I k \Delta x}$$

$$\xi = (1 - C) + C e^{-I k \Delta x}$$

$$|\xi|^2 = \left[(1 - C) + C e^{-I k \Delta x} \right] \left[(1 - C) + C e^{I k \Delta x} \right]$$

$$|\xi|^2 = (1 - C)^2 + C^2 + (1 - C)C(e^{I k \Delta x} + e^{-I k \Delta x})$$

$$|\xi|^2 = (1 - C)^2 + C^2 + 2(1 - C)C \cos(k \Delta x)$$

$$|\xi|^2 = 1 - 2(1 - C)C [1 - \cos(k \Delta x)]$$

Given

$$|\xi|^2 = 1 - 2(1 - C)C [1 - \cos(k \Delta x)]$$

in order to have $|\xi|^2 \leq 1$

$$-1 \leq 1 - 2(1 - C)C [1 - \cos(k \Delta x)] \leq 1$$

$$-2 \leq -2(1 - C)C [1 - \cos(k \Delta x)] \leq 0$$

$$1 \geq (1 - C)C [1 - \cos(k \Delta x)] \geq 0$$

thus

$$1 - C \geq 0$$

$$C \leq 1$$

$$\frac{v \Delta t}{\Delta x} \leq 1$$

Thus for **stability** we need to pick a time-step

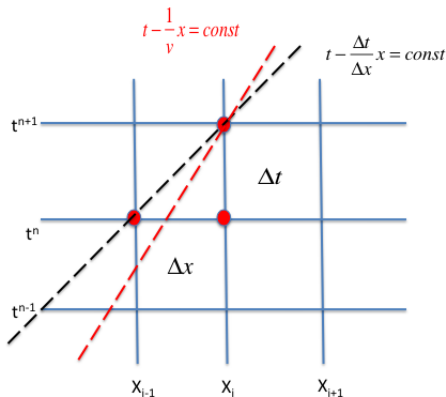
$$\Delta t \leq \frac{\Delta x}{v}$$

The **stability** condition

$$\Delta t \leq \frac{\Delta x}{v}$$

implies that the **numerical** characteristics are contained within the **physical** characteristics since

$$\frac{\Delta t}{\Delta x} \leq \frac{1}{v}$$



How does FTBS prevent the onset of instabilities?

Recall

$$\phi_i^{n+1} = \phi_i^n - C (\phi_i^n - \phi_{i-1}^n)$$

where $C \equiv \Delta t v / \Delta x$. Substitute

$$\phi_i^{n+1} = \phi_i^n + \Delta t \partial_t \phi_i^n + \frac{\Delta t^2}{2} \partial_t^2 \phi_i^n + O(\Delta t^3)$$

$$\phi_{i-1}^n = \phi_i^n - \Delta x \partial_x \phi_i^n + \frac{\Delta x^2}{2} \partial_x^2 \phi_i^n + O(\Delta x^3)$$

then

$$\begin{aligned} \phi_i^n + \Delta t \partial_t \phi_i^n + \frac{\Delta t^2}{2} \partial_t^2 \phi_i^n &= \phi_i^n \\ -C \left[\phi_i^n - \phi_i^n + \Delta x \partial_x \phi_i^n - \frac{\Delta x^2}{2} \partial_x^2 \phi_i^n \right] \end{aligned}$$

Then

$$\Delta t \partial_t \phi + \frac{\Delta t^2}{2} \partial_t^2 \phi = -v \frac{\Delta t}{\Delta x} \left[\Delta x \partial_x \phi - \frac{\Delta x^2}{2} \partial_x^2 \phi \right]$$

$$\partial_t \phi + \frac{\Delta t}{2} \partial_t^2 \phi = -v \left[\partial_x \phi - \frac{\Delta x}{2} \partial_x^2 \phi \right]$$

$$\partial_t \phi + v \partial_x \phi + \frac{\Delta t}{2} \partial_t^2 \phi - v \frac{\Delta x}{2} \partial_x^2 \phi = 0$$

but from $\partial_t \phi = -v \partial_x \phi$ we have that

$$\partial_t^2 \phi = -v \partial_t \partial_x \phi = -v \partial_x \partial_t \phi = v^2 \partial_x^2 \phi$$

thus

$$\partial_t \phi + v \partial_x \phi + v^2 \frac{\Delta t}{2} \partial_x^2 \phi - v \frac{\Delta x}{2} \partial_x^2 \phi = 0$$

$$\partial_t \phi + v \partial_x \phi + \left(v^2 \frac{\Delta t}{2} - v \frac{\Delta x}{2} \right) \partial_x^2 \phi = 0$$

$$\partial_t \phi + v \partial_x \phi + \left(v^2 \frac{\Delta t}{2} - v \frac{\Delta x}{2} \right) \partial_x^2 \phi = 0$$

$$\partial_t \phi + v \partial_x \phi - v \frac{\Delta x}{2} \left(1 - v \frac{\Delta t}{\Delta x} \right) \partial_x^2 \phi = 0$$

$$\partial_t \phi + v \partial_x \phi - v \frac{\Delta x}{2} (1 - C) \partial_x^2 \phi = 0$$

This equation has the form

$$\partial_t \phi + v \partial_x \phi - \alpha \partial_x^2 \phi = 0$$

advection-diffusion equation with

$$\alpha \equiv v \frac{\Delta x}{2} (1 - C)$$

Recall that for stability $C \leq 1$, thus $\alpha \geq 0$.

Given

$$\phi(t, x) = \phi_0 e^{-pt} e^{-i k(x-qt)}$$

Substitution into

$$\partial_t \phi + v \partial_x \phi = 0 \Rightarrow p = 0 \quad q = v$$

$$\partial_t \phi + v \partial_x \phi - \alpha \partial_x^2 \phi = 0 \Rightarrow p = \alpha k^2 \quad q = v \quad \text{dissipation}$$

$$\partial_t \phi + v \partial_x \phi - \beta \partial_x^3 \phi = 0 \Rightarrow p = 0 \quad q = v - \beta k^2 \quad \text{dispersion}$$

- That is, the FTBS discretization introduces **artificial numerical dissipation** to prevent the growth of instabilities.
- Notice that the dissipation coefficient $\alpha \propto \Delta t$.
- Therefore, in the continuum limit $\lim_{\Delta x \rightarrow 0} \alpha = 0$