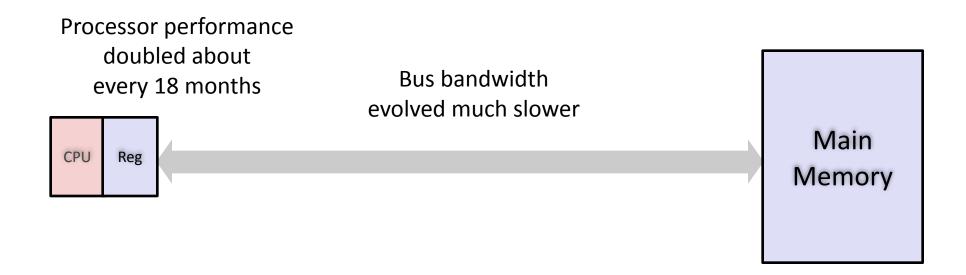
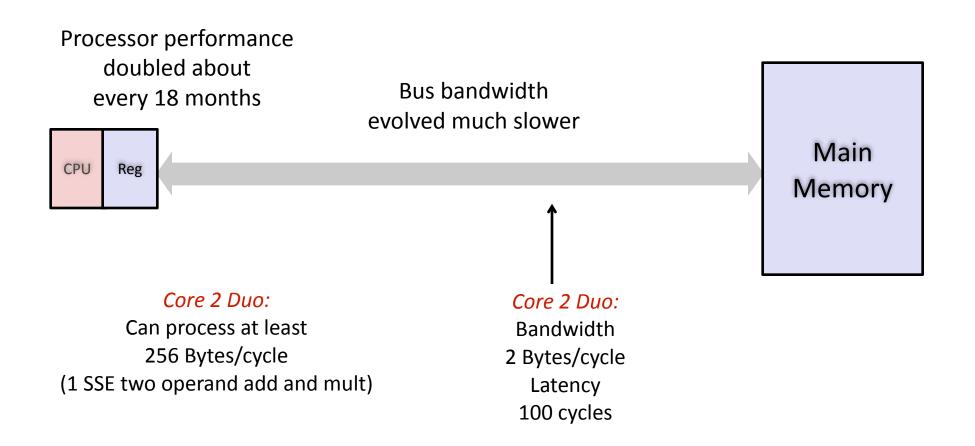
MEMORY/ CACHES

CAS CS210 6.1.1, 6.1.4 and 6.2--6.5

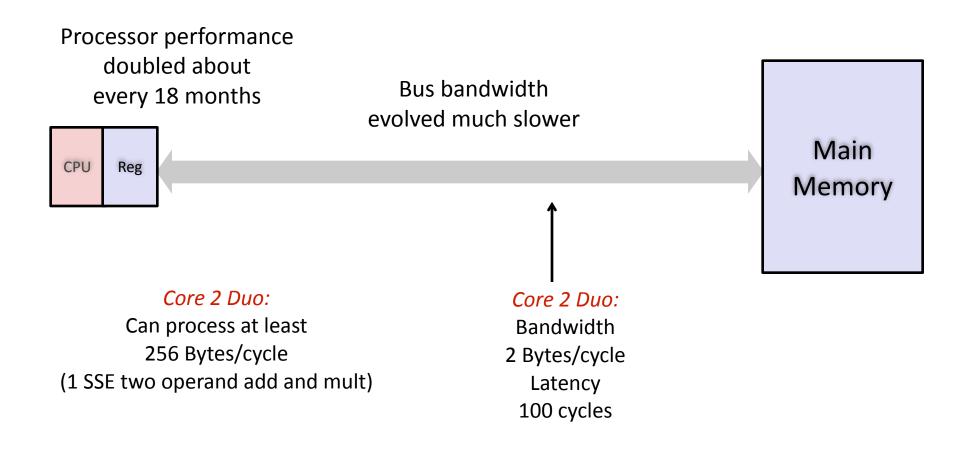
Problem: Processor-Memory Bottleneck



Problem: Processor-Memory Bottleneck



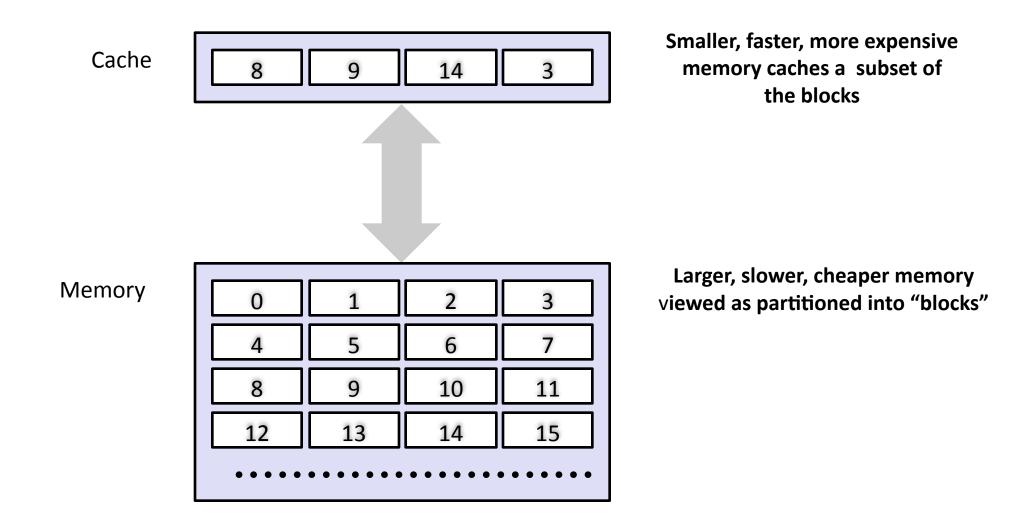
Problem: Processor-Memory Bottleneck

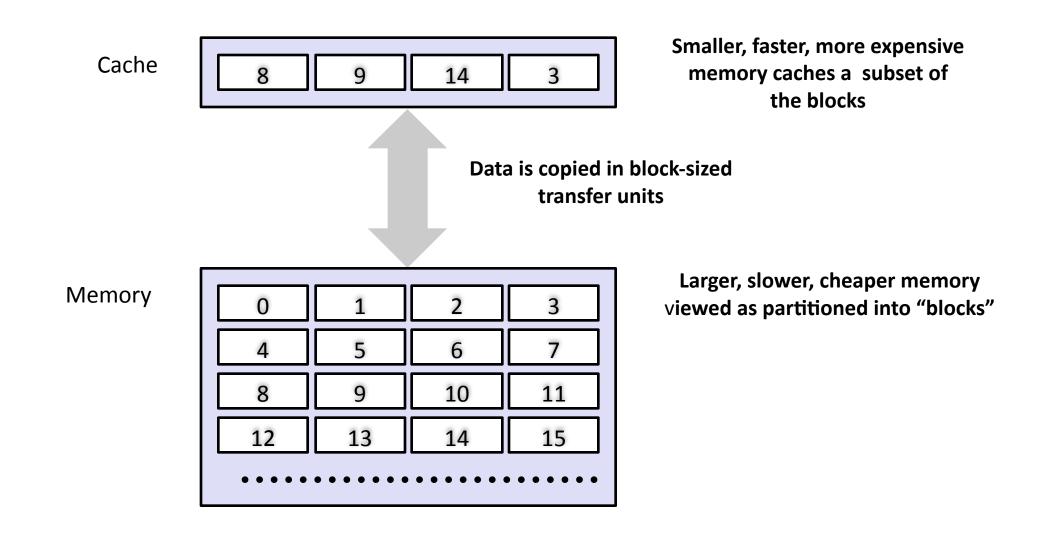


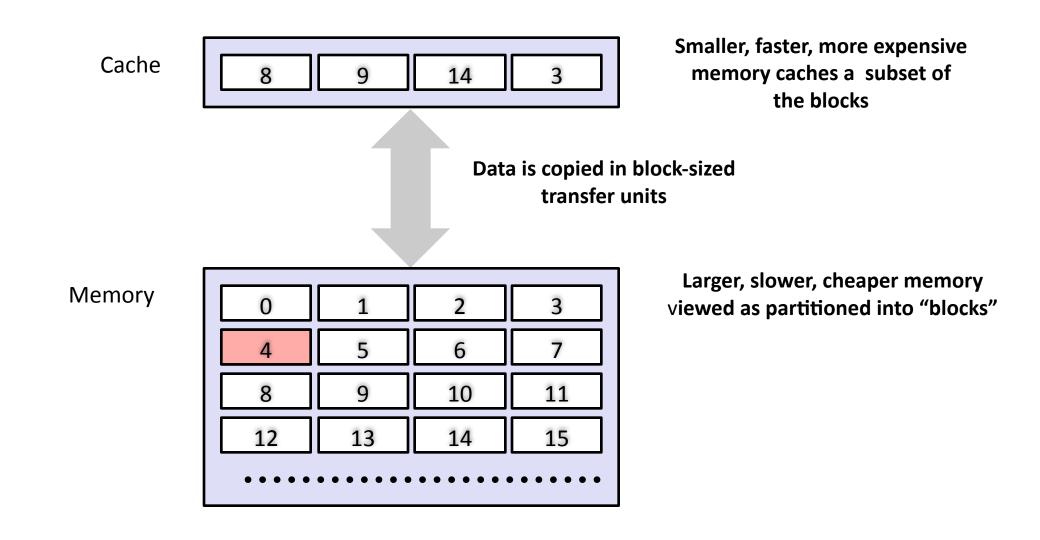
Solution: Caches

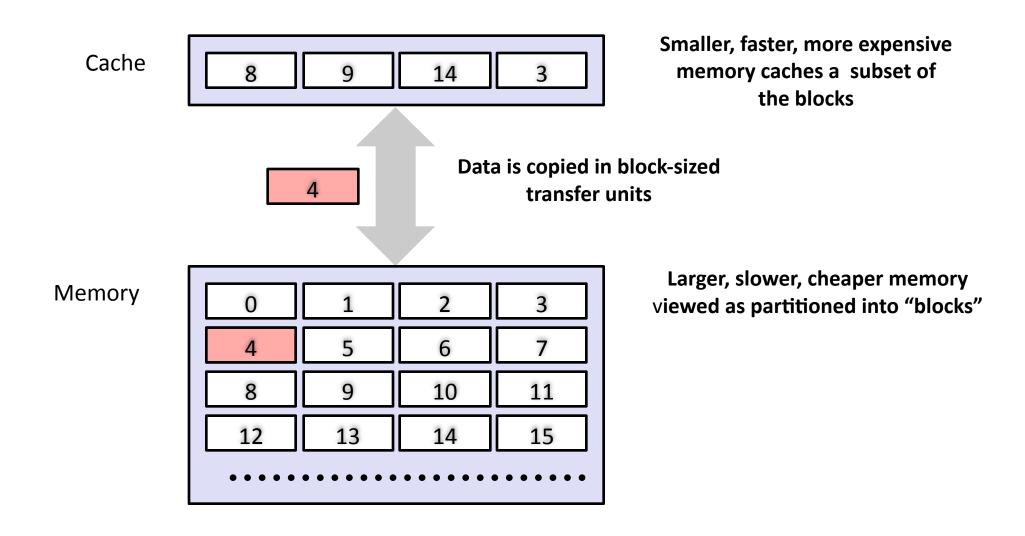
Cache

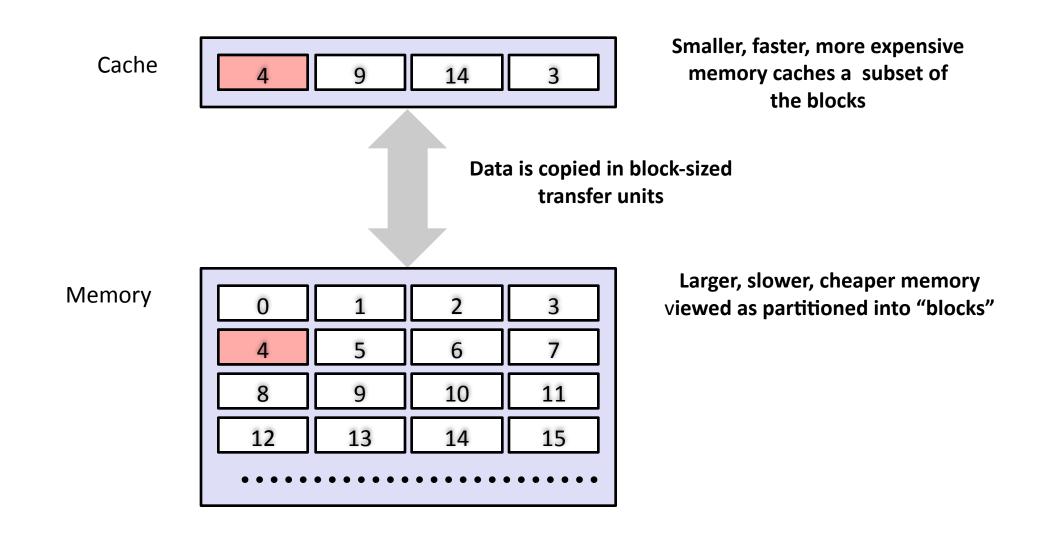
■ Definition: Computer memory with short access time used for the storage of frequently or recently used instructions or data

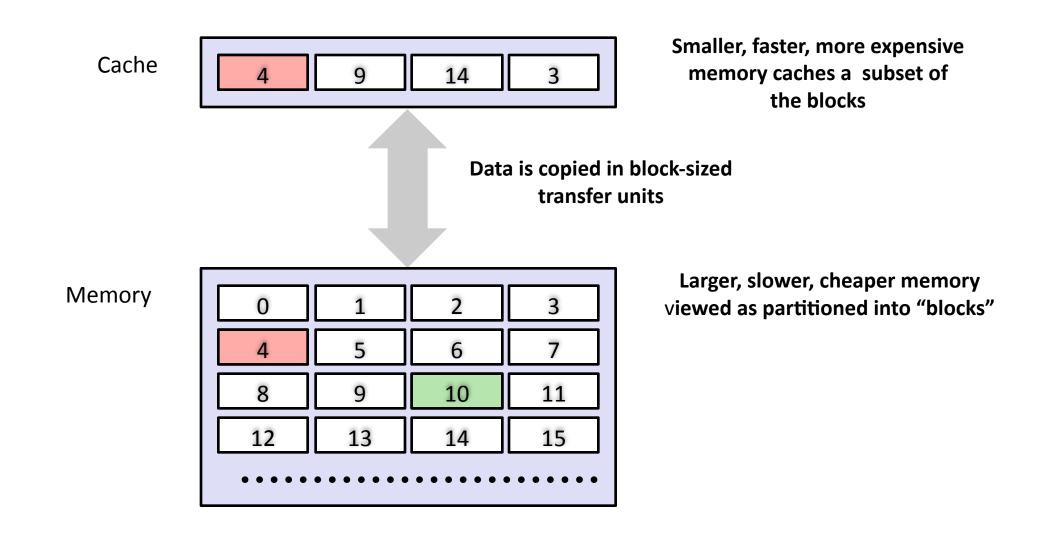


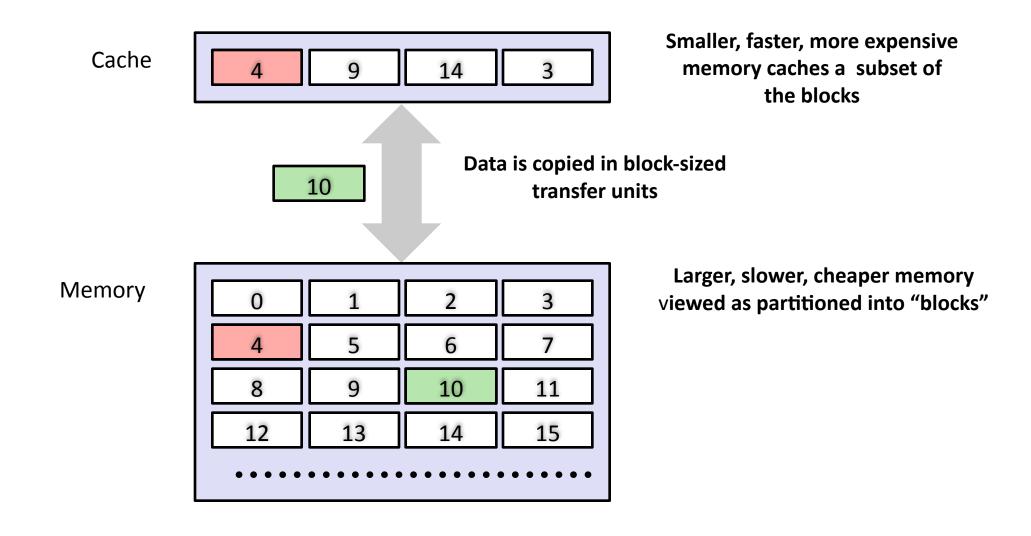


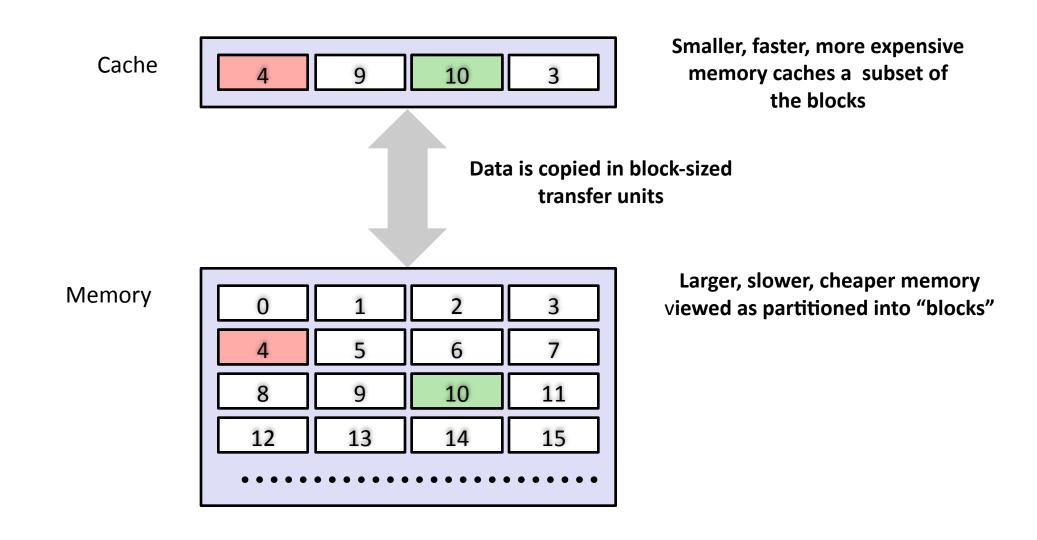


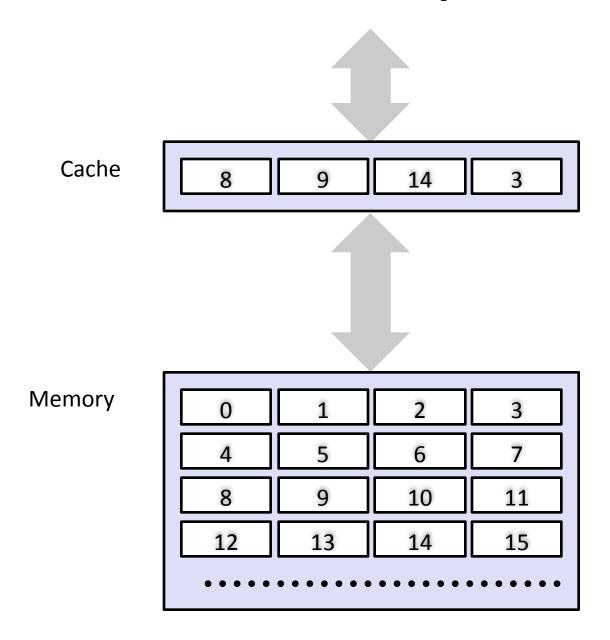


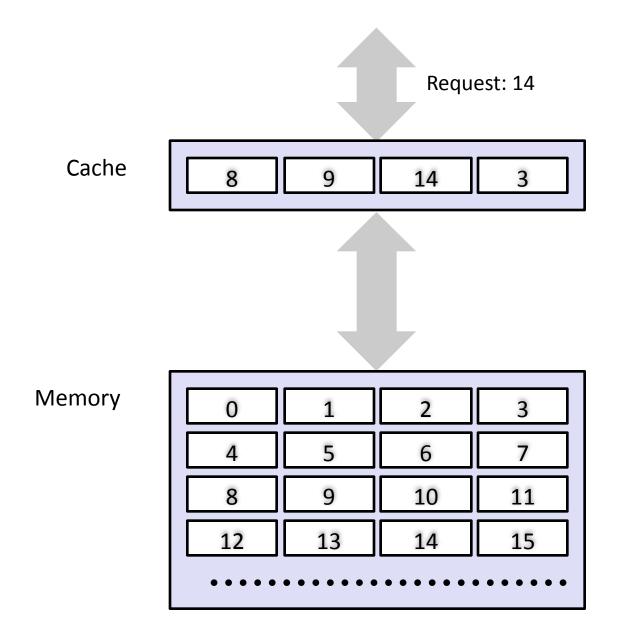




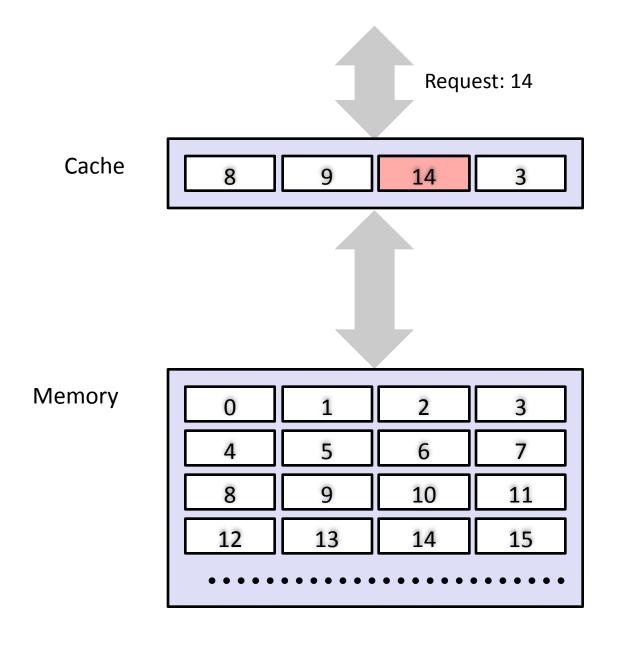








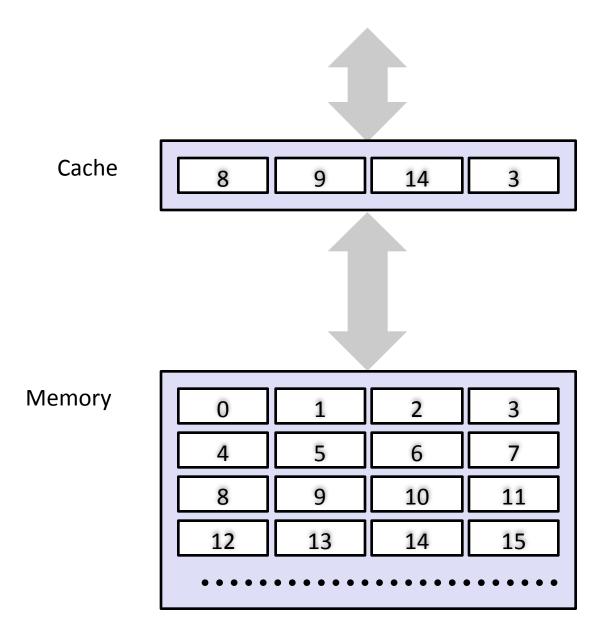
Data in block b is needed

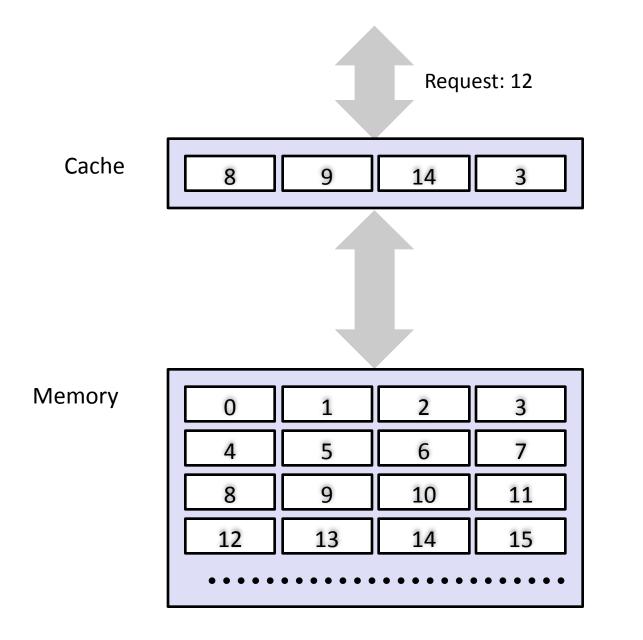


Data in block b is needed

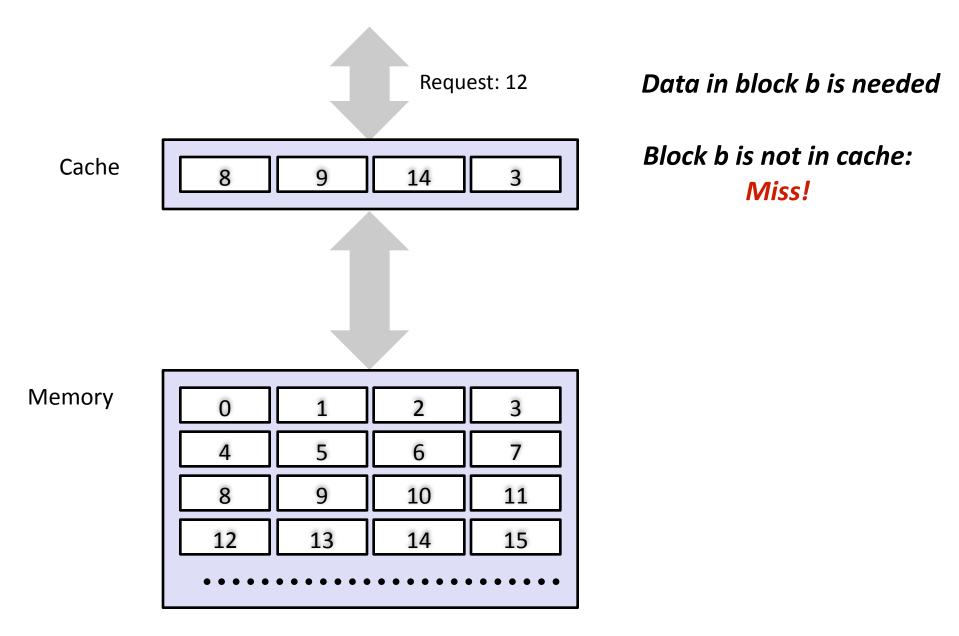
Block b is in cache:

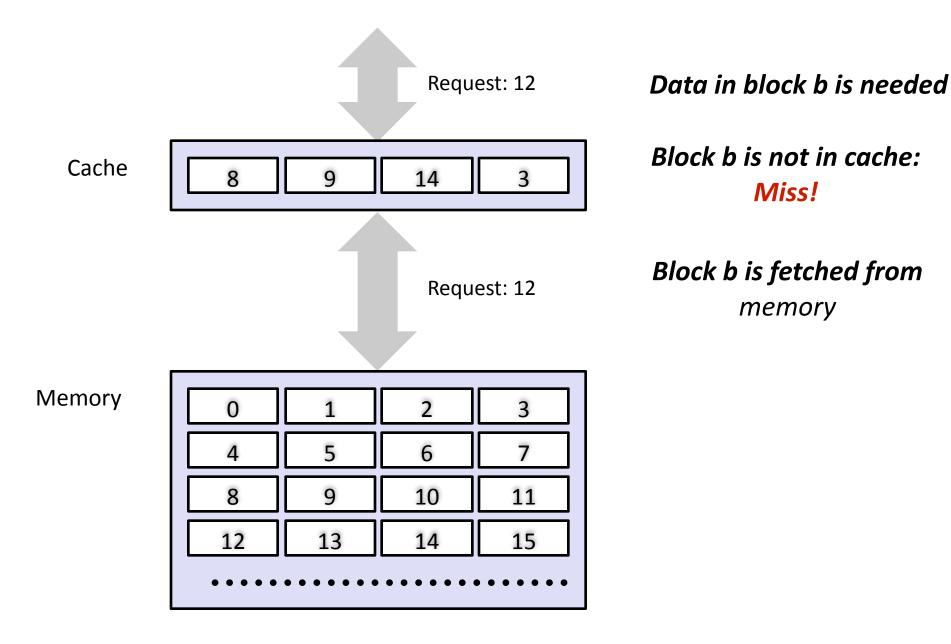
Hit!

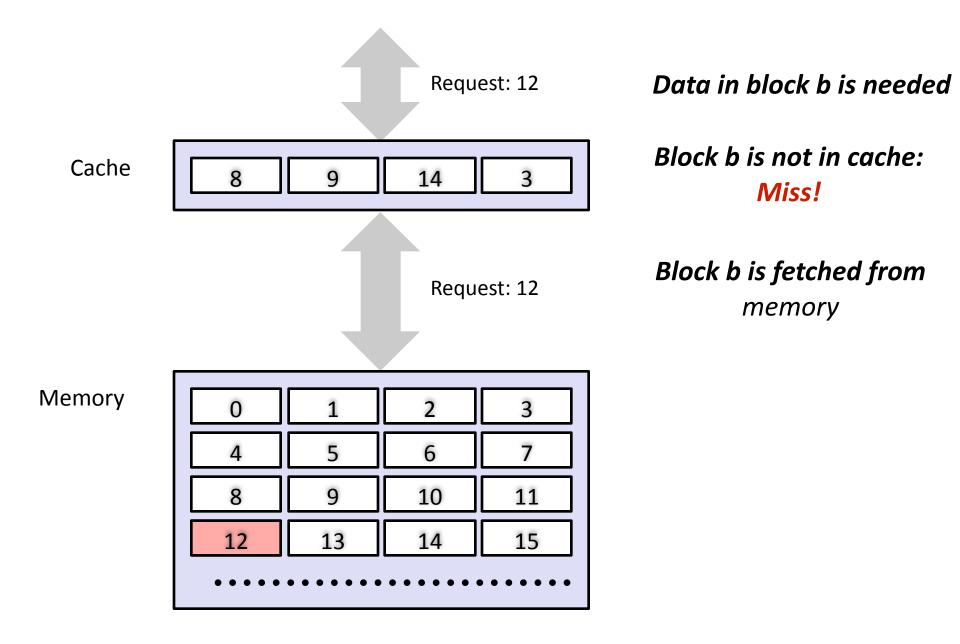


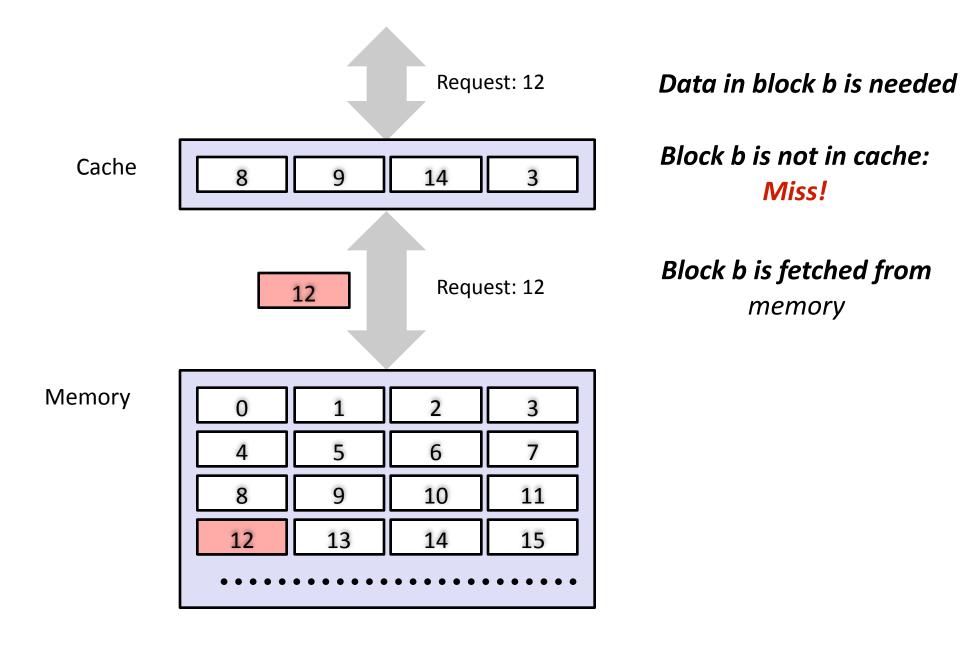


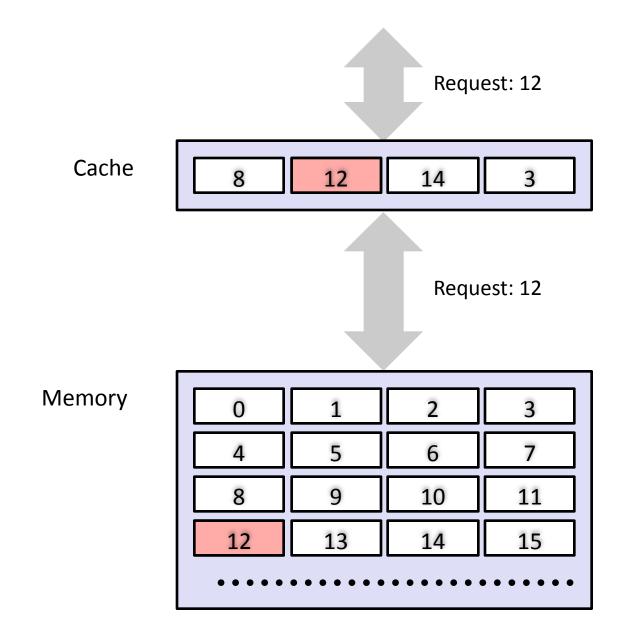
Data in block b is needed











Data in block b is needed

Block b is not in cache: Miss!

Block b is fetched from memory

Block b is stored in cache

- Placement policy: determines where b goes
- Replacement policy: determines which block gets evicted (victim)

Cache Performance Metrics

Miss Rate

- Fraction of memory references not found in cache (misses / accesses)
 - = 1 hit rate
- Typical numbers (in percentages):
 - 3-10% for L1
 - can be quite small (e.g., < 1%) for L2, depending on size, etc.</p>

Hit Time

- Time to deliver a line in the cache to the processor
 - includes time to determine whether the line is in the cache
- Typical numbers:
 - 1-2 clock cycle for L1
 - 5-20 clock cycles for L2

Miss Penalty

- Additional time required because of a miss
 - typically 50-200 cycles for main memory (Trend: increasing!)

- Huge difference between a hit and a miss
 - Could be 100x, if just L1 and main memory

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 - Consider: cache hit time of 1 cycle miss penalty of 100 cycles
 - Average access time:

```
97% hits: 1 cycle + 0.03 * 100 cycles = 4 cycles
```

99% hits: 1 cycle + 0.01 * 100 cycles = 2 cycles

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99% hits: 1 cycle + 0.01 * 100 cycles = 2 cycles

■ This is why "miss rate" is used instead of "hit rate"

Types of Cache Misses

Cold (compulsory) miss

Occurs on first access to a block

Conflict miss

- Most hardware caches limit blocks to a small subset (sometimes a singleton) of the available cache slots
 - e.g., block i must be placed in slot (i mod 4)
- Conflict misses occur when the cache is large enough, but multiple data objects all map to the same slot
 - e.g., referencing blocks 0, 8, 0, 8, ... would miss every time

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Capacity miss

 Occurs when the set of active cache blocks (working set) is larger than the cache

■ Locality: Programs tend to use data and instructions with addresses near or equal to those they have used recently

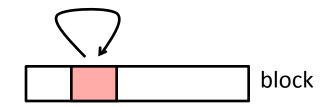
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■ Temporal locality:

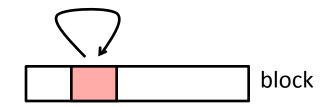
 Recently referenced items are likely to be referenced again in the near future



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 Recently referenced items are likely to be referenced again in the near future

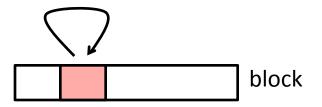


Why Caches Work

Locality: Programs tend to use data and instructions with addresses near or equal to those they have used recently

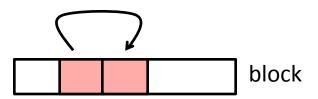
Temporal locality:

 Recently referenced items are likely to be referenced again in the near future



Spatial locality:

 Items with nearby addresses tend to be referenced close together in time



Data:

- Temporal: **sum** referenced in each iteration
- Spatial: array a [] accessed in stride-1 pattern

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- Spatial: array a [] accessed in stride-1 pattern

Instructions:

- Temporal: cycle through loop repeatedly
- Spatial: reference instructions in sequence
- Being able to assess the locality of code is a crucial skill for a programmer

Multidimensional (Nested) Arrays

Declaration

 $T \mathbf{A}[R][C];$

- 2D array of data type T
- R rows, C columns
- Type *T* element requires *K* bytes

Array Size

R * C * K bytes

Arrangement

Row-Major Ordering

int A[R][C];

A [0] [0]		A [0] [C-1]	A [1] [0]		A [1] [C-1]		•	•	•	A [R-1] [0]		A [R-1] [C-1]
4*R*C Bytes												

A[0][0] • • • A[0][C-1]

A[R-1][0] • • • A[R-1][C-1]

A[i][j] is element of type T, which requires K bytes

Address:

$$A + i*(C*K) + j*K$$

= $A + (i*C+j) * K$

A[i][j] is element of type T, which requires K bytes

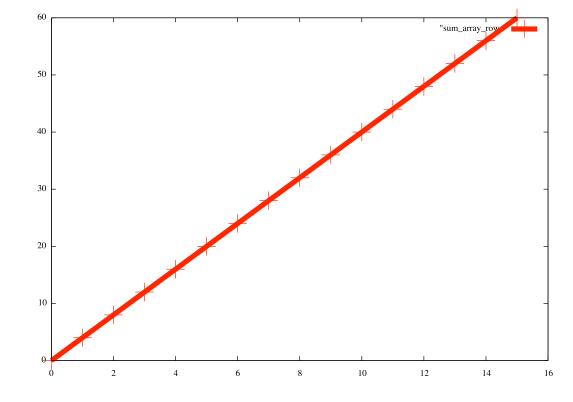
Address:

$$A + i*(C*K) + j*K$$

 $= A + (i*C+j) * K$

$$a + (i*N+j) * sizeof(int) = a + 4(i*N+j) : N=4,M=4$$

X	a	X	a
0	0	8	32
1	4	9	36
2	8	10	40
3	12	11	44
4	16	12	48
5	20	13	52
6	24	14	56
7	28	15	60



A[i][j] is element of type T, which requires K bytes

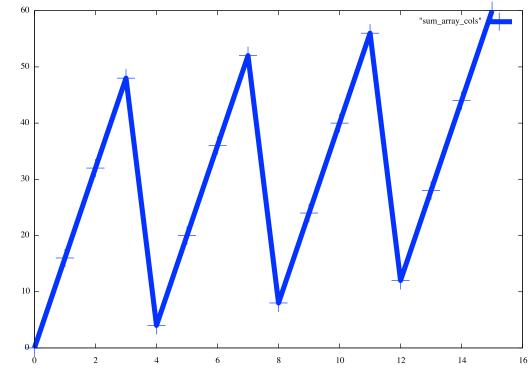
Address:

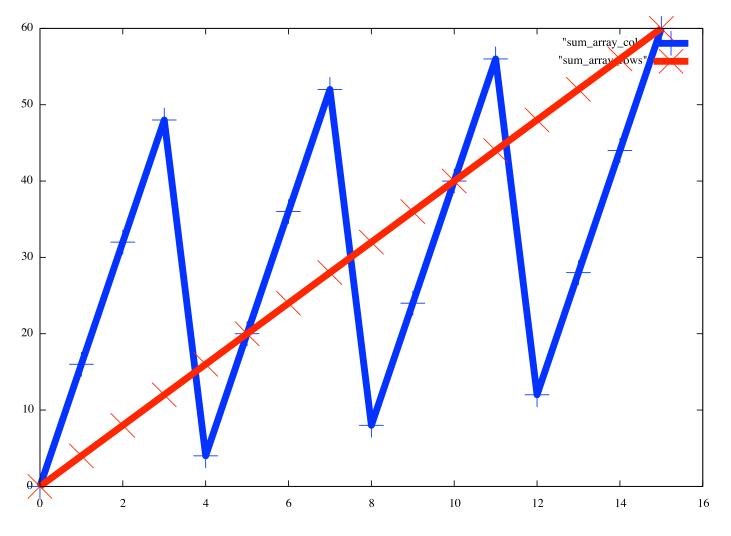
$$A + i*(C*K) + j*K$$

 $= A + (i*C+j) * K$

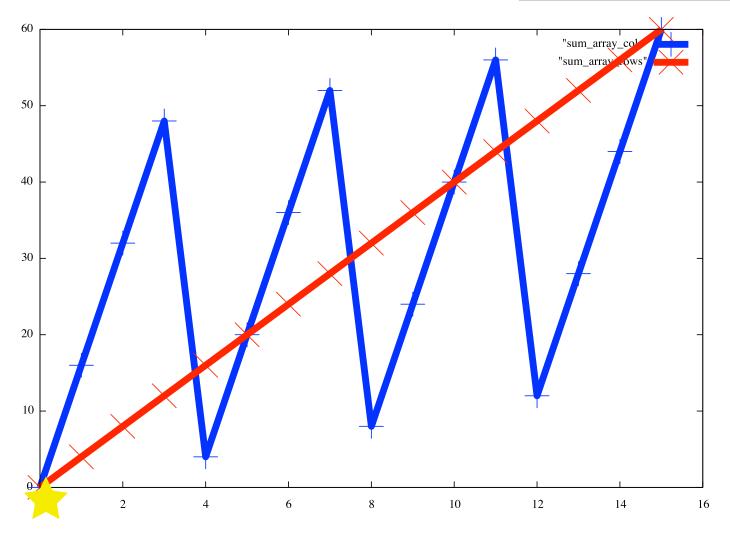
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0	0	8	8
1	16	9	24
2	32	10	40
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4	4	12	12
5	20	13	28
6	36	14	44
7	52	15	60

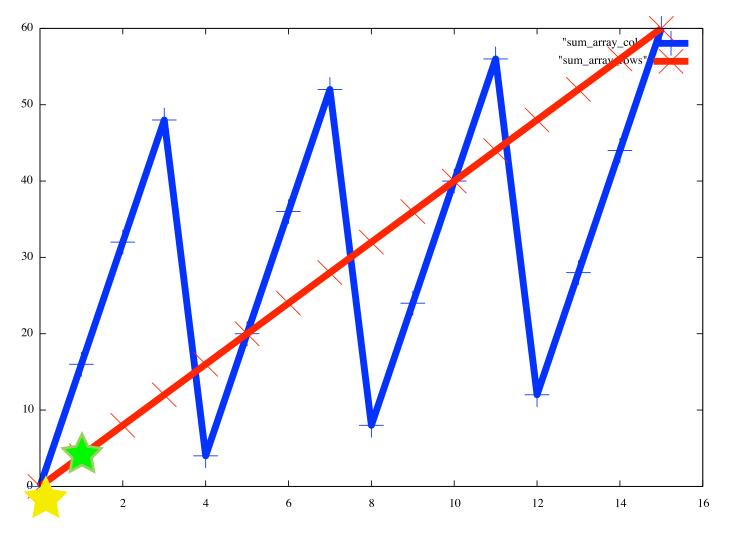




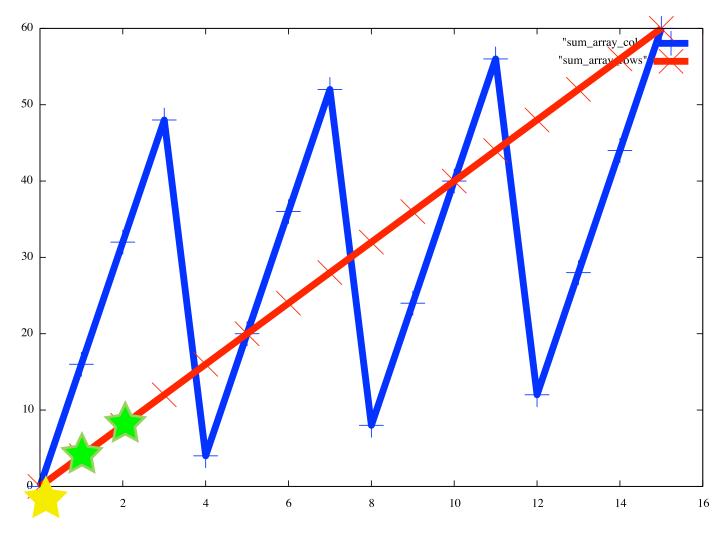
single line 16 byte cache



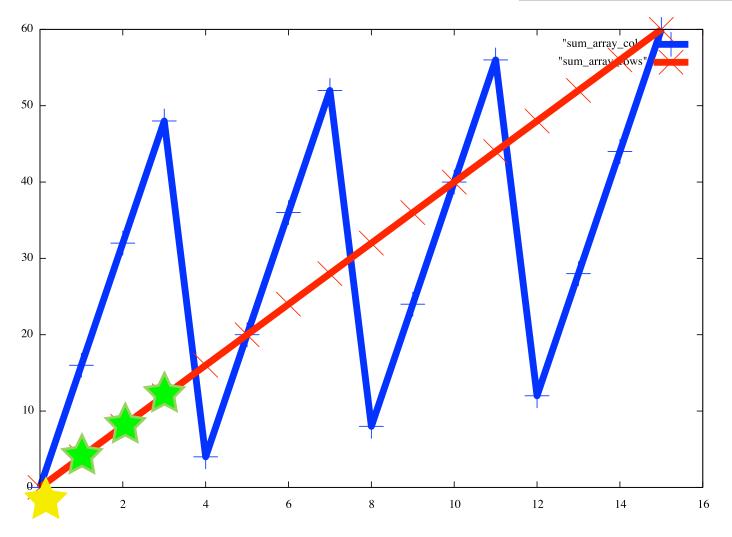




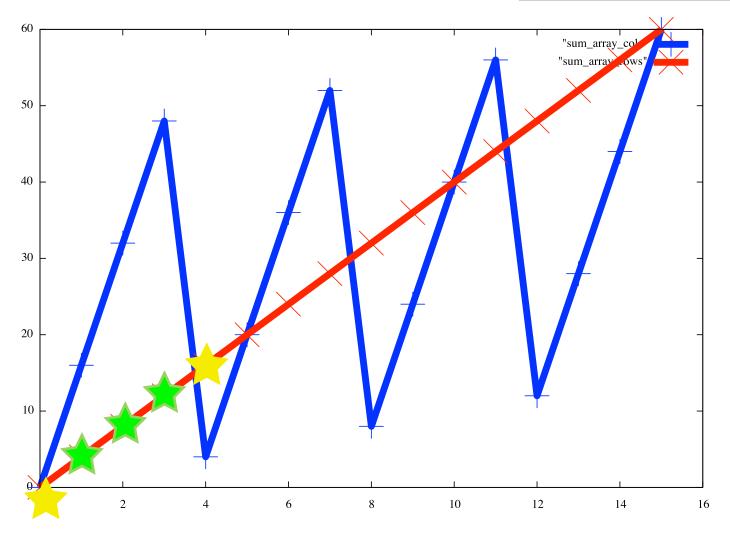
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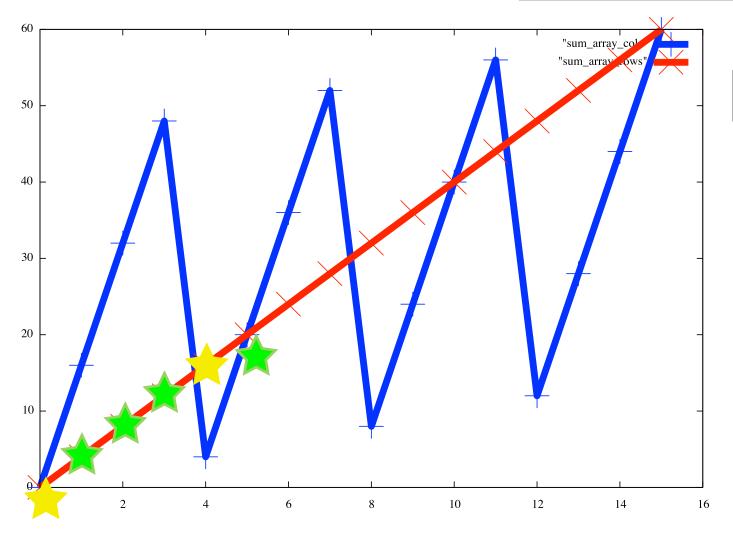
single line 16 byte cache



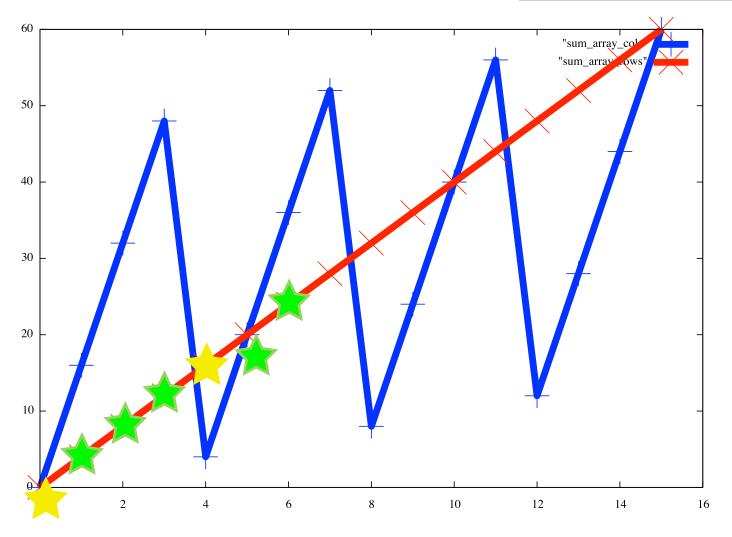




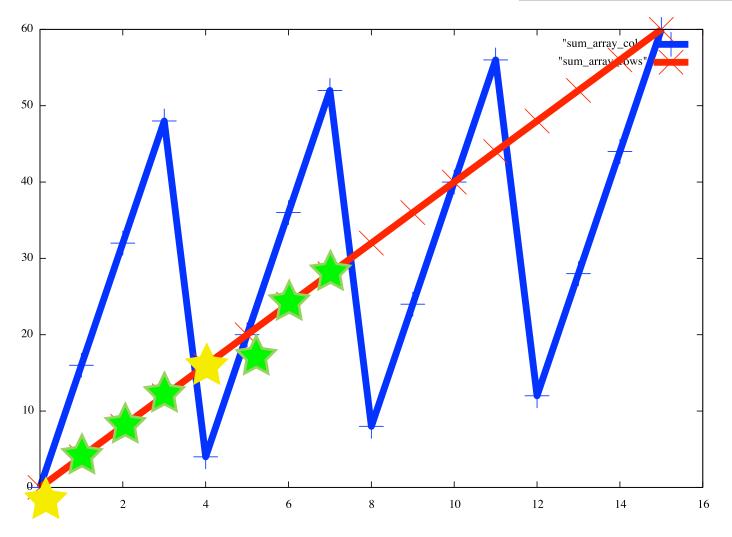




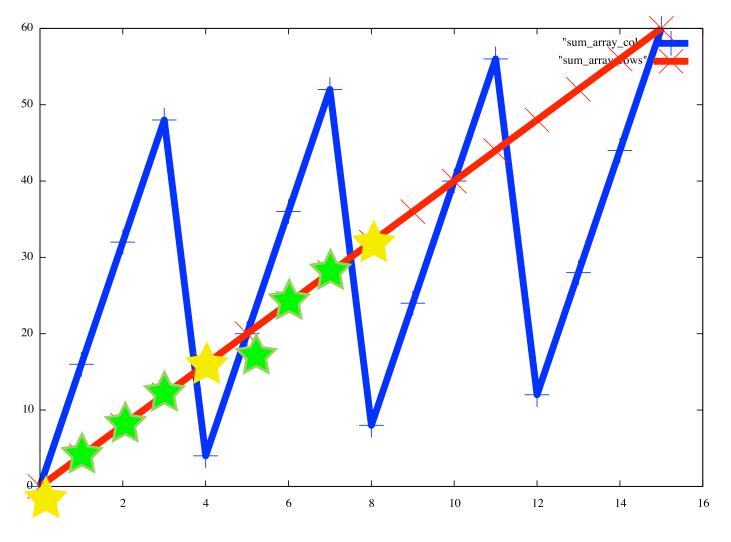
single line 16 byte cache



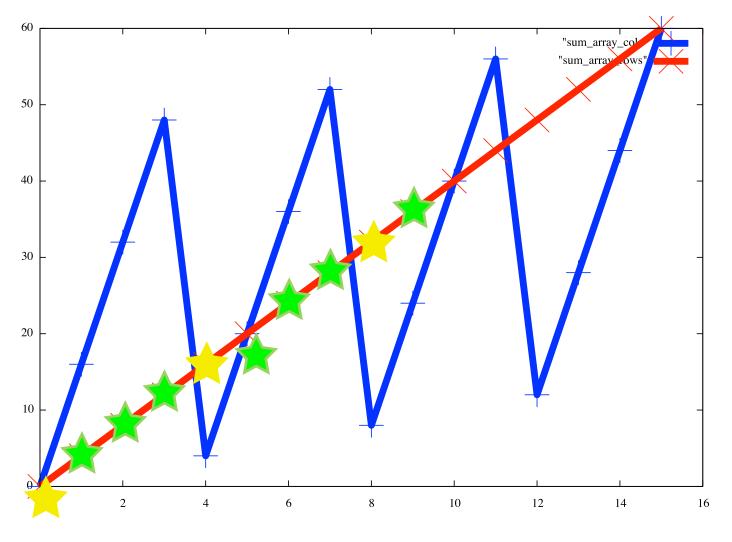




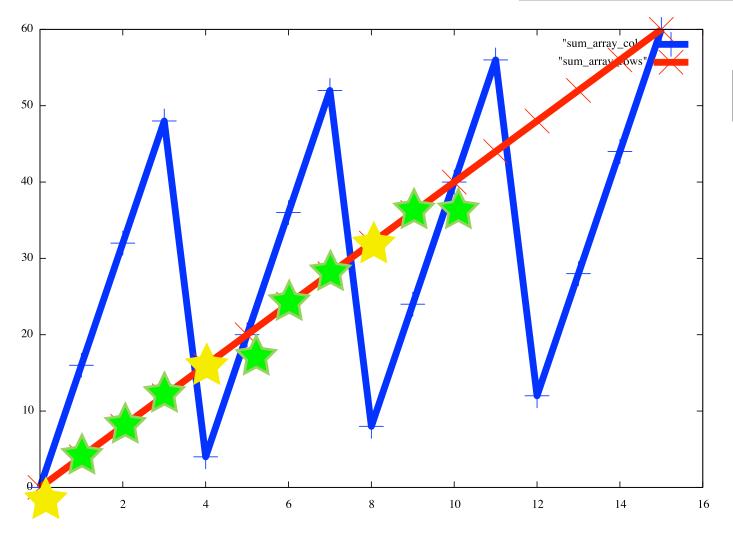




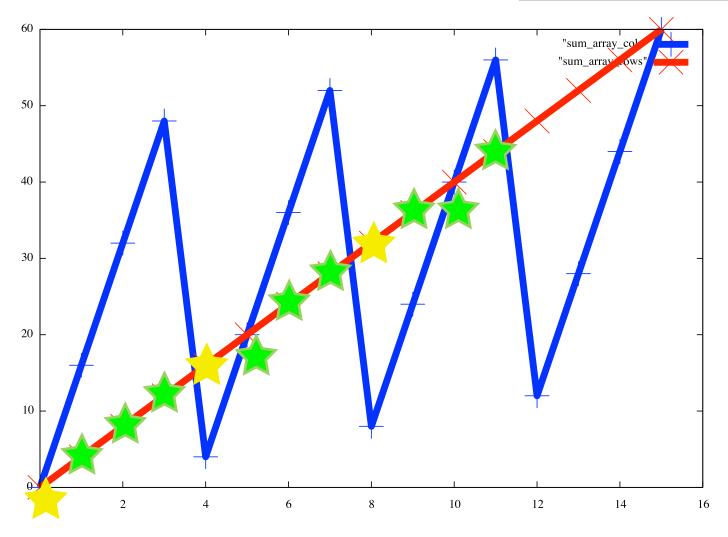
single line 16 byte cache



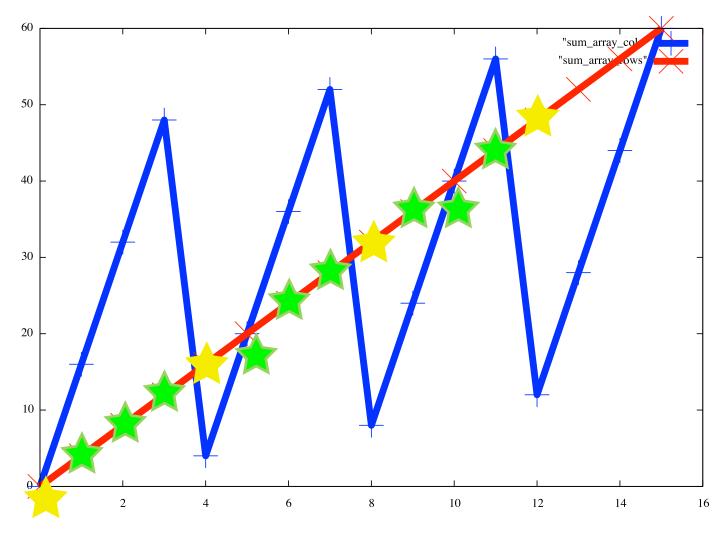
single line 16 byte cache



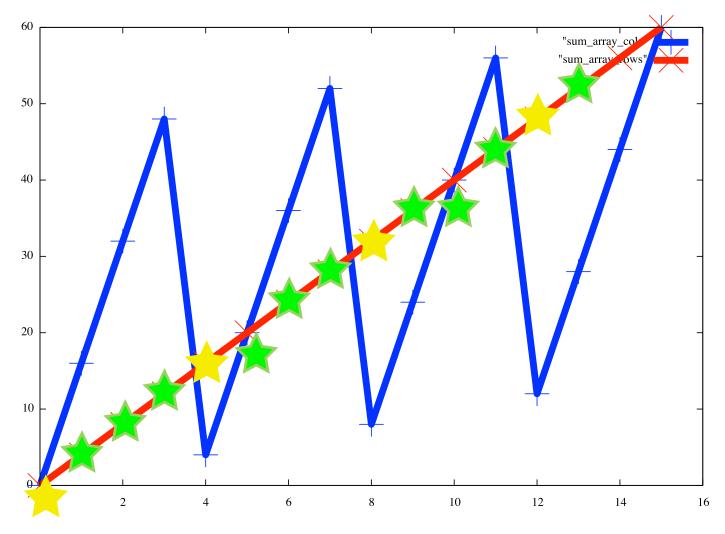
single line 16 byte cache



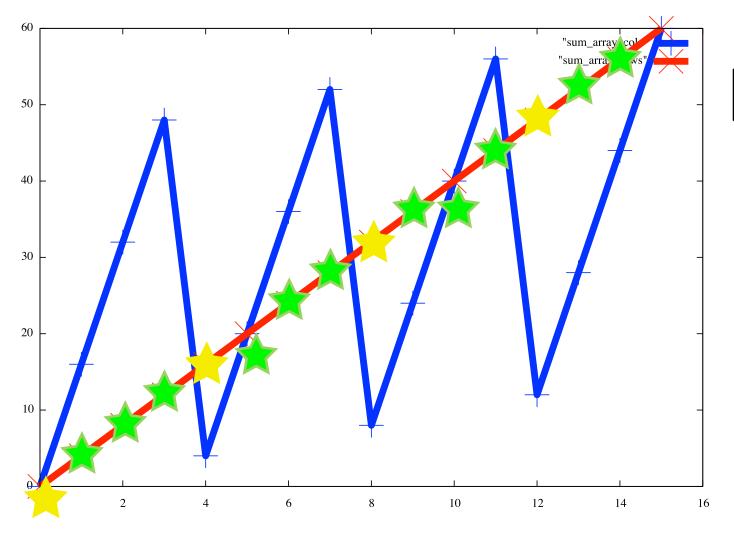




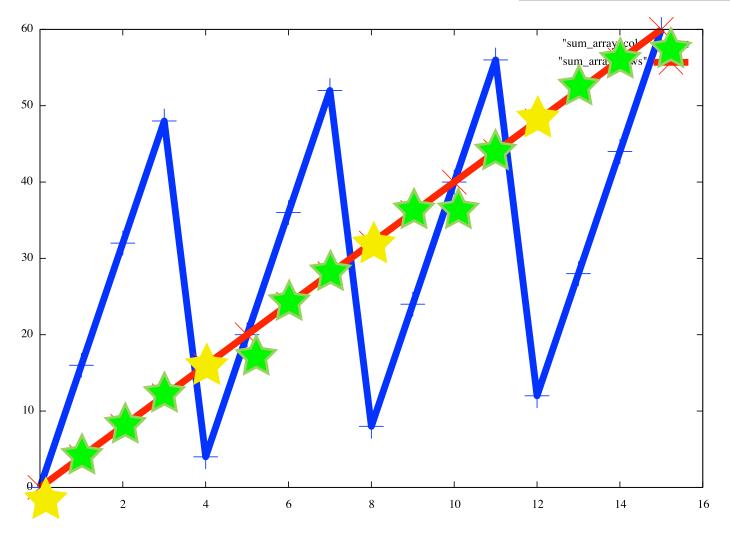
single line 16 byte cache



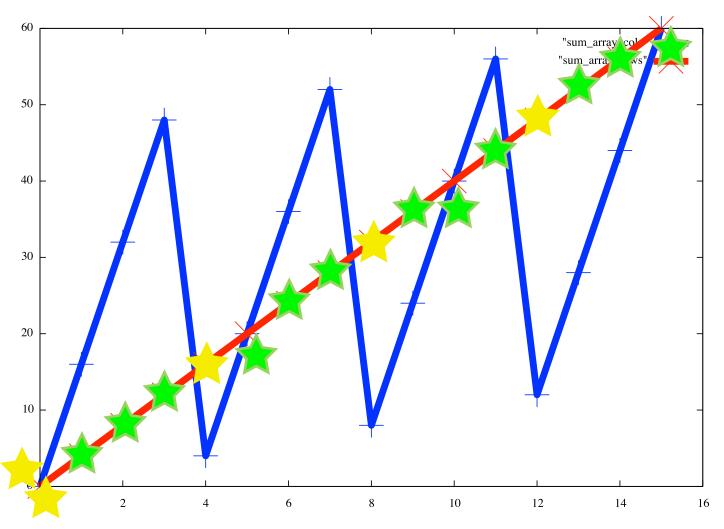
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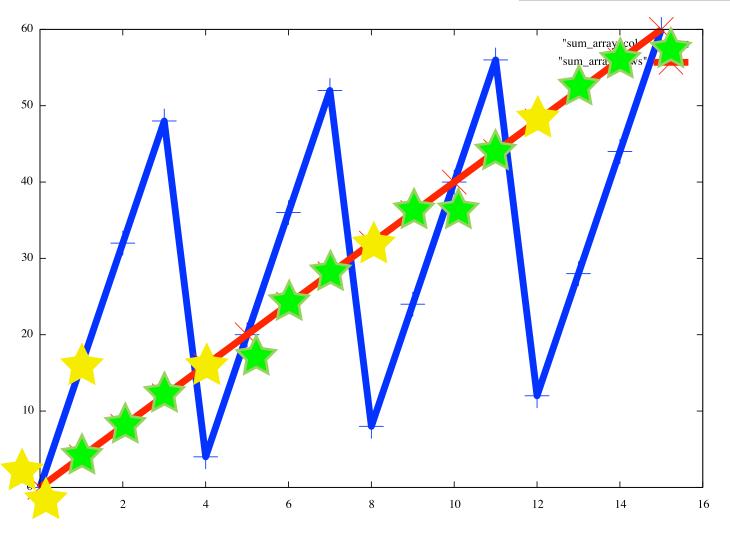
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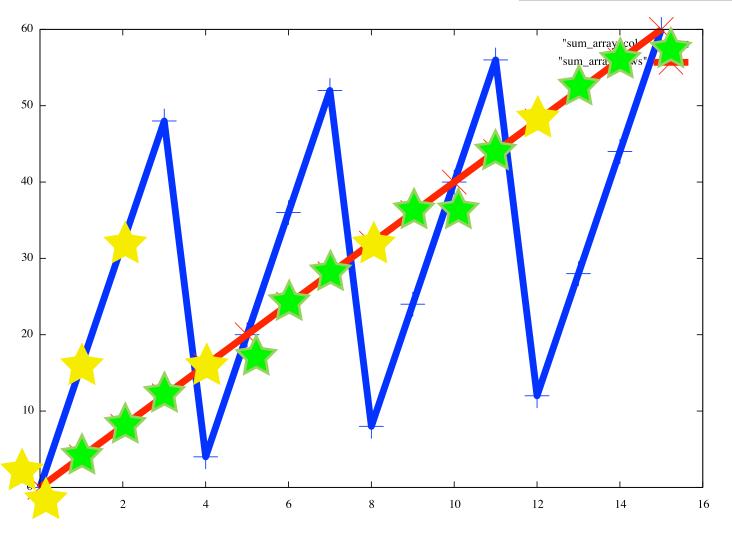
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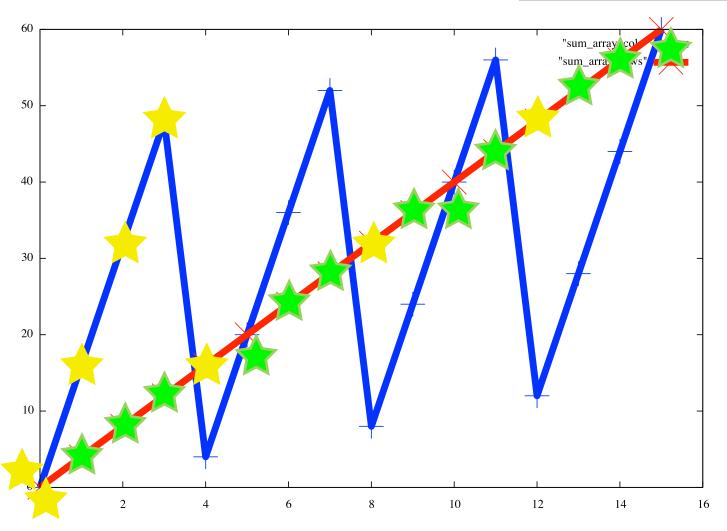




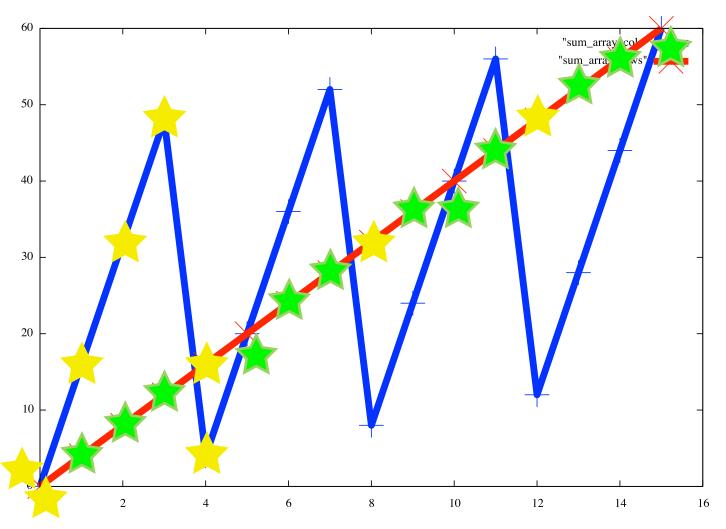




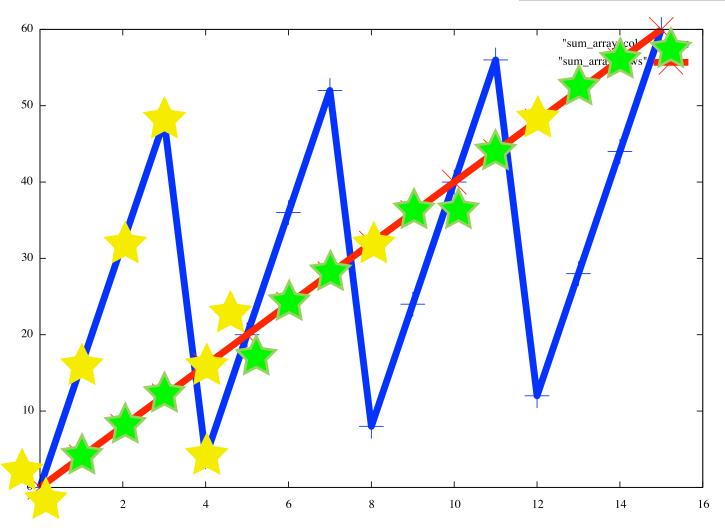
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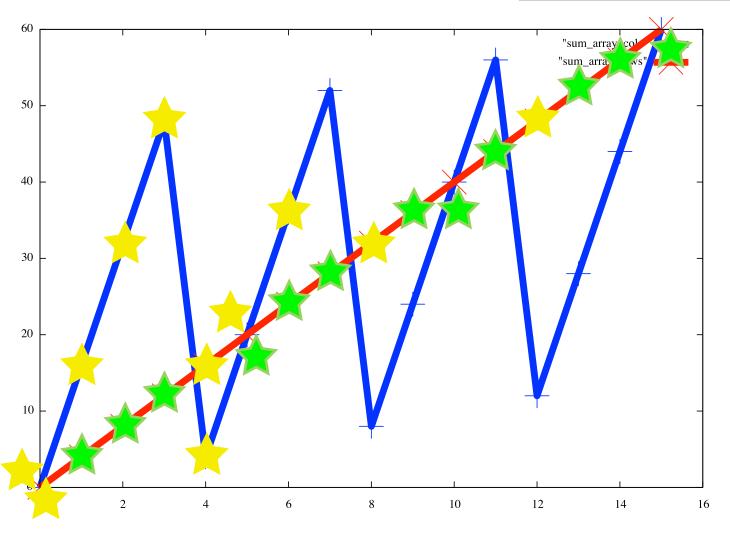




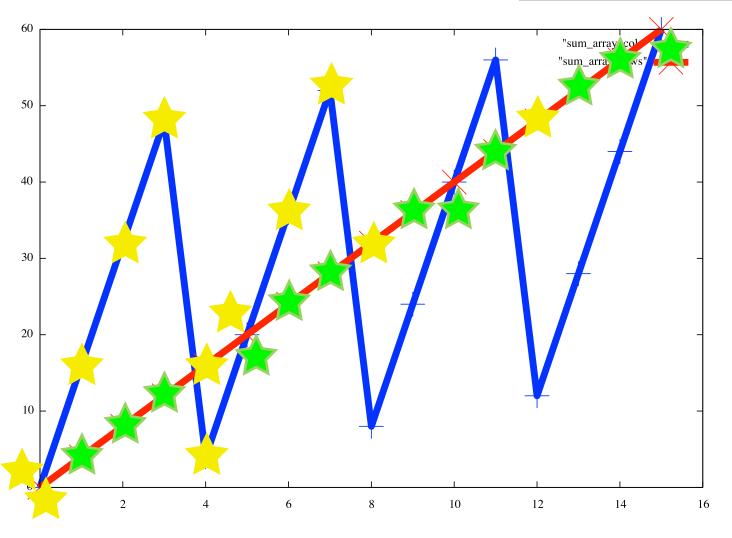




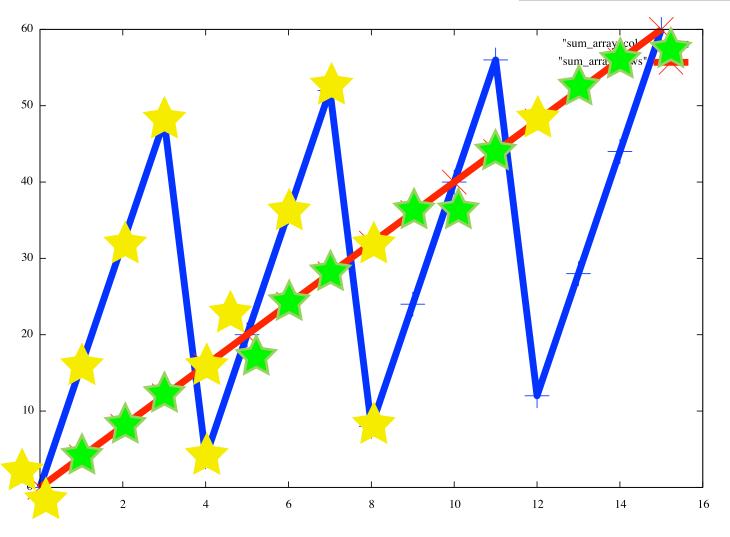






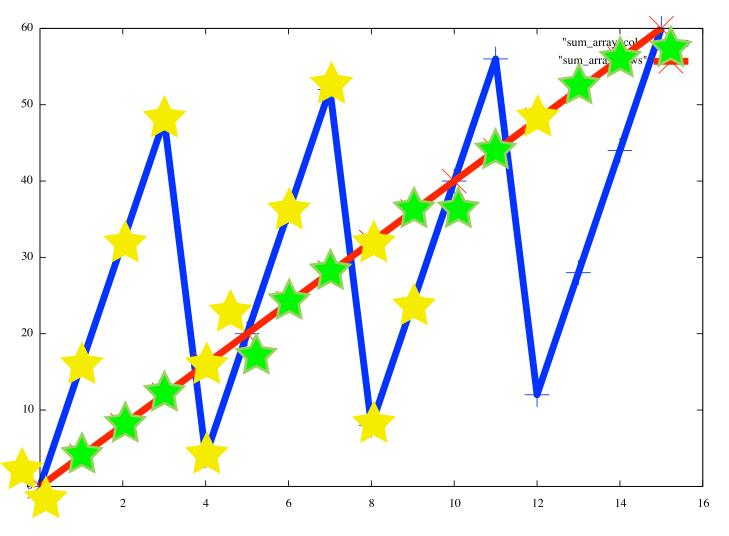




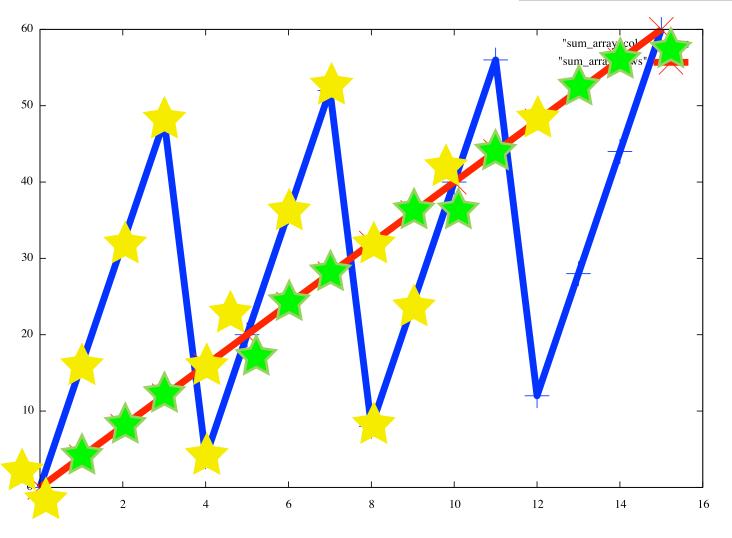


single line 16 byte cache

int int int int

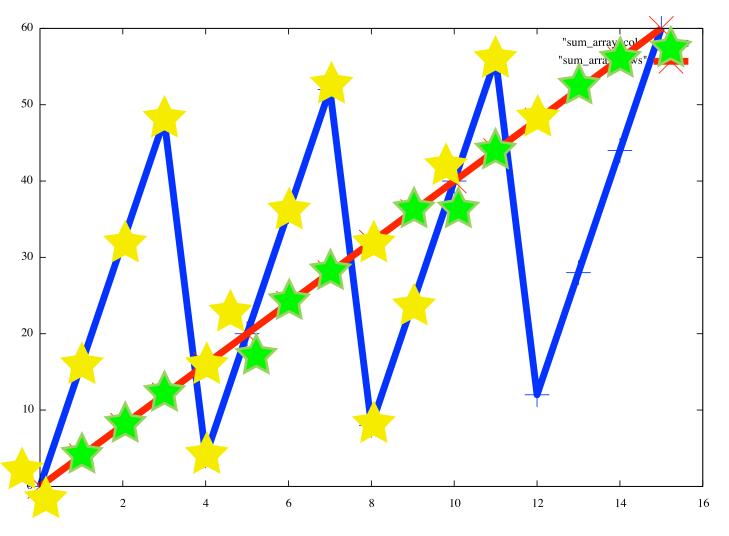


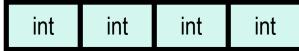


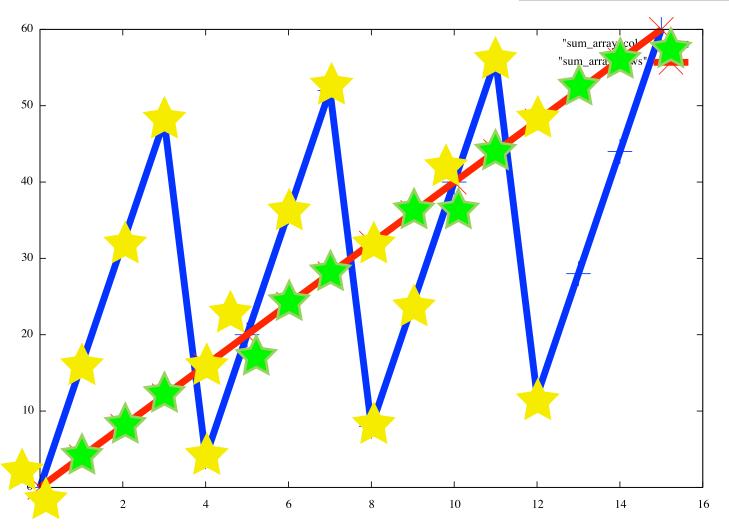


single line 16 byte cache

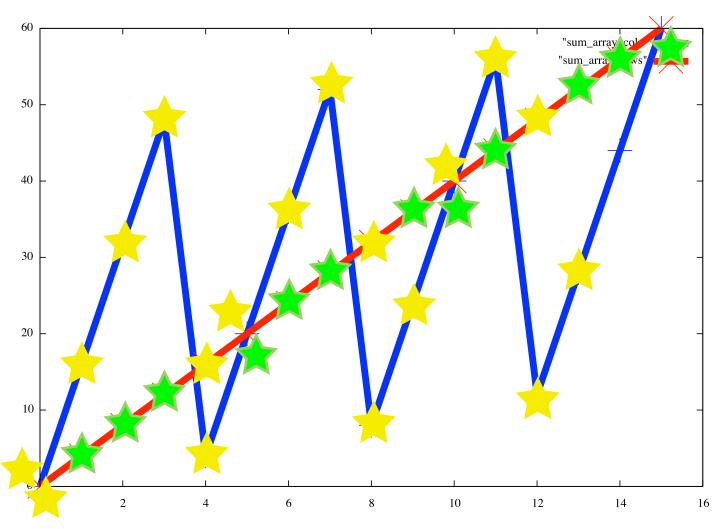
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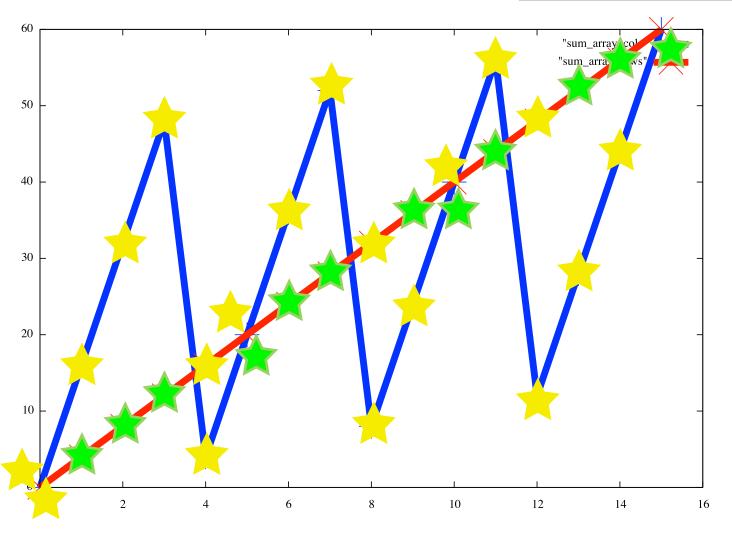






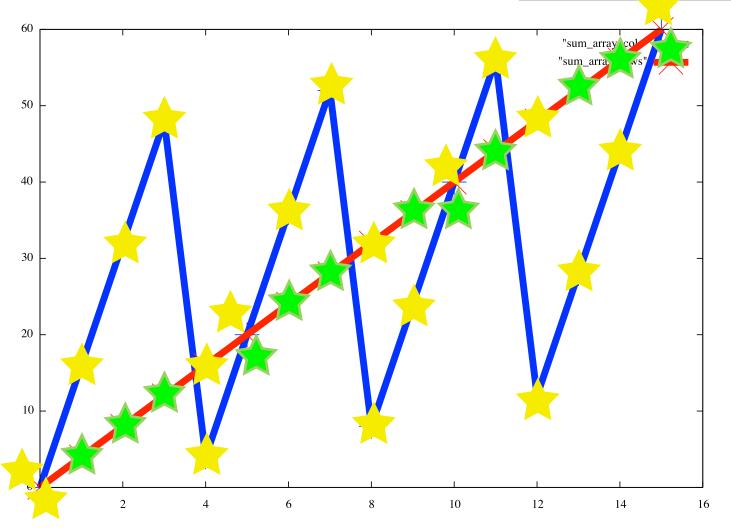




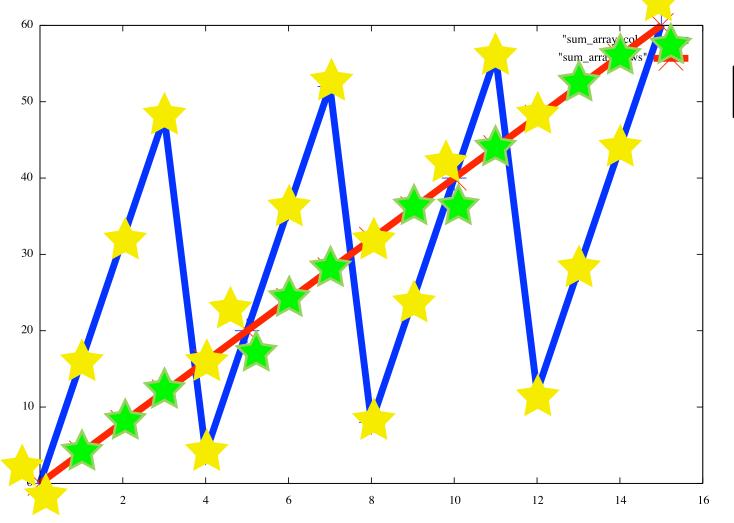


single line 16 byte cache

int int int int







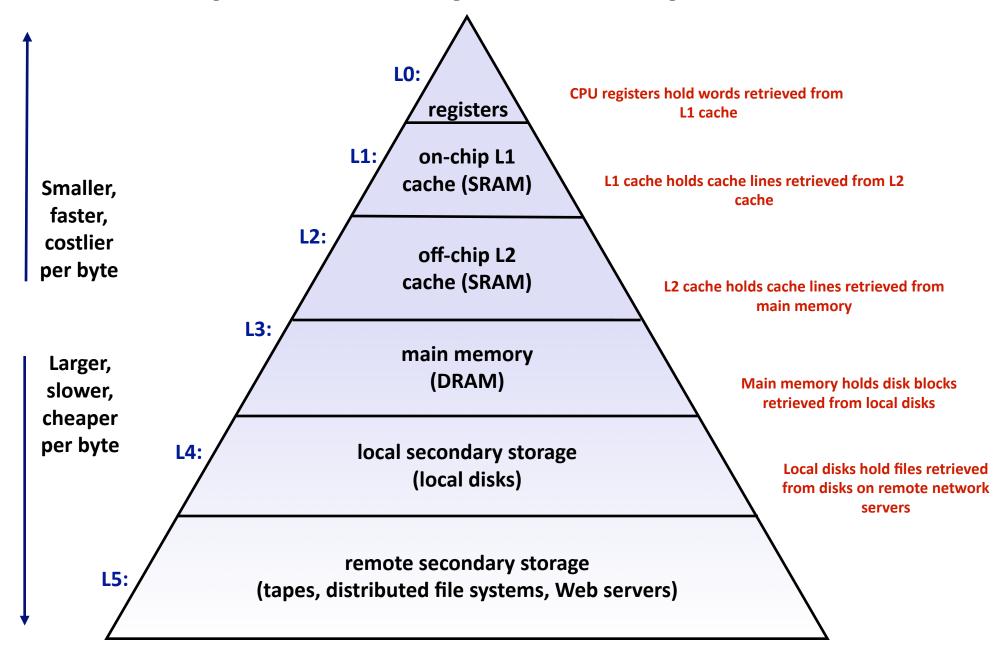


	sum array rows	sum array cols	
HITS	12	0	
MISSES	4	16	

Memory Hierarchies

- Some fundamental and enduring properties of hardware and software systems:
 - Faster storage technologies almost always cost more per byte and have lower capacity
 - The gaps between memory technology speeds are widening
 - True of registers \leftrightarrow DRAM, DRAM \leftrightarrow disk, etc.
 - Well-written programs tend to exhibit good locality
- These properties complement each other beautifully
- They suggest an approach for organizing memory and storage systems known as a memory hierarchy

An Example Memory Hierarchy



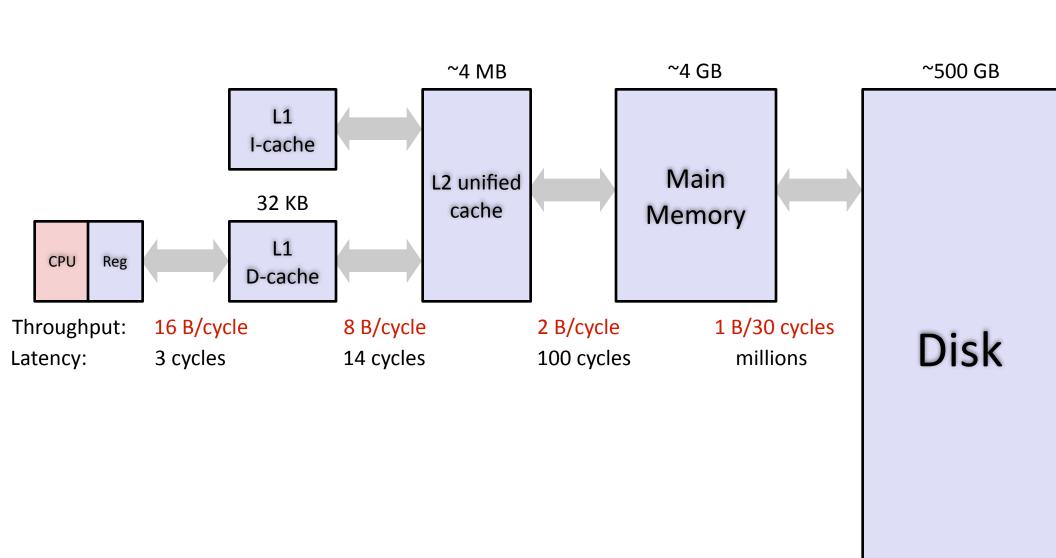
Examples of Caching in the Hierarchy

Cache Type	What is Cached?	Where is it Cached?	Latency (cycles)	Managed By
Registers	4-byte words	CPU core	0	Compiler
TLB	Address translations	On-Chip TLB	0	Hardware
L1 cache	64-bytes block	On-Chip L1	1	Hardware
L2 cache	64-bytes block	Off-Chip L2	10	Hardware
Virtual Memory	4-KB page	Main memory	100	Hardware+OS
Buffer cache	Parts of files	Main memory	100	OS
Network buffer cache	Parts of files	Local disk	10,000,000	AFS/NFS client
Browser cache	Web pages	Local disk	10,000,000	Web browser
Web cache	Web pages	Remote server disks	1,000,000,000	Web proxy server

Memory Hierarchy: Core 2 Duo

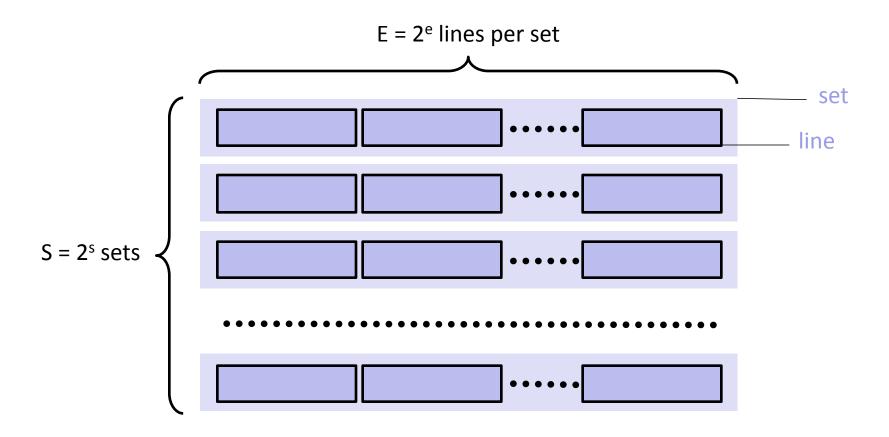
L1/L2 cache: 64 B blocks

Not drawn to scale

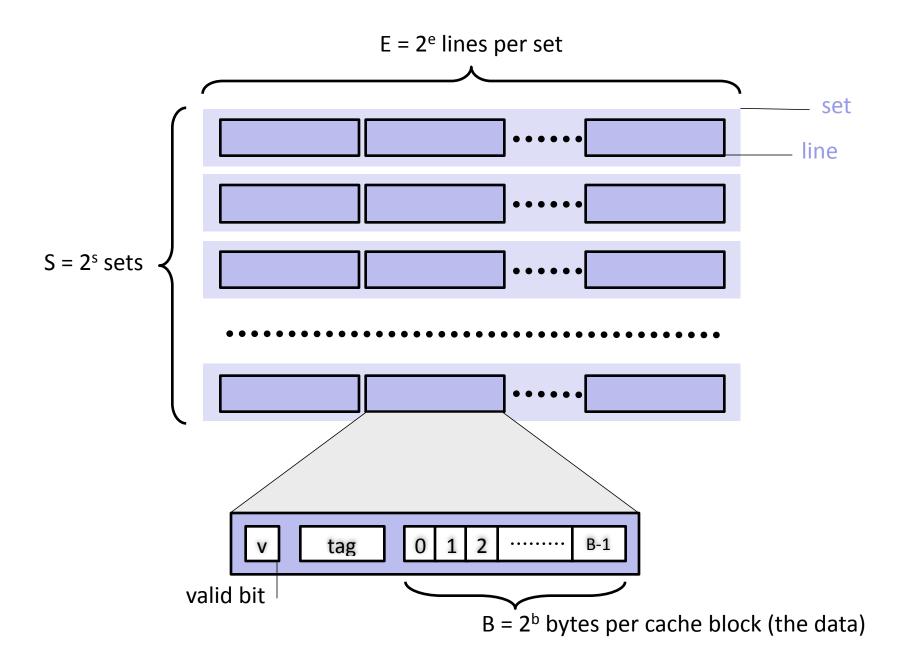


CACHE ORGANIZATION

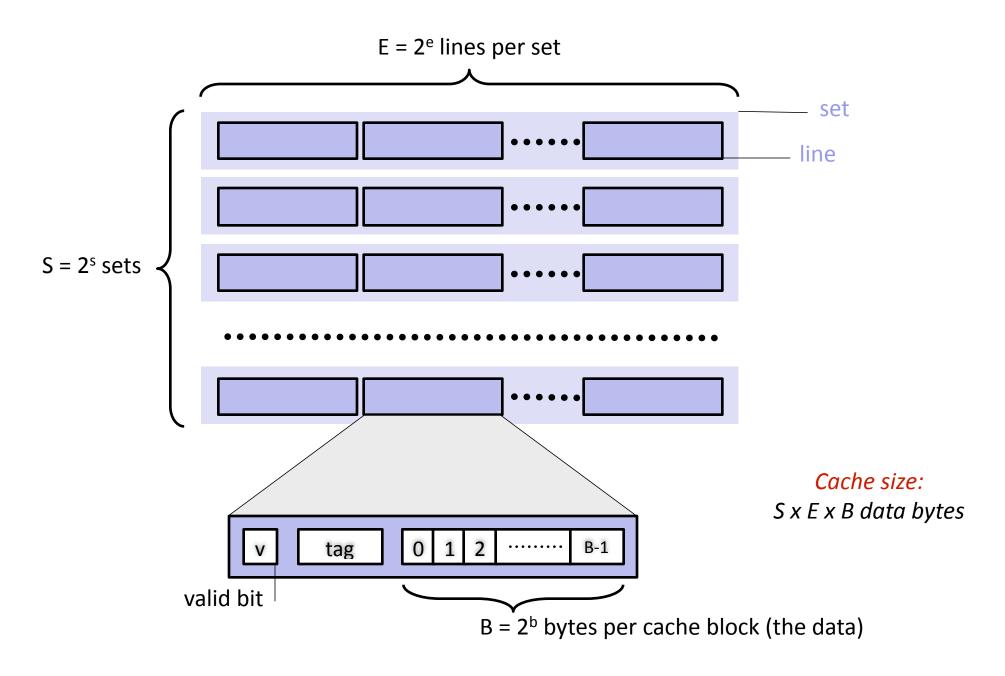
General Cache Organization (S, E, B)



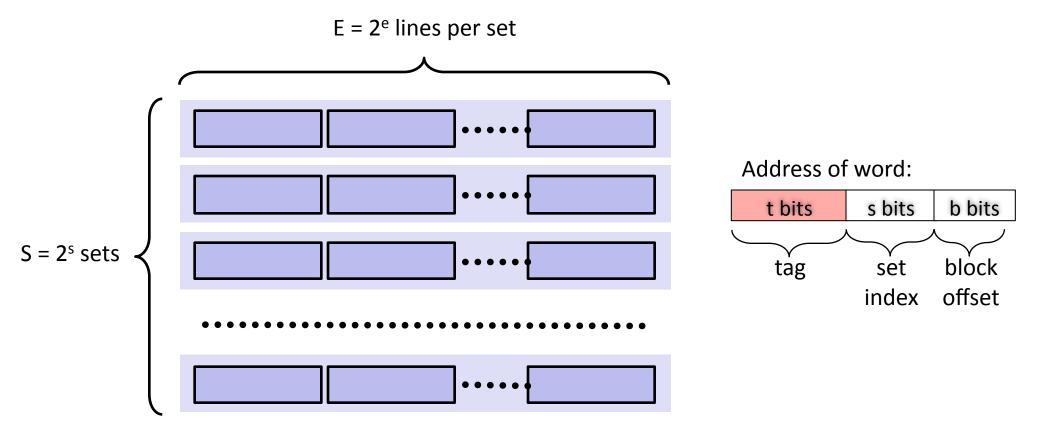
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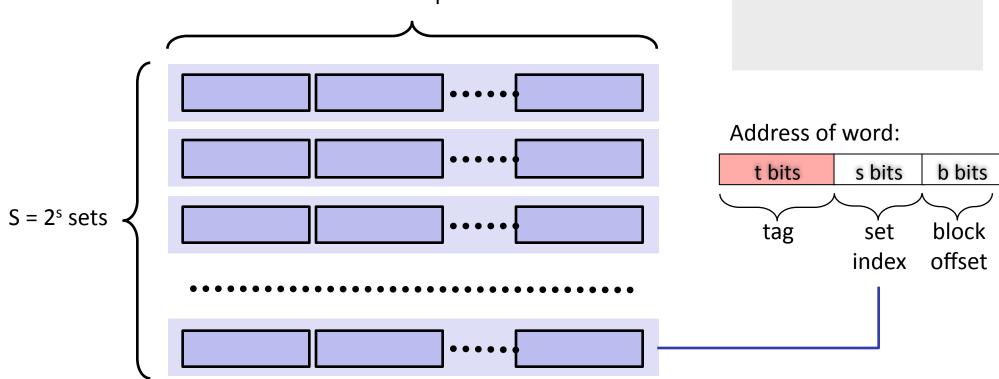


Cache Read



Cache Read

E = 2^e lines per set

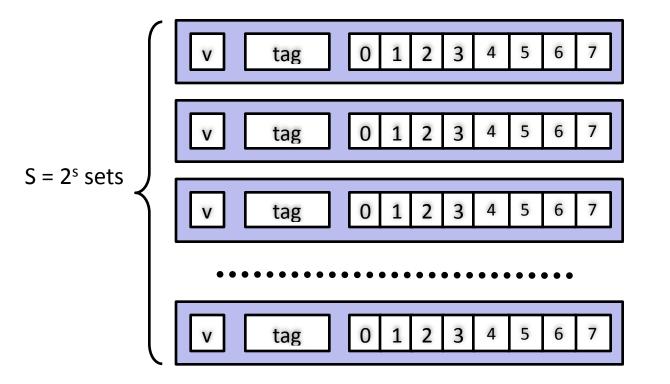


Locate set

Locate set **Cache Read** • Check if any line in set has matching tag E = 2^e lines per set *Yes + line valid: hit* Address of word: t bits s bits b bits $S = 2^s$ sets tag block set offset index B-1 tag valid bit $B = 2^b$ bytes per cache block (the data)

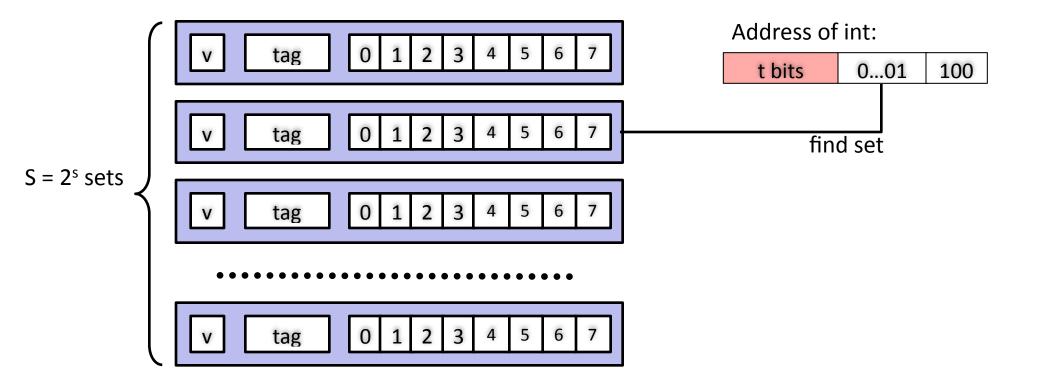
Locate set **Cache Read** • Check if any line in set has matching tag $E = 2^e$ lines per set Yes + line valid: hit Locate data starting at offset Address of word: t bits s bits b bits $S = 2^s$ sets block set tag index_offset data begins at this offset B-1 tag valid bit $B = 2^b$ bytes per cache block (the data)

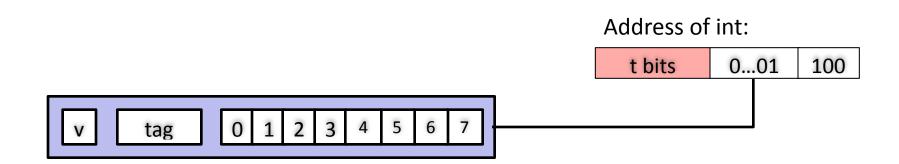
Direct mapped: One line per set Assume: cache block size 8 bytes

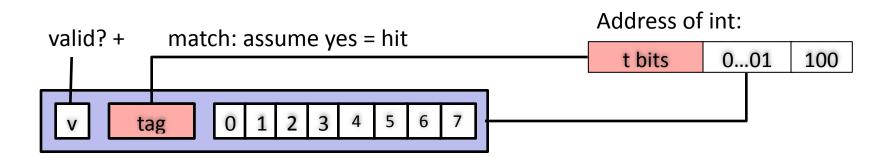


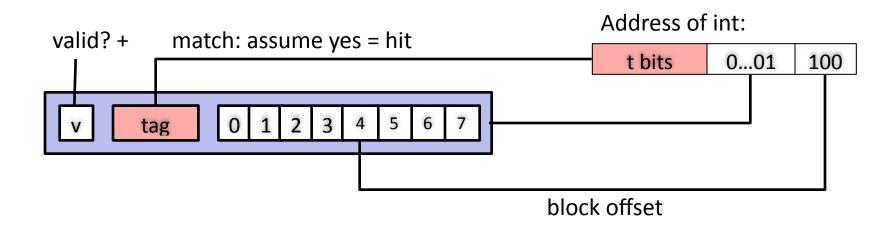
Address of int:

t bits 0...01 100

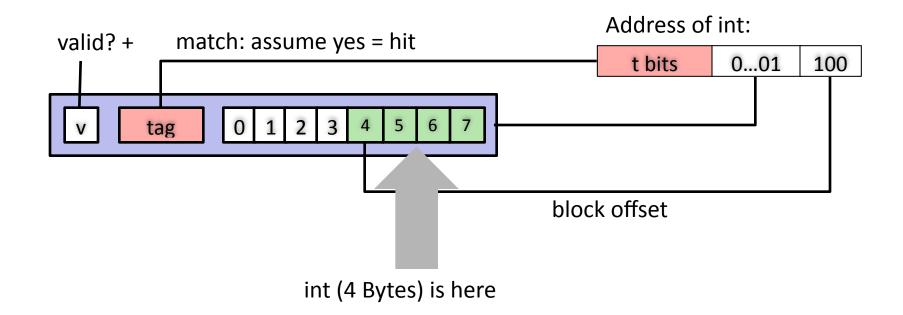








Direct mapped: One line per set Assume: cache block size 8 bytes



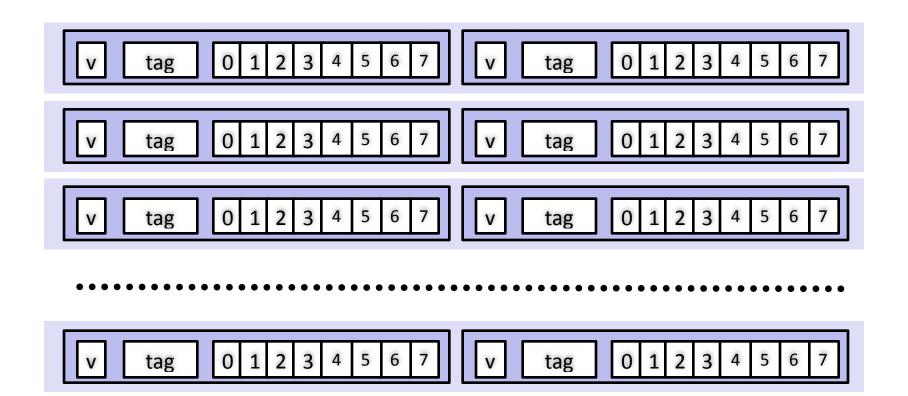
No match: old line is evicted and replaced

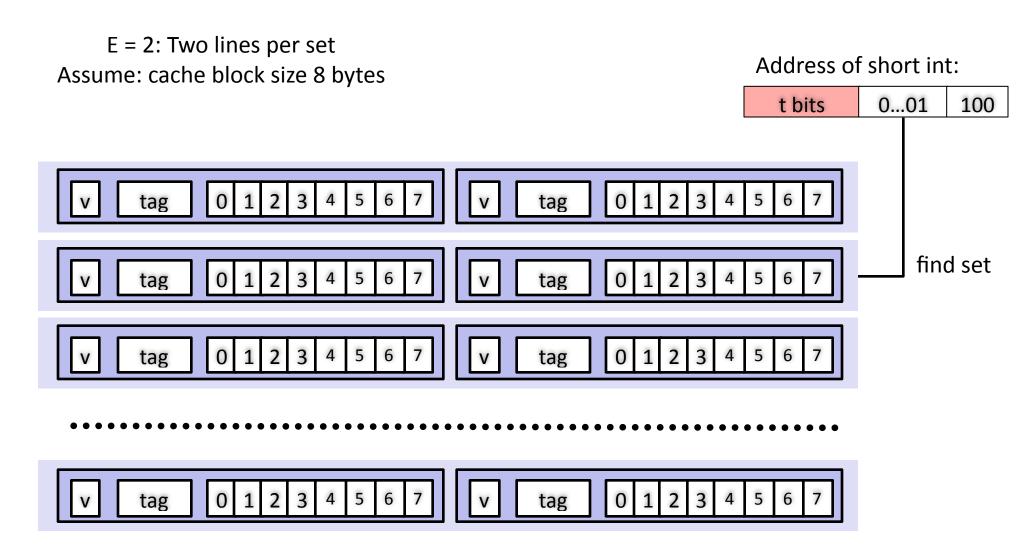
E = 2: Two lines per set

Assume: cache block size 8 bytes

Address of short int:

t bits 0...01 100





E = 2: Two lines per set
Assume: cache block size 8 bytes

Address of short int:

t bits

0...01

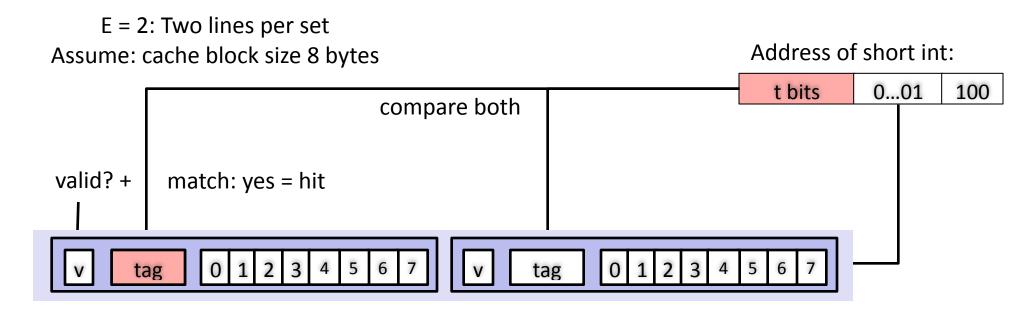
100

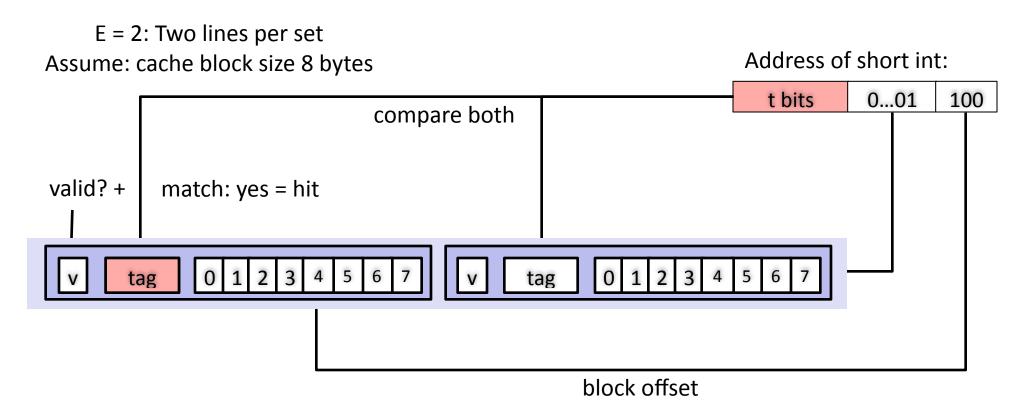
E = 2: Two lines per set

Assume: cache block size 8 bytes

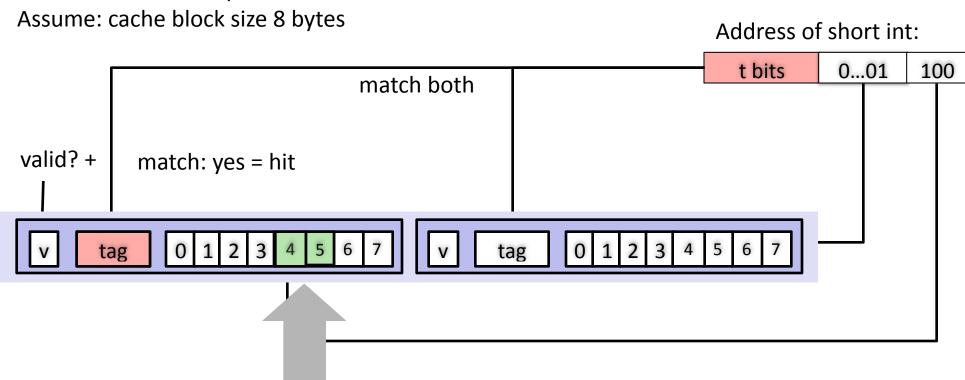
Compare both

v tag 0 1 2 3 4 5 6 7 v tag 0 1 2 3 4 5 6 7





E = 2: Two lines per set



short int (2 Bytes) is here

No match:

- One line in set is selected for eviction and replacement
- Replacement policies: random, least recently used (LRU), ...

What about writes?

- Multiple copies of data exist:
 - L1, L2, Main Memory, Disk
- What to do one a write-hit?
 - Write-through (write immediately to memory)
 - Write-back (defer write to memory until replacement of line)
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Typical

- Write-through + No-write-allocate
- Write-back + Write-allocate

Software Caches are More Flexible

Examples

File system buffer caches, web browser caches, etc.

Some design differences

- Almost always fully associative
 - so, no placement restrictions
 - index structures like hash tables are common
- Often use complex replacement policies
 - misses are very expensive when disk or network involved
 - worth thousands of cycles to avoid them
- Not necessarily constrained to single "block" transfers
 - may fetch or write-back in larger units, opportunistically

CACHE OPTIMIZATIONS

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- Loop transformations

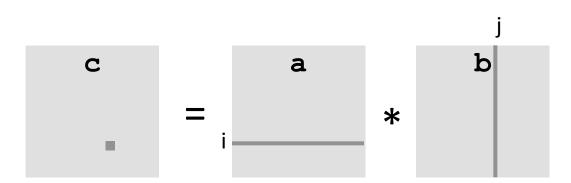
Cache versus register level optimization:

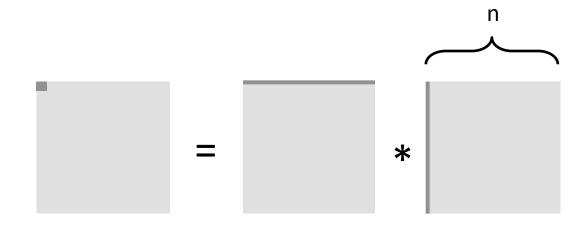
- In both cases locality desirable
- Register space much smaller + requires scalar replacement to exploit temporal locality
- Register level optimizations include exhibiting instruction level parallelism (conflicts with locality)

Example: Matrix Multiplication

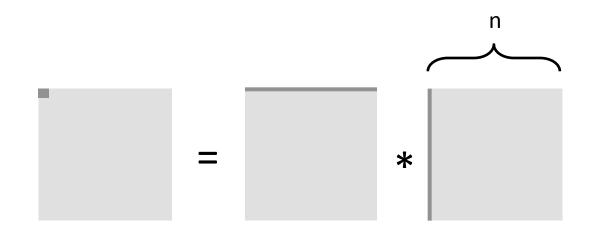
```
c = (double *) calloc(sizeof(double), n*n);

/* Multiply n x n matrices a and b */
void mmm(double *a, double *b, double *c, int n) {
   int i, j, k;
   for (i = 0; i < n; i++)
        for (j = 0; j < n; j++)
        for (k = 0; k < n; k++)
        c[i*n+j] += a[i*n + k]*b[k*n + j];
}</pre>
```

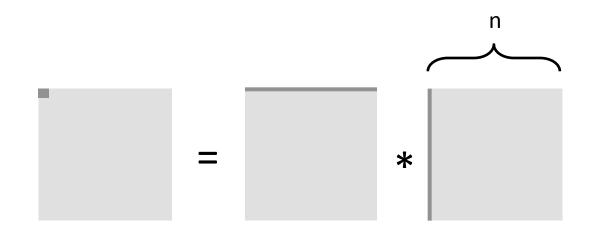




- Matrix elements are doubles
- Cache block = 8 doubles
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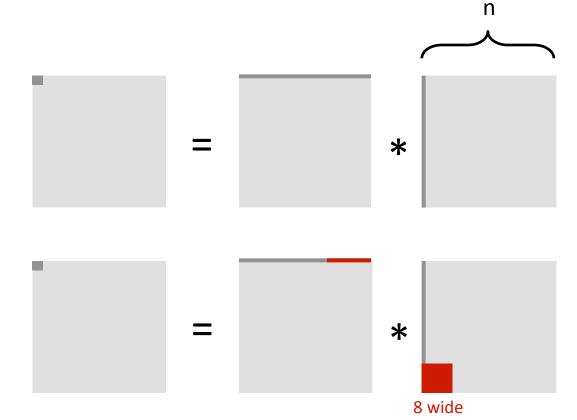
Assume:

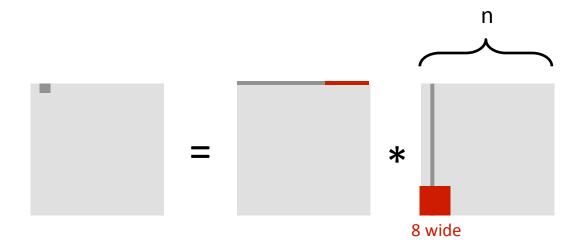
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First iteration:

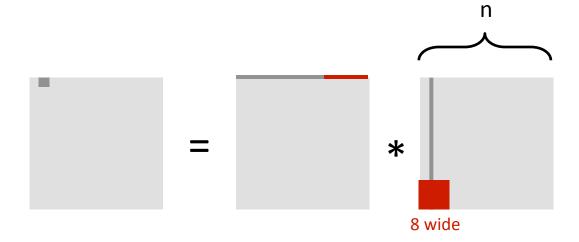
- n/8 + n = 9n/8 misses

Afterwards in cache: (schematic)

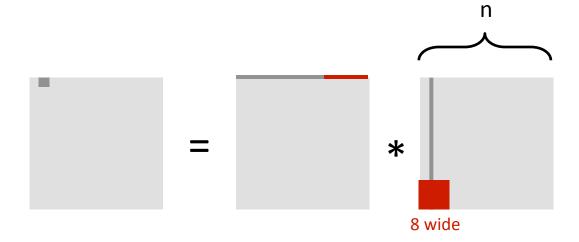




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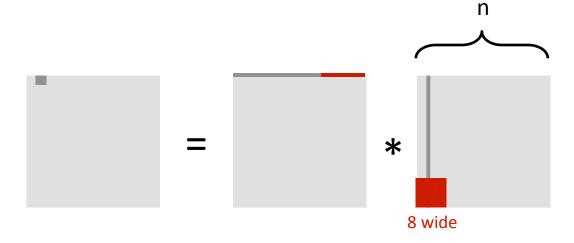


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Second iteration:

Again:n/8 + n = 9n/8 misses

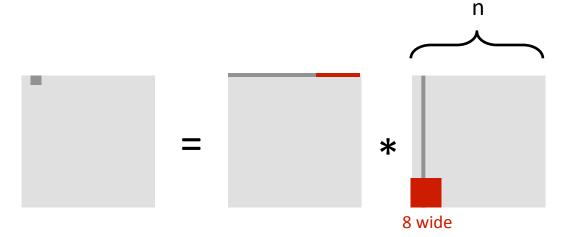


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Second iteration:

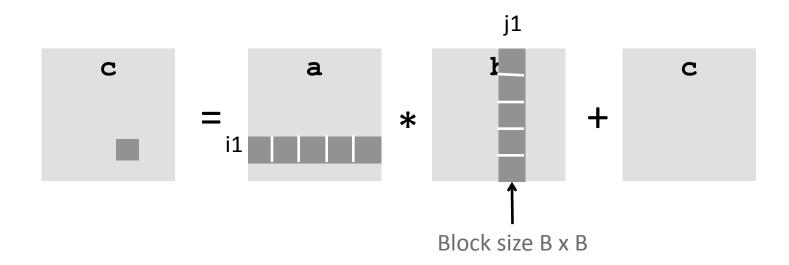
Again: n/8 + n = 9n/8 misses

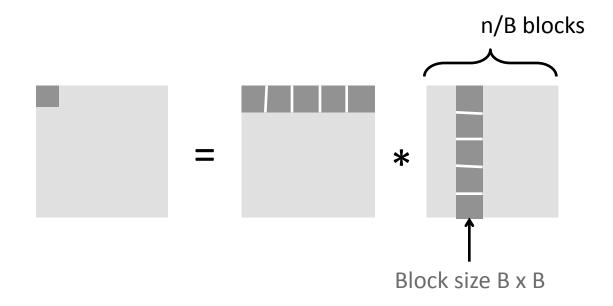


■ Total misses:

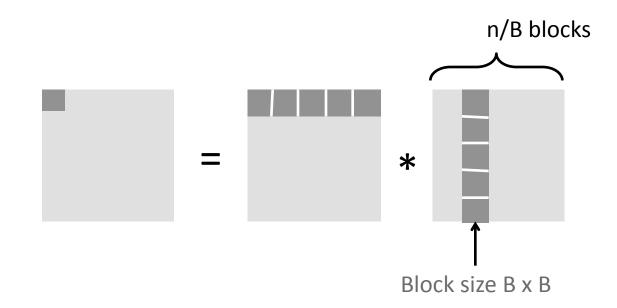
 $-9n/8 * n^2 = (9/8) * n^3$

Blocked Matrix Multiplication

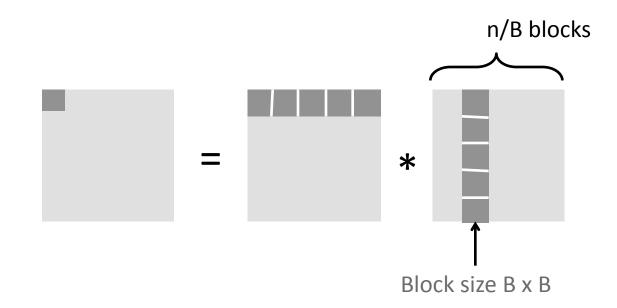




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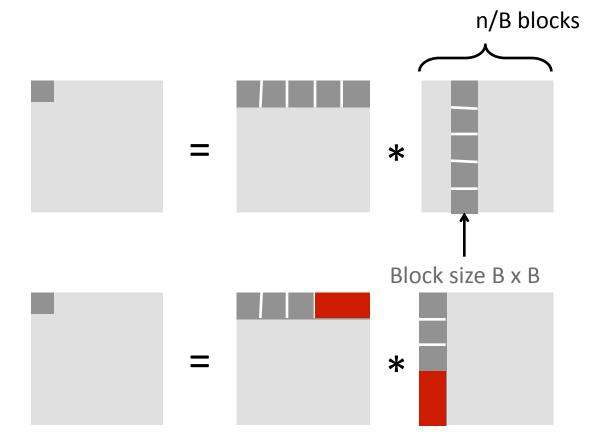
Assume:

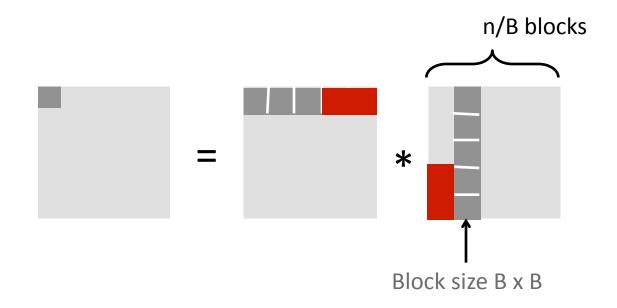
- Cache block = 8 doubles
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First (block) iteration:

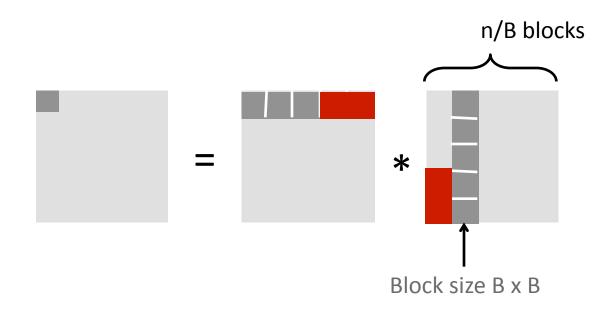
- B²/8 misses for each block
- $2n/B * B^2/8 = nB/4$ (omitting matrix c)

Afterwards in cache (schematic)

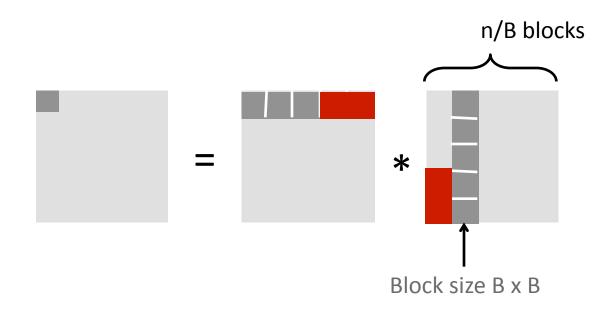




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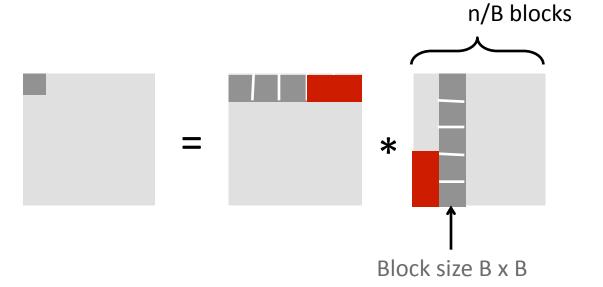


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Second (block) iteration:

- Same as first iteration
- $-2n/B * B^2/8 = nB/4$

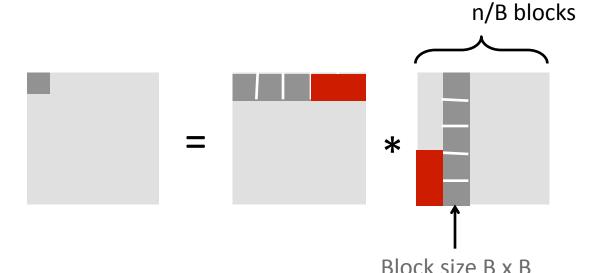


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- Three blocks fit into cache: 3B² < C

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■ Total misses:

 \blacksquare nB/4 * (n/B)² = n³/(4B)

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- Blocking: 1/(4B) * n³

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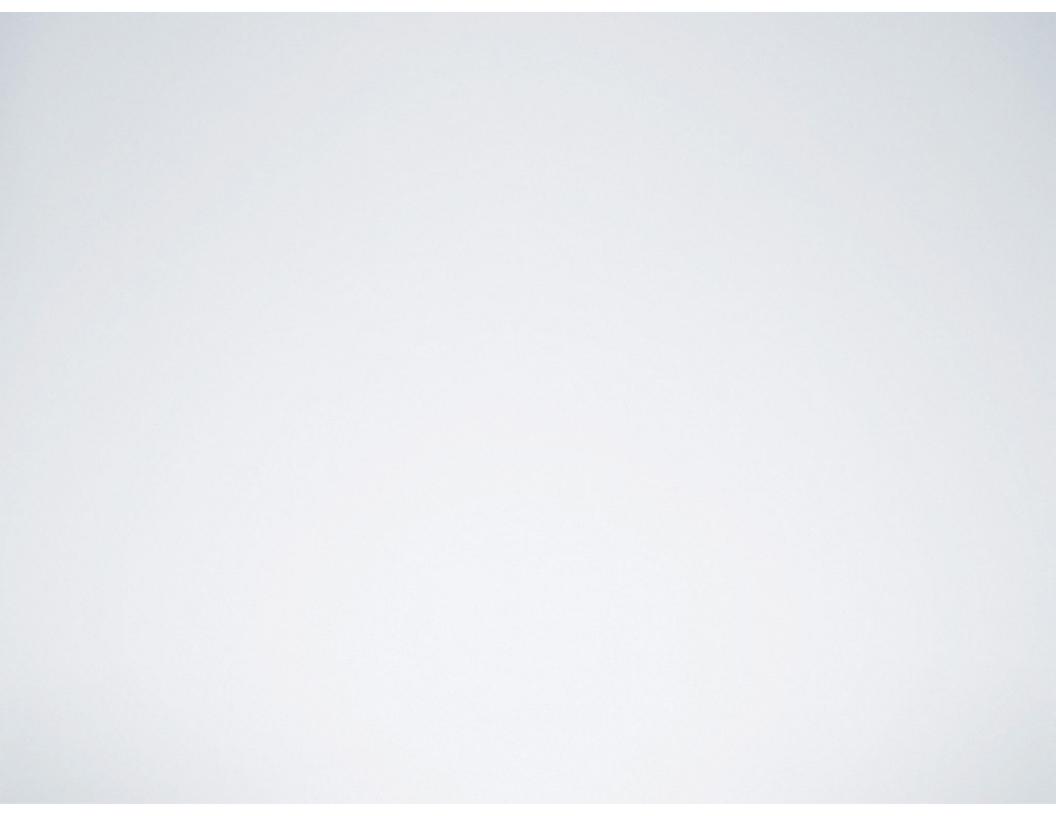
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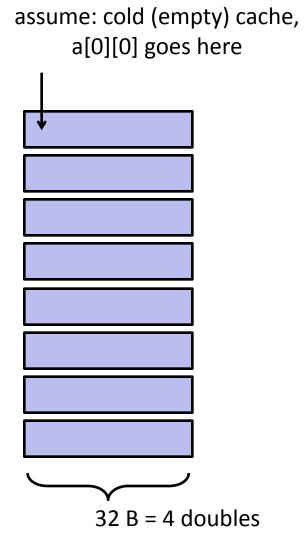
- No blocking: (9/8) * n³
- Blocking: 1/(4B) * n³
- Suggest largest possible block size B, but limit 3B² < C! (can possibly be relaxed a bit, but there is a limit for B)
- Reason for dramatic difference:
 - Matrix multiplication has inherent temporal locality:
 - Input data: 3n², computation 2n³
 - Every array elements used O(n) times!
 - But program has to be written properly



Locality Example #3

How can it be fixed?

Example



blackboard

Example

Ignore the variables sum, i, j

