## Math 141

### Lecture 16[material reduced]

**Greg Maloney** 

**Todor Miley** 

University of Massachusetts Boston

Spring 2015

## Outline

- Curves
  - The Cycloid

2 Arc Length

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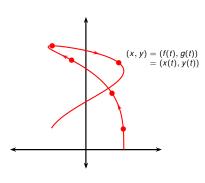
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# Curves Defined by Parametric Equations



- Suppose a particle moves along the curve in the picture.
- The x-coordinate and y-coordinate of the particle are some functions of the time t.
- We can write x = f(t) and y = g(t).
- Less formally, we may directly write (x, y) = (x(t), y(t)).
- We say that the equations  $\begin{vmatrix} x &= f(t) \\ y &= g(t) \end{vmatrix}$  are parametric equations of a parametric curve.
- Note that the curve can't be written as y = f(x): it fails the vertical line test.

## Definition (Curve in *n*-dimensional space)

We define an arbitrary n-tuple of functions  $f_1, \ldots, f_n$  on [a, b] to be a parametric curve (or simply curve). If C is a curve, we write C as:

$$C: \begin{vmatrix} x_1 & = & f_1(t) \\ x_2 & = & f_2(t) \\ & \vdots & \\ x_n & = & f_n(t) \end{vmatrix}, t \in [a, b]$$

where  $x_1, \ldots, x_n$  are the labels of the *n*-dimensional coordinate system.

Curves in 2- and 3-dimensional space will be of special interest:

A curve in dimension 2 is given by:

A curve in dimension 3 is given by:

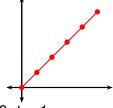
$$C: \begin{vmatrix} x &= f(t) \\ y &= g(t) \end{vmatrix}, t \in [a,b]$$
 .  $C: \begin{vmatrix} x &= f(t) \\ y &= g(t) \\ z &= h(t) \end{vmatrix}$  .

#### Consider the two parametric curves:

$$\gamma_1: \left| \begin{array}{ccc} x & = & t^2 \\ y & = & t^2 \end{array} \right., t \in [0, 1]$$

$$\gamma_2: \left| \begin{array}{ccc} x & = & t \\ y & = & t \end{array} \right., t \in [0,1]$$





Plug in t = 0, t = 0.2, t = 0.4, t = 0.6, t = 0.8, t = 1.

#### Question

Are the above curves different?

To answer this question we need a definition.

Recall a parametric curve C was defined as the data

$$C: \begin{vmatrix} x_1 & = & f_1(t) \\ x_2 & = & f_2(t) \\ \vdots & & , t \in [a, b] \\ x_n & = & f_n(t) \end{vmatrix}$$

#### **Definition**

A *curve image* (or simply a curve) is any set of points that arises by traversing some continuous curve. In other words, a curve image is any set that can be written in the form

$$\{(f_1(t),\ldots,f_n(t)) \mid t \in [a,b]\}$$
,

for some continuous functions  $f_1, \ldots, f_n$ .

Recall a parametric curve C was defined as the data

$$C: \begin{vmatrix} x_1 &=& f_1(t) \\ x_2 &=& f_2(t) \\ \vdots &&, t \in [a,b] \\ x_n &=& f_n(t) \end{vmatrix}$$

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If we don't require that the functions be continuous, every set of points will be a curve and the definition would be pointless.

Recall a parametric curve C was defined as the data

$$C: \begin{vmatrix} x_1 & = & f_1(t) \\ x_2 & = & f_2(t) \\ & \vdots & & , t \in [a, b] \\ x_n & = & f_n(t) \end{vmatrix}$$

#### Definition

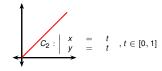
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$$\{(f_1(t),\ldots,f_n(t)) \mid t \in [a,b]\}$$
,

for some continuous functions  $f_1, \ldots, f_n$ .

Informally, a curve image "remembers" only the points lying on the curve but forgets the "speed" with which each point was visited and "how many times" each point was visited.

$$C_1: \left| \begin{array}{ccc} x & = & t^2 \\ y & = & t^2 \end{array} \right., t \in [0, 1]$$



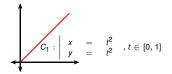
#### Question

Are the above curves different?

Are the above parametric curves different? Yes.

Are the above curve images different? No.

- As parametric curves,  $C_1$  and  $C_2$  are different:  $C_1$ ,  $C_2$  are given by different functions.
- As curve images,  $C_1$ ,  $C_2$  coincide.
- The original question is incorrectly posed: the word "curve" does not have a mathematical definition without the words "parametric" or "image" attached to it.





#### Question

Are the above curves different?

Are the above parametric curves different? Yes.

Are the above curve images different? No.

- Nonetheless we sometimes use the word "curve" informally, without specifying "parametric curve" or "curve image".
- In this case, whether we mean "parametric curve" or "curve image" should be clear from the context. If not, we are using mathematical language incorrectly.

# Graphs of functions as curve images

Consider a graph of a function given by

$$y = f(x)$$

• Write x = t. Then y = f(x) = f(t), so we get the system

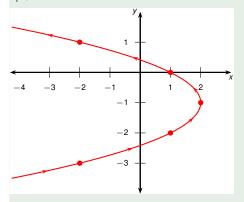
$$C: \left| \begin{array}{ccc} x & = & t \\ y & = & f(t) \end{array} \right|, t \in [a, b]$$

#### Observation

The graph of an arbitrary function can be written as the image of a curve C using the above transformation.

Sketch and identify the curve image defined by the equations

$$\begin{array}{rcl} x & = & -t^2 + 2 \\ y & = & t - 1 \end{array}$$



t	X	У
<b>-2</b>	- 2	<b>– 3</b>
<b>– 1</b>	1	<b>– 2</b>
0	2	<b>– 1</b>
1	1	0
2	-2	1

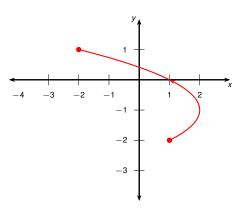
Eliminate t: from second equation we have t = y + 1 and therefore:

$$x = -t^{2} + 2$$

$$= -(y+1)^{2} + 2$$

$$= -v^{2} - 2v + 1$$

Thus our curve image is a parabola, as expected.



$$\begin{vmatrix} x & = -t^2 + 2 \\ y & = t - 1 \end{vmatrix}$$
,  $-1 \le t \le 2$ 

- There was no restriction placed on t in the last example.
- In such a case we assume  $t \in (-\infty, \infty)$ , i.e., t runs over all real numbers.
- In general we are expected to specify the interval in which t lies.
- For example, if we restrict the previous example to
   t∈ [-1,2], we get the part of the parabola that begins at (1,-2) and ends at (-2,1).
- We say that (1, -2) is the initial point and (-2, 1) is the terminal point of the curve.

Spring 2015

# Implicit vs Explicit (Parametric) Curve Equations

Consider the parametric curve

$$\begin{vmatrix} x & = -t^2 + 2 \\ y & = t - 1 \end{vmatrix}.$$

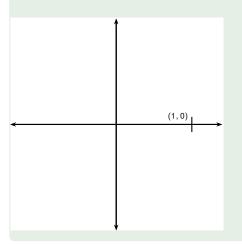
 As we saw in preceding slides/lectures, all points (x, y) on the image of this curve satisfy the equation

$$x + (y + 1)^2 - 2 = 0$$

- Equations of the first form are called explicit (parametric) curve equations.
- Equations of the second form are called implicit equations of the curve image.
- Explicit (parametric) curve equations have the advantage that it is easy to generate points on the curve.
- Implicit curve equations have the advantage that it is easy to check whether a point is on the curve.

Sketch and identify the curve defined by the parametric equations

$$x = \cos t$$
,  $y = \sin t$ .

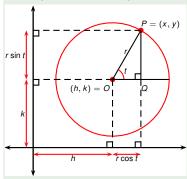


t	X	У
0	1	0
π 6 π 3 π 2 π	$\frac{\sqrt{3}}{2}$	$\frac{1}{2}$
$\pi$	1	$\sqrt{\frac{2}{3}}$
3	$\frac{1}{2}$	2
$\frac{\pi}{2}$	0	1
	<u> </u>	0
$\frac{3\pi}{2}$ $2\pi$	0	<b>– 1</b>
$2\pi$	1	0

$$x^2 + y^2 = \cos^2 t + \sin^2 t = 1$$

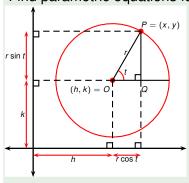
Therefore (x, y) travels on the unit circle  $x^2 + y^2 = 1$ .

Find parametric equations for the circle with center (h, k) and radius r.



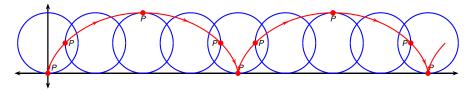
- Let O be the center of the circle with coordinates (h, k).
- Let P be a point on the circle with coordinates (x, y).
- Let t, Q be as indicated on the figure.
- Then  $|OQ| = r \cos t$ .
- $|PQ| = r \sin t$ .
- Then the coordinates of P are  $(h + r \cos t, k + r \sin t)$ .
- In this way we get the parametric equations  $\begin{vmatrix} x = h + r \cos t \\ y = k + r \sin t \end{vmatrix}$ ,  $t \in [0, 2\pi]$

Find parametric equations for the circle with center (h, k) and radius r.



- Alternative solution: x = cos t, y = sin t are parametric equations of the unit circle.
- Multiply by r to scale the circle to have radius r:  $x = r \cos t$ ,  $y = r \sin t$ .
- Add h to x and k to y to translate the circle h units to the left and k units up:
   x = h + r cos t, y = k + r sin t

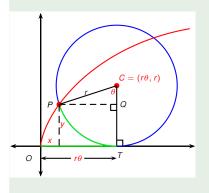
# The Cycloid



## **Definition (Cycloid)**

The curve traced out by a point P on the circumference of a circle as the circle rolls along a straight line is called a cycloid.

Find parametric equations of a cycloid made using a circle with radius r that rolls along the x-axis such that P hits the origin.



Therefore the equations are  $x = r(\theta - \sin \theta)$ ,

- We choose our parameter to be  $\theta$ , the angle of rotation of the circle.
- How far has the circle moved if it has rolled through  $\theta$  radians?

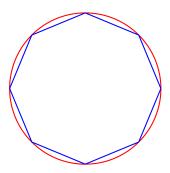
$$|OT| = \operatorname{arc}PT = r\theta$$

- Then the center is  $C = (r\theta, r)$ .
- Let the coordinates of P be (x, y).

$$x = |OT| - |PQ| = r\theta - r\sin\theta$$
  
 $y = |CT| - |CQ| = r - r\cos\theta$ 

$$y = r(1 - \cos \theta), \quad \theta \in \mathbb{R}$$

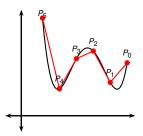
## Arc Length



- What do we mean by the length of a curve?
- The length of a polygon is easy to compute: add up the length of the line segments that form the polygon.
- If the curve is a circle, approximate it by a polygon.
- Then take the limit as the number of segments of the polygon goes to  $\infty$ .

Let 
$$\gamma$$
 be the curve  $\gamma$ :  $\begin{vmatrix} x = x(t) \\ y = y(t) \end{vmatrix}$ ,  $t \in [a, b]$ 

- Divide [a, b] into n subintervals with endpoints  $t_0, t_1, \ldots, t_n$  and equal width  $\Delta t$ .
- The points  $P_i = (x(t_i), y(t_i))$  lie on the curve  $\gamma$ . The lengths of the segments with endpoints with consecutive indices from  $P_0, P_1, \ldots, P_n$  approximate the length of the curve  $\gamma$ .
- The length *L* of the curve  $\gamma$  is the limit of the lengths of these segments as  $n \to \infty$ .



$$L = \lim_{n \to \infty} \sum_{i=1}^{n} |P_{i-1}P_i|$$

Let 
$$\gamma$$
 be the curve  $\gamma$ :  $\begin{vmatrix} x = x(t) \\ y = y(t) \end{vmatrix}$ ,  $t \in [a, b]$ 

$$L = \lim_{n \to \infty} \sum_{i=1}^{n} |P_{i-1}P_i| = \lim_{n \to \infty} \sum_{i=1}^{n} \sqrt{(x'(s_i))^2 + (y'(r_i))^2} \, \Delta t$$
$$= \int_{a}^{b} \sqrt{(x'(t))^2 + (y'(t))^2} \, dt$$

If f has continuous derivative, we can compute the above limit.

• Let 
$$\begin{vmatrix} x_i = x(t_i) \\ y_i = y(t_i) \end{vmatrix}$$
, and  $\begin{vmatrix} \Delta x = x_i - x_{i-1} = x(t_i) - x(t_{i-1}) \\ \Delta y = y_i - y_{i-1} = y(t_i) - y(t_{i-1}) \end{vmatrix}$ .

- Then  $|P_i P_{i-1}| = \sqrt{(\Delta x)^2 + (\Delta y)^2}$ .
- Mean Value Theorem: there exist numbers  $s_i$  and  $r_i$  between  $t_{i-1}$  and  $t_i$  such that  $x(t_i) x(t_{i-1}) = x'(s_i)(t_i t_{i-1})$  and  $y(t_i) y(t_{i-1}) = y'(r_i)(t_i t_{i-1})$ .
- $\Delta x = x'(s_i) \Delta t, \, \Delta y = y'(r_i) \Delta t.$

$$|P_{i-1}P_i| = \sqrt{(\Delta x)^2 + (\Delta y)^2} = \sqrt{(x'(s_i)\Delta t)^2 + (y'(r_i)\Delta t)^2} = \sqrt{(x'(s_i))^2 + (y'(r_i))^2} \sqrt{(\Delta t)^2} = \sqrt{(x'(s_i))^2 + (y'(r_i))^2} \Delta t$$

# The Arc Length Formula

Let 
$$\gamma: \left| \begin{array}{ccc} x & = & x(t) \\ y & = & y(t) \end{array} \right|, t \in [a, b].$$

#### **Definition**

Suppose x'(t) and y'(t) (exist and) are continuous on [a,b]. Then the length of the curve  $\gamma$  is defined as

$$L(\gamma) = \int_{a}^{b} \sqrt{(x'(t))^{2} + (y'(t))^{2}} dt$$

$$= \int_{a}^{b} \sqrt{\left(\frac{dx}{dt}\right)^{2} + \left(\frac{dy}{dt}\right)^{2}} dt \quad \text{in Leibniz notation }.$$

## Arc length of graph of a function

#### Question

What is the length of the graph of the curve given by the graph of y = f(x)?

• The graph of y = f(x) is written as a curve as

$$\gamma: \left| \begin{array}{ccc} x & = & t \\ y & = & f(t) \end{array} \right|, t \in [a, b] .$$

• In other words, the question asks what is the length  $L(\gamma)$  of  $\gamma$ . That is a straightforward computation:

$$L(\gamma) = \int \sqrt{(x'(t))^2 + (y'(t))^2} dt = \int \sqrt{1 + (f'(t))^2} dt$$

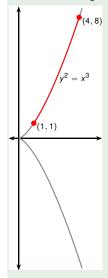
# The Arc Length Formula

#### Definition

Suppose f' exists and is continuous on [a, b]. Then the length of the curve y = f(x),  $a \le x \le b$ , is

$$L = \int_{a}^{b} \sqrt{1 + (f'(x))^2} \, dx$$
$$= \int_{a}^{b} \sqrt{1 + \left(\frac{dy}{dx}\right)^2} \, dx \quad \text{(in Leibniz notation)} .$$

Find the length of the arc of  $y^2 = x^3$  between (1, 1) and (4, 8).



• 
$$y = x^{3/2}$$
 and  $y' = \frac{3}{2}x^{1/2}$ .

• 
$$u = 1 + \frac{9}{4}x$$
 and  $du = \frac{9}{4}dx$ .

• When 
$$x = 1$$
,  $u = \frac{13}{4}$ .

• When 
$$x = 4$$
,  $u = 10$ .

$$L = \int_{1}^{4} \sqrt{1 + (y')^{2}} dx$$

$$= \int_{1}^{4} \sqrt{1 + \frac{9}{4}x} dx = \int_{13/4}^{10} \frac{4}{9} \sqrt{u} du$$

$$= \frac{4}{9} \left[ \frac{2}{3} u^{3/2} \right]_{13/4}^{10} = \frac{8}{27} \left( 10^{3/2} - \left( \frac{13}{4} \right)^{3/2} \right)$$

If a curve has equation x = g(y),  $c \le y \le d$ , and g'(y) is continuous, then we can get the length of the curve by interchanging the roles of x and y in the arc length formula:

$$L = \int_c^d \sqrt{1 + (g'(y))^2} \, \mathrm{d}y = \int_c^d \sqrt{1 + \left(\frac{\mathrm{d}x}{\mathrm{d}y}\right)^2} \, \mathrm{d}y$$

Find the length of the arc of  $x = y^2$  from (0,0) to (1,1).

- $x = y^2$ , so dx/dy = 2y.
- Substitute  $y = \frac{1}{2} \tan \theta$ , so  $dy = \frac{1}{2} \sec^2 \theta d\theta$ , and  $\sqrt{1 + 4y^2} = \sec \theta$ .
- When y = 0,  $\tan \theta = 0$ , so  $\theta = 0$ .
- When y = 1,  $\tan \theta = 2$ , so  $\theta = \arctan(2)$  (call this  $\alpha$ ).

$$L = \int_0^1 \sqrt{1 + (dx/dy)^2} \, dy = \int_0^1 \sqrt{1 + 4y^2} \, dy$$

$$= \int_0^\alpha \sec \theta \cdot \frac{1}{2} \sec^2 \theta \, d\theta = \frac{1}{2} \int_0^\alpha \sec^3 \theta \, d\theta$$

$$= \frac{1}{2} \cdot \frac{1}{2} [\sec \theta \tan \theta + \ln|\sec \theta + \tan \theta|]_0^\alpha$$

$$= \frac{1}{4} (\sec \alpha \tan \alpha + \ln|\sec \alpha + \tan \alpha|)$$

$$= \frac{1}{4} \left( 2\sqrt{5} + \ln|\sqrt{5} + 2| \right)$$

## Example $((a+b)^2, (a-b)^2, 2ab = 1/2)$



Find the length of the arc of  $y = \frac{1}{6}e^{3x} + \frac{1}{6}e^{-3x}$  from x = 0 to x = 1.

$$y' = \frac{1}{2}e^{3x} - \frac{1}{2}e^{-3x}.$$

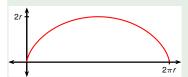
$$(y')^2 = \frac{1}{4}e^{6x} - \frac{1}{4}e^{3x}e^{-3x} - \frac{1}{4}e^{3x}e^{-3x} + \frac{1}{4}e^{-6x}$$

$$= \frac{1}{4}e^{6x} - \frac{1}{2} + \frac{1}{4}e^{-6x}.$$

$$L = \int_0^1 \sqrt{1 + (y')^2} dx = \int_0^1 \sqrt{1 + \frac{1}{4}e^{6x} - \frac{1}{2} + \frac{1}{4}e^{-6x}} dx$$

$$= \int_0^1 \sqrt{\frac{1}{4}e^{6x} + \frac{1}{2} + \frac{1}{4}e^{-6x}} dx = \int_0^1 \sqrt{\left(\frac{1}{2}e^{3x} + \frac{1}{2}e^{-3x}\right)^2} dx$$

$$= \int_0^1 \left(\frac{1}{2}e^{3x} + \frac{1}{2}e^{-3x}\right) dx = \left[\frac{1}{6}e^{3x} - \frac{1}{6}e^{-3x}\right]_0^1 = \frac{e^3 - e^{-3}}{6}.$$



Find the length of one arch of the cycloid

$$x = r(\theta - \sin \theta), \quad y = r(1 - \cos \theta).$$

The first arch is  $0 \le \theta \le 2\pi$ .

$$L = \int_0^{2\pi} \sqrt{\left(\frac{dx}{d\theta}\right)^2 + \left(\frac{dy}{d\theta}\right)^2} d\theta = \int_0^{2\pi} \sqrt{(r(1-\cos\theta))^2 + (r\sin\theta)^2} d\theta$$
$$= \int_0^{2\pi} \sqrt{r^2(1-2\cos\theta + \cos^2\theta + \sin^2\theta)} d\theta = r \int_0^{2\pi} \sqrt{2(1-\cos\theta)} d\theta$$

Use the identity 
$$\sin^2 x = \frac{1}{2}(1 - \cos 2x)$$
. Then

$$\sqrt{2(1-\cos\theta)} = \sqrt{4\sin^2(\theta/2)} = 2|\sin(\theta/2)| = 2\sin(\theta/2)$$

$$L = r \int_0^{2\pi} 2\sin(\theta/2) d\theta = r [-4\cos(\theta/2)]_0^{2\pi} = 8r$$