

Math 141

Lecture 17

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Outline

- 1 Modeling with Differential Equations
 - Models of Population Growth
 - A Model for the Motion of a Spring
 - General Differential Equations

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 - Orthogonal Trajectories
 - Mixing Problems

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 - Orthogonal Trajectories
 - Mixing Problems
- 4 Models for Population Growth
 - The Law of Natural Growth
 - The Logistic Model

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Modeling with Differential Equations

- When modeling real-world problems, we often have a relationship between an unknown function and some of its derivatives.
- Such a relationship is called a differential equation.
- It is not always possible to find an explicit solution to a differential equation, but sometimes a graphical or approximate answer can be good enough for applications.

Models of Population Growth

- One model for population growth assumes that the population grows at a rate proportional to its size.
- In other words, if a certain number of bacteria produce a certain number of offspring in a certain time, then ten times that many bacteria produce ten times that many offspring in the same time.
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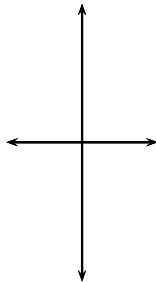
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- The rate of growth is dP/dt .
- Then “rate of growth proportional to population size” means

$$\frac{dP}{dt} = kP$$

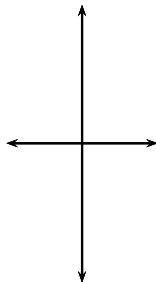
where k is the proportionality constant.

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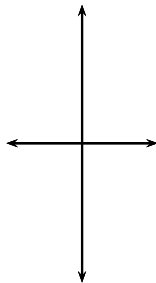
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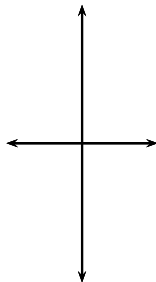
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- Let $P(t) = Ce^{kt}$ (C is a constant). Then

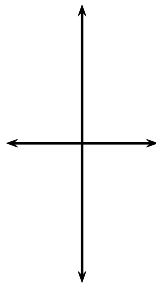
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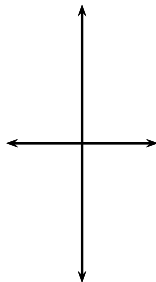
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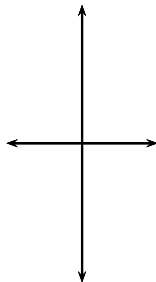
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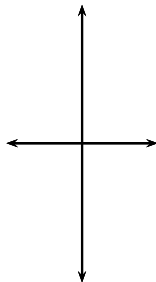
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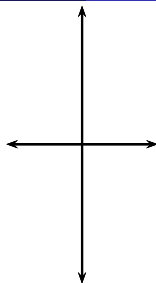
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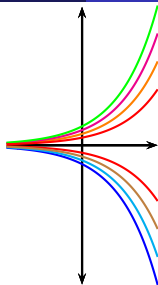


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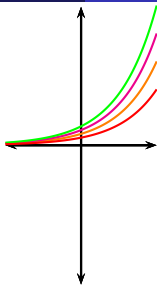


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- Therefore any function of the form $P(t) = Ce^{kt}$ satisfies the equation. We will see later that there is no other solution.
- Letting C vary over the real numbers gives a family of solutions.
- Since populations are non-negative, only solutions with $C > 0$ are relevant.

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- To take this into account, make two assumptions:
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- Here is an expression that takes both assumptions into account:

$$\frac{dP}{dt} = kP \left(1 - \frac{P}{K} \right)$$

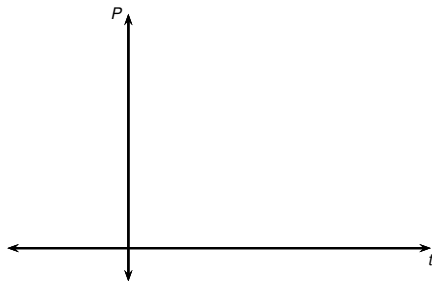
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- This is called the logistic differential equation.

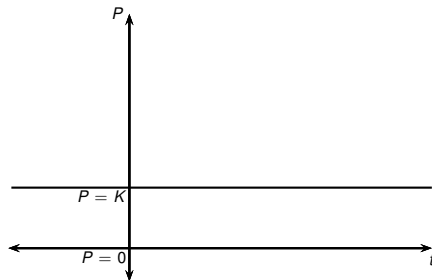
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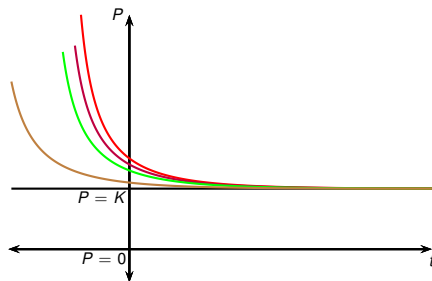
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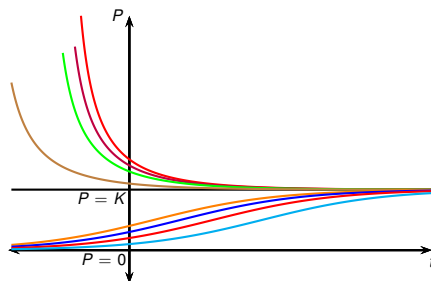
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- If $P > K$, then $1 - P/K < 0$, so $dP/dt < 0$, and P decreases.



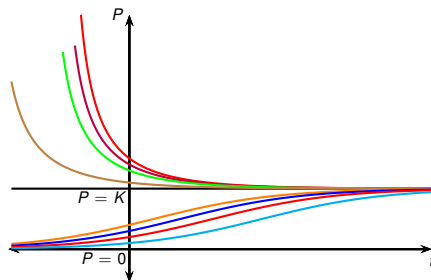
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- As $P \rightarrow K$, $1 - P/K \rightarrow 0$, so $dP/dt \rightarrow 0$ and P levels off.



A Model for the Motion of a Spring

- Suppose we have an object with mass m attached to a spring.
- Hooke's Law: if the spring is stretched or compressed x units from its natural length, then it exerts a force that is proportional to x .
- Force equals mass times acceleration.
- Acceleration is the second derivative of displacement with respect to time.

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- Sine and cosine functions are solutions.

General Differential Equations

Definition (Differential Equation)

A differential equation is an equation that contains an unknown function and some of its derivatives.

Definition (Order of a Differential Equation)

The order of a differential equation is the highest derivative that appears in it.

Definition (Solution)

A function f is called a solution of a differential equation if the equation is satisfied when f and its derivatives are plugged in.

Definition (To Solve a Differential Equation)

When we are asked to solve a differential equation we are expected to find all possible solutions.

Example

Show that every member of the family of functions

$$y = \frac{1 + ce^t}{1 - ce^t}$$

is a solution of the differential equation $y' = \frac{1}{2}(y^2 - 1)$.

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- Often we don't want to find all solutions (the general solution).
- Instead, we only want to find a single solution that satisfies some additional requirement.
- Often that requirement has the form $y(t_0) = y_0$.
- This is called an initial condition.
- This type of problem is called an initial value problem.

Example

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from Example 1.

$$\begin{aligned} 2 &= \frac{1 + ce^0}{1 - ce^0} = \frac{1 + c}{1 - c} \\ 2(1 - c) &= 1 + c \\ 2 - 2c &= 1 + c \\ c &= 1/3 \end{aligned}$$

Therefore the solution to the initial-value problem is

$$y = \frac{1 + \frac{1}{3}e^t}{1 - \frac{1}{3}e^t} = \frac{3 + e^t}{3 - e^t}.$$

Direction Fields and Euler's Method

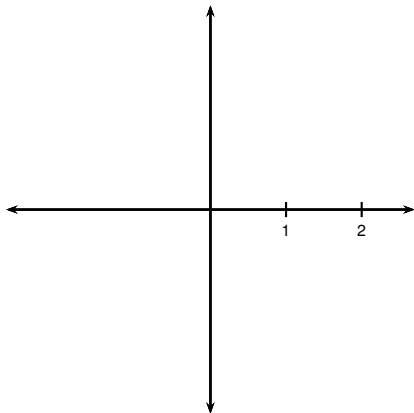
- Often we don't know how to find explicit solutions to a differential equation.
- Nevertheless, we can learn a lot about the solutions using:
 - A graphical approach (direction fields)
 - A numerical approach (Euler's method)

Direction Fields and Euler's Method

- Often we don't know how to find explicit solutions to a differential equation.
- Nevertheless, we can learn a lot about the solutions using:
 - A graphical approach (direction fields)
 - A numerical approach (Euler's method)
- Today we will discuss direction fields, but not Euler's method.

Direction Fields

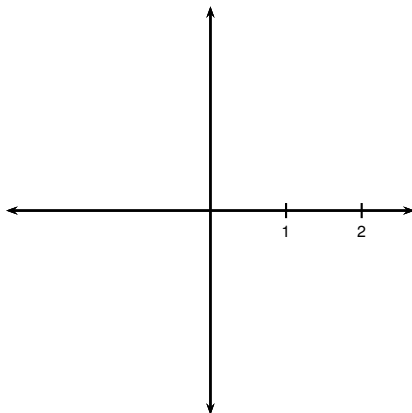
- How do we sketch the graph of the solution to $y' = x + y$ that satisfies the initial condition $y(0) = 1$?



Direction Fields

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- Make a table of values of y' .

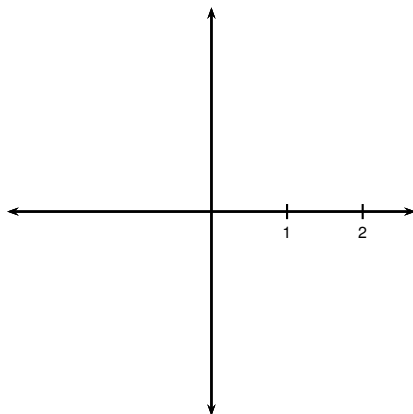
Point	y'
$(1, 0)$	
$(-1, 0)$	
$(0, 1)$	
$(0, -1)$	
$(0, 0)$	
$(1, 1)$	
$(1, -1)$	
$(-1, 1)$	
$(-1, -1)$	



Direction Fields

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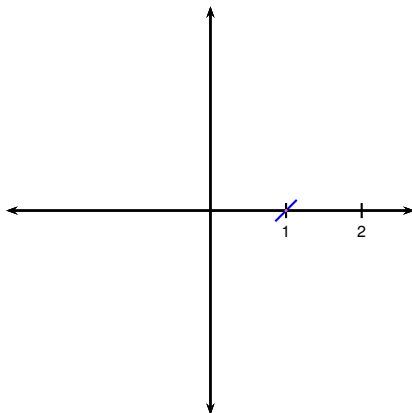
Point	y'
(1, 0)	
(-1, 0)	
(0, 1)	
(0, -1)	
(0, 0)	
(1, 1)	
(1, -1)	
(-1, 1)	
(-1, -1)	



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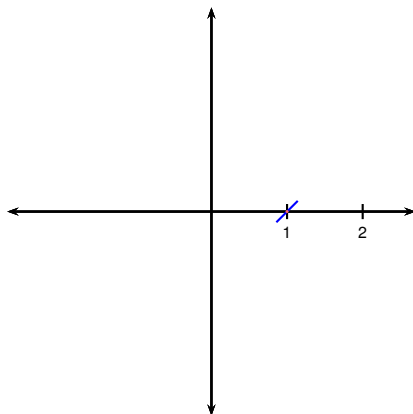
Point	y'
(1, 0)	1
(-1, 0)	
(0, 1)	
(0, -1)	
(0, 0)	
(1, 1)	
(1, -1)	
(-1, 1)	
(-1, -1)	



Direction Fields

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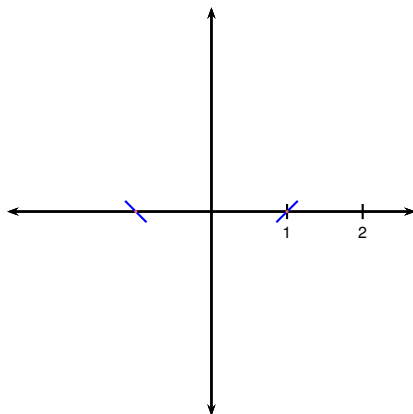
Point	y'
$(1, 0)$	1
$(-1, 0)$	
$(0, 1)$	
$(0, -1)$	
$(0, 0)$	
$(1, 1)$	
$(1, -1)$	
$(-1, 1)$	
$(-1, -1)$	



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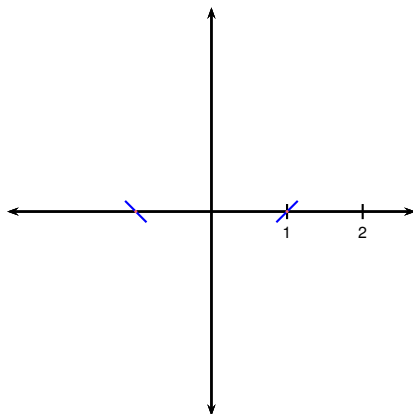
Point	y'
$(1, 0)$	1
$(-1, 0)$	-1
$(0, 1)$	
$(0, -1)$	
$(0, 0)$	
$(1, 1)$	
$(1, -1)$	
$(-1, 1)$	
$(-1, -1)$	



Direction Fields

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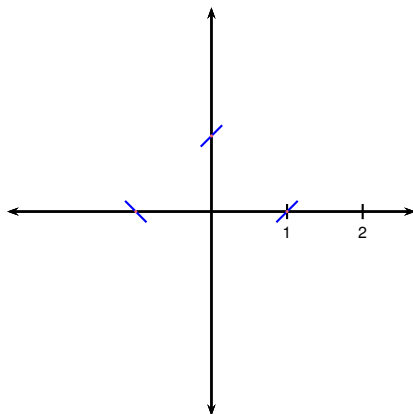
Point	y'
$(1, 0)$	1
$(-1, 0)$	-1
$(0, 1)$	
$(0, -1)$	
$(0, 0)$	
$(1, 1)$	
$(1, -1)$	
$(-1, 1)$	
$(-1, -1)$	



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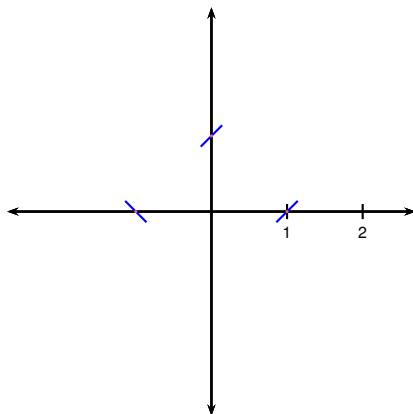
Point	y'
$(1, 0)$	1
$(-1, 0)$	-1
$(0, 1)$	1
$(0, -1)$	
$(0, 0)$	
$(1, 1)$	
$(1, -1)$	
$(-1, 1)$	
$(-1, -1)$	



Direction Fields

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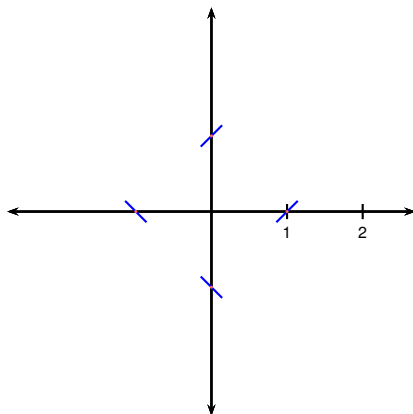
Point	y'
$(1, 0)$	1
$(-1, 0)$	-1
$(0, 1)$	1
$(0, -1)$	-1
$(0, 0)$	0
$(1, 1)$	2
$(1, -1)$	0
$(-1, 1)$	0
$(-1, -1)$	-2



Direction Fields

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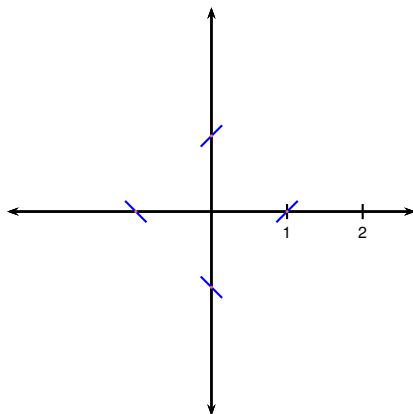
Point	y'
$(1, 0)$	1
$(-1, 0)$	-1
$(0, 1)$	1
$(0, -1)$	-1
$(0, 0)$	
$(1, 1)$	
$(1, -1)$	
$(-1, 1)$	
$(-1, -1)$	



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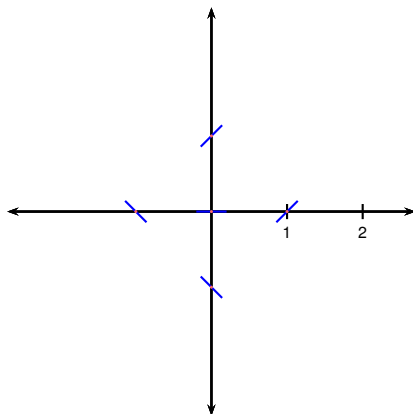
Point	y'
$(1, 0)$	1
$(-1, 0)$	-1
$(0, 1)$	1
$(0, -1)$	-1
$(0, 0)$	
$(1, 1)$	
$(1, -1)$	
$(-1, 1)$	
$(-1, -1)$	



Direction Fields

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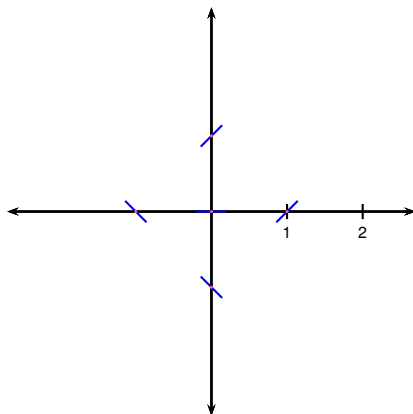
Point	y'
$(1, 0)$	1
$(-1, 0)$	-1
$(0, 1)$	1
$(0, -1)$	-1
$(0, 0)$	0
$(1, 1)$	
$(1, -1)$	
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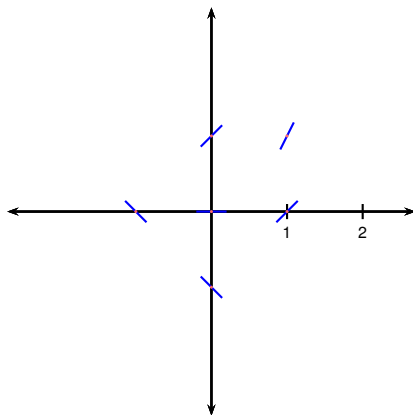
Point	y'
$(1, 0)$	1
$(-1, 0)$	-1
$(0, 1)$	1
$(0, -1)$	-1
$(0, 0)$	0
$(1, 1)$	
$(1, -1)$	
$(-1, 1)$	
$(-1, -1)$	



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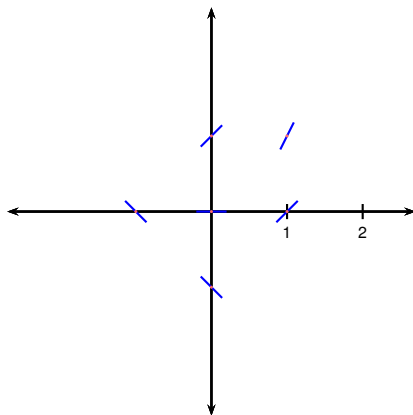
Point	y'
$(1, 0)$	1
$(-1, 0)$	-1
$(0, 1)$	1
$(0, -1)$	-1
$(0, 0)$	0
$(1, 1)$	2
$(1, -1)$	
$(-1, 1)$	
$(-1, -1)$	



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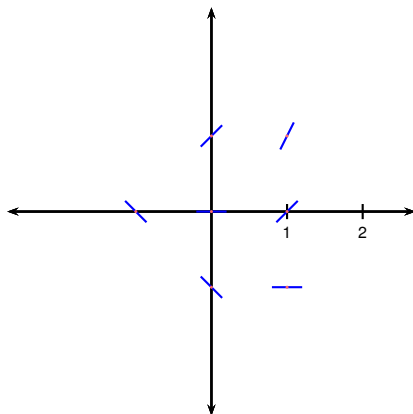
Point	y'
$(1, 0)$	1
$(-1, 0)$	-1
$(0, 1)$	1
$(0, -1)$	-1
$(0, 0)$	0
$(1, 1)$	2
$(1, -1)$	
$(-1, 1)$	
$(-1, -1)$	



Direction Fields

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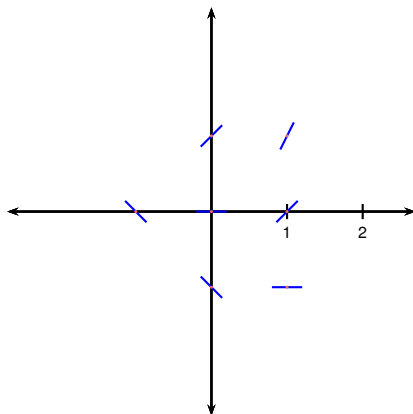
Point	y'
$(1, 0)$	1
$(-1, 0)$	-1
$(0, 1)$	1
$(0, -1)$	-1
$(0, 0)$	0
$(1, 1)$	2
$(1, -1)$	0
$(-1, 1)$	
$(-1, -1)$	



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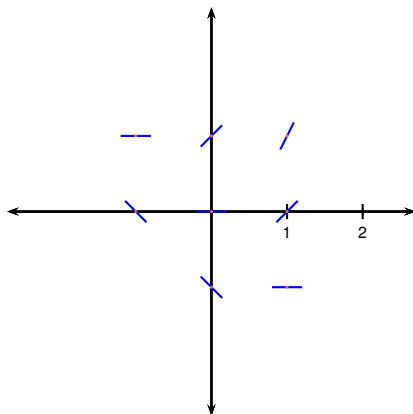
Point	y'
$(1, 0)$	1
$(-1, 0)$	-1
$(0, 1)$	1
$(0, -1)$	-1
$(0, 0)$	0
$(1, 1)$	2
$(1, -1)$	0
$(-1, 1)$	
$(-1, -1)$	



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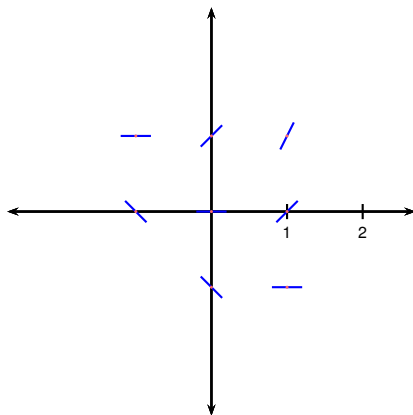
Point	y'
$(1, 0)$	1
$(-1, 0)$	-1
$(0, 1)$	1
$(0, -1)$	-1
$(0, 0)$	0
$(1, 1)$	2
$(1, -1)$	0
$(-1, 1)$	0
$(-1, -1)$	0



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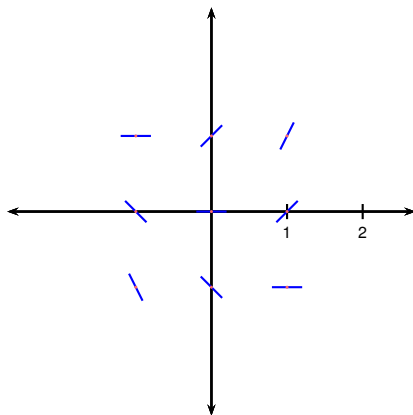
Point	y'
$(1, 0)$	1
$(-1, 0)$	-1
$(0, 1)$	1
$(0, -1)$	-1
$(0, 0)$	0
$(1, 1)$	2
$(1, -1)$	0
$(-1, 1)$	0
$(-1, -1)$	0



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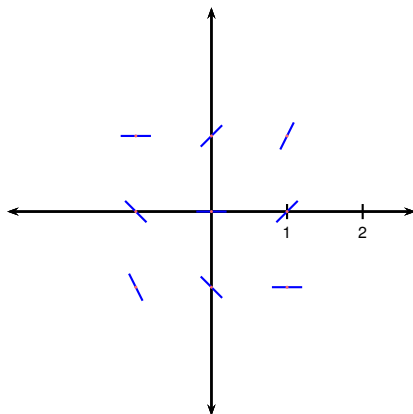
Point	y'
$(1, 0)$	1
$(-1, 0)$	-1
$(0, 1)$	1
$(0, -1)$	-1
$(0, 0)$	0
$(1, 1)$	2
$(1, -1)$	0
$(-1, 1)$	0
$(-1, -1)$	-2



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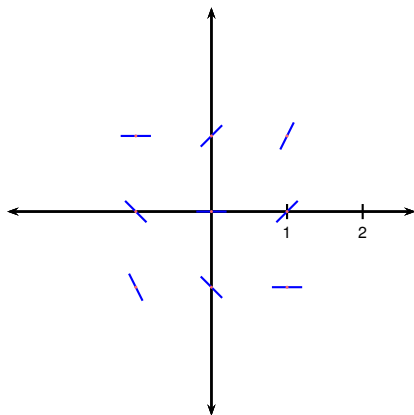
Point	y'
$(1, 0)$	1
$(-1, 0)$	-1
$(0, 1)$	1
$(0, -1)$	-1
$(0, 0)$	0
$(1, 1)$	2
$(1, -1)$	0
$(-1, 1)$	0
$(-1, -1)$	-2



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Point	y'
$(1, 0)$	1
$(-1, 0)$	-1
$(0, 1)$	1
$(0, -1)$	-1
$(0, 0)$	0
$(1, 1)$	2
$(1, -1)$	0
$(-1, 1)$	0
$(-1, -1)$	-2

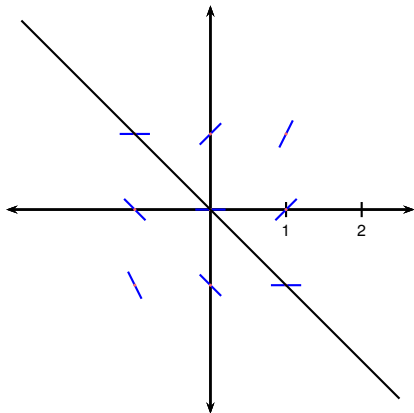


Line	y'
$y = -x$	
$y = -x + \frac{1}{2}$	
$y = -x + 1$	
$y = -x - \frac{1}{2}$	
$y = -x - 1$	

Direction Fields

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Point	y'
$(1, 0)$	1
$(-1, 0)$	-1
$(0, 1)$	1
$(0, -1)$	-1
$(0, 0)$	0
$(1, 1)$	2
$(1, -1)$	0
$(-1, 1)$	0
$(-1, -1)$	-2

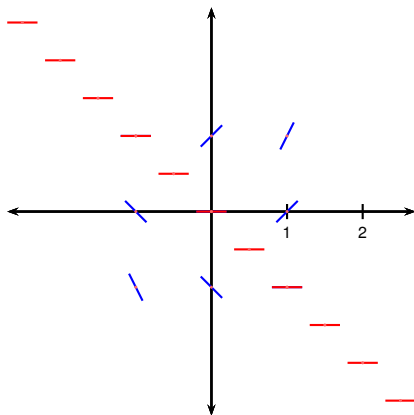


Line	y'
$y = -x$	
$y = -x + \frac{1}{2}$	
$y = -x + 1$	
$y = -x - \frac{1}{2}$	
$y = -x - 1$	

Direction Fields

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Point	y'
$(1, 0)$	1
$(-1, 0)$	-1
$(0, 1)$	1
$(0, -1)$	-1
$(0, 0)$	0
$(1, 1)$	2
$(1, -1)$	0
$(-1, 1)$	0
$(-1, -1)$	-2

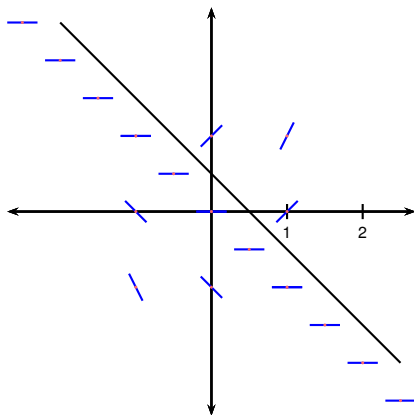


Line	y'
$y = -x$	0
$y = -x + \frac{1}{2}$	
$y = -x + 1$	
$y = -x - \frac{1}{2}$	
$y = -x - 1$	

Direction Fields

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Point	y'
$(1, 0)$	1
$(-1, 0)$	-1
$(0, 1)$	1
$(0, -1)$	-1
$(0, 0)$	0
$(1, 1)$	2
$(1, -1)$	0
$(-1, 1)$	0
$(-1, -1)$	-2

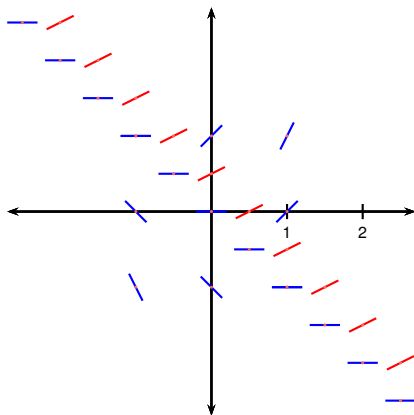


Line	y'
$y = -x$	0
$y = -x + \frac{1}{2}$	
$y = -x + 1$	
$y = -x - \frac{1}{2}$	
$y = -x - 1$	

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Point	y'
$(1, 0)$	1
$(-1, 0)$	-1
$(0, 1)$	1
$(0, -1)$	-1
$(0, 0)$	0
$(1, 1)$	2
$(1, -1)$	0
$(-1, 1)$	0
$(-1, -1)$	-2

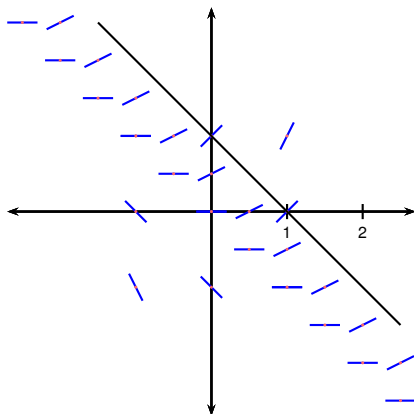


Line	y'
$y = -x$	0
$y = -x + \frac{1}{2}$	$\frac{1}{2}$
$y = -x + 1$	1
$y = -x + \frac{3}{2}$	$\frac{3}{2}$
$y = -x + 2$	2

Direction Fields

- How do we sketch the graph of the solution to $y' = x + y$ that satisfies the initial condition $y(0) = 1$?
- Make a table of values of y' .

Point	y'
(1, 0)	1
(-1, 0)	-1
(0, 1)	1
(0, -1)	-1
(0, 0)	0
(1, 1)	2
(1, -1)	0
(-1, 1)	0
(-1, -1)	-2

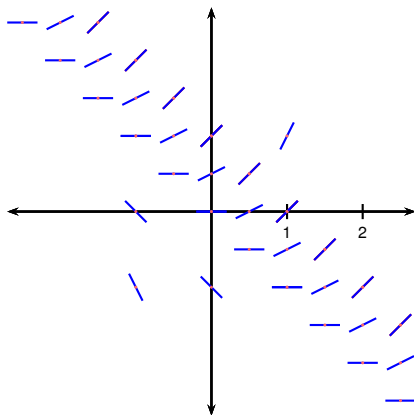


Line	y'
$y = -x$	0
$y = -x + \frac{1}{2}$	$\frac{1}{2}$
$y = -x + 1$	
$y = -x - \frac{1}{2}$	
$y = -x - 1$	

Direction Fields

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Point	y'
$(1, 0)$	1
$(-1, 0)$	-1
$(0, 1)$	1
$(0, -1)$	-1
$(0, 0)$	0
$(1, 1)$	2
$(1, -1)$	0
$(-1, 1)$	0
$(-1, -1)$	-2

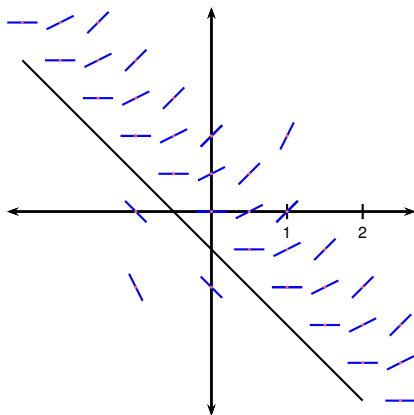


Line	y'
$y = -x$	0
$y = -x + \frac{1}{2}$	$\frac{1}{2}$
$y = -x + 1$	1
$y = -x - \frac{1}{2}$	$-\frac{1}{2}$
$y = -x - 1$	-1

Direction Fields

- How do we sketch the graph of the solution to $y' = x + y$ that satisfies the initial condition $y(0) = 1$?
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Point	y'
$(1, 0)$	1
$(-1, 0)$	-1
$(0, 1)$	1
$(0, -1)$	-1
$(0, 0)$	0
$(1, 1)$	2
$(1, -1)$	0
$(-1, 1)$	0
$(-1, -1)$	-2

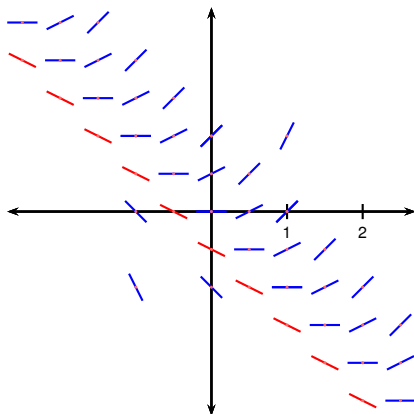


Line	y'
$y = -x$	0
$y = -x + \frac{1}{2}$	$\frac{1}{2}$
$y = -x + 1$	1
$y = -x - \frac{1}{2}$	
$y = -x - 1$	

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Point	y'
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$(-1, 0)$	-1
$(0, 1)$	1
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$(0, 0)$	0
$(1, 1)$	2
$(1, -1)$	0
$(-1, 1)$	0
$(-1, -1)$	-2

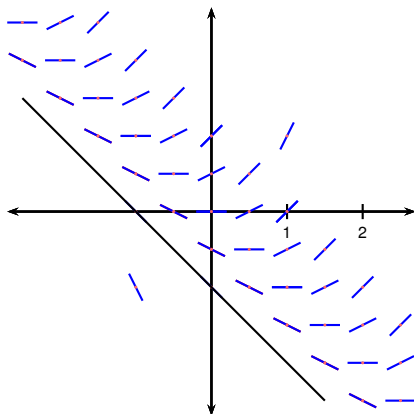


Line	y'
$y = -x$	0
$y = -x + \frac{1}{2}$	$\frac{1}{2}$
$y = -x + 1$	1
$y = -x - \frac{1}{2}$	$-\frac{1}{2}$
$y = -x - 1$	-1

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Point	y'
$(1, 0)$	1
$(-1, 0)$	-1
$(0, 1)$	1
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$(0, 0)$	0
$(1, 1)$	2
$(1, -1)$	0
$(-1, 1)$	0
$(-1, -1)$	-2

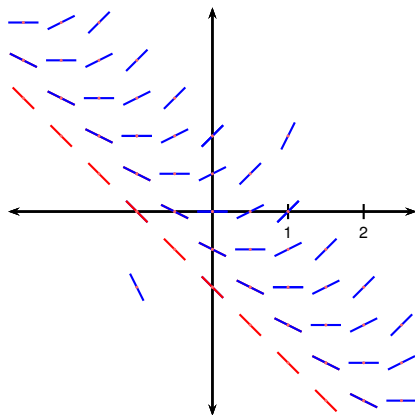


Line	y'
$y = -x$	0
$y = -x + \frac{1}{2}$	$\frac{1}{2}$
$y = -x + 1$	1
$y = -x - \frac{1}{2}$	$-\frac{1}{2}$
$y = -x - 1$	-1

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Point	y'
$(1, 0)$	1
$(-1, 0)$	-1
$(0, 1)$	1
$(0, -1)$	-1
$(0, 0)$	0
$(1, 1)$	2
$(1, -1)$	0
$(-1, 1)$	0
$(-1, -1)$	-2

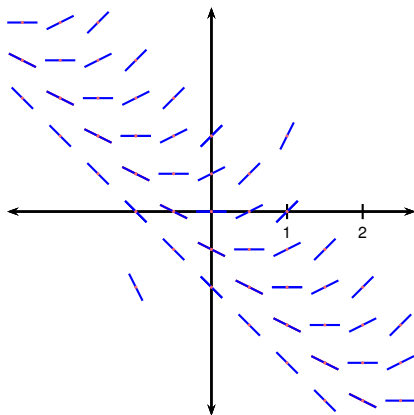


Line	y'
$y = -x$	0
$y = -x + \frac{1}{2}$	$\frac{1}{2}$
$y = -x + 1$	1
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Direction Fields

- How do we sketch the graph of the solution to $y' = x + y$ that satisfies the initial condition $y(0) = 1$?
- Make a table of values of y' .

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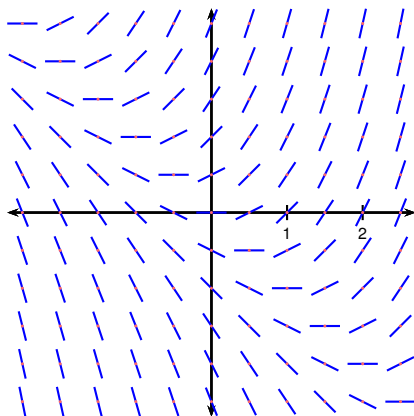


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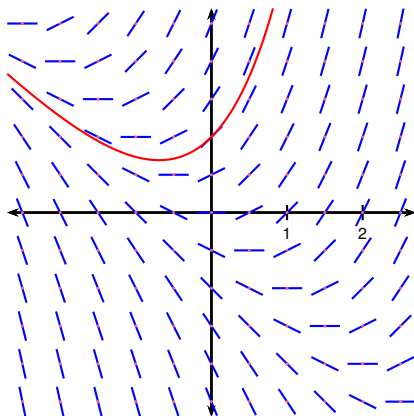


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Separable Equations

In this section, we will discuss a type of differential equation, called a separable equation, for which it is possible to find an explicit solution.

Definition (Separable Equation)

A separable equation is a first-order equation in which the expression for dy/dx can be factored as a function of x times a function of y . In other words,

$$\frac{dy}{dx} = g(x)f(y).$$

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$$\frac{dy}{dx} = g(x)f(y).$$

Let $f(y) = 1/h(y)$. Then

$$\frac{dy}{dx} = \frac{g(x)}{h(y)}.$$

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- This defines y implicitly as a function of x .
- Sometimes we might be able to solve explicitly for y in terms of x .

Why does this process yield a function that satisfies the original differential equation? Suppose that $\int h(y)dy = \int g(x)dx$. Then we will use the Chain Rule to show that y satisfies the original equation.

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Example

Solve the differential equation $\frac{dy}{dx} = \frac{x^2}{y^2}$, and find the solution that satisfies the initial condition $y(0) = 2$.

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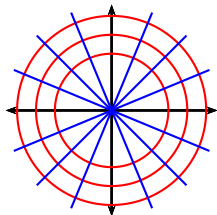
The function $y = 0$ satisfies the equation. General solution:

$$y = A e^{x^3/3}.$$

Orthogonal Trajectories

Definition (Orthogonal Trajectory)

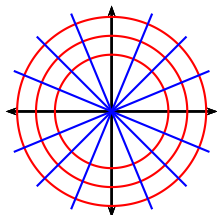
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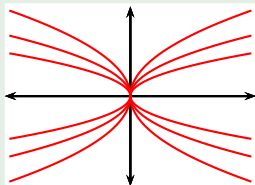
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Each member of the family $y = mx$ of straight lines passing through the origin is an orthogonal trajectory to the family $x^2 + y^2 = r^2$ of circles centered at the origin.

Example

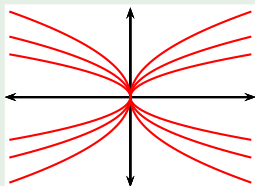
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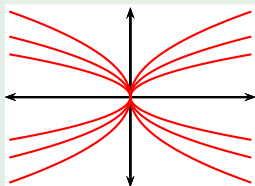


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Find the orthogonal trajectories of the family $x = ky^2$, where k is an arbitrary constant. **Differentiate implicitly:**

$$x = ky^2$$

$$1 = 2ky \frac{dy}{dx}$$



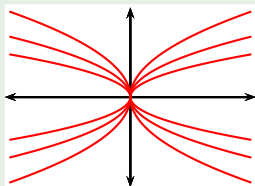
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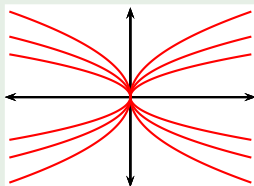
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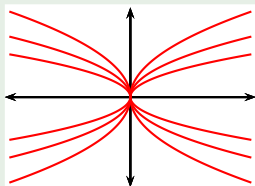
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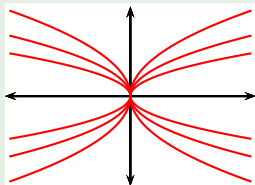
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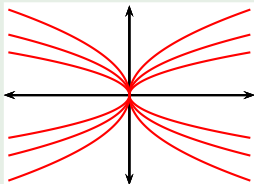
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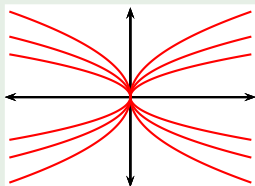
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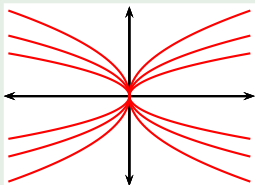
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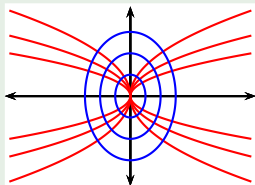
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The ellipses $x^2 + \frac{y^2}{2} = C$ are all orthogonal trajectories to $x = ky^2$.

Mixing Problems

- Typical mixing problems involve:
- A tank of fixed capacity.
- A completely mixed solution of some substance in the tank.
- A solution of a certain concentration enters the tank at a fixed rate.
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- The mixture leaves at the other end at a fixed rate (possibly a different rate).
- Let $y(t)$ denote the amount of substance in the tank at time t .
- Then $y'(t)$ denotes the rate at which the substance is being added minus the rate at which it is being removed.
- This often gives a differential equation.

Example

A tank contains 20 kg of salt dissolved in 5000 L of water. Brine that contains 0.03 kg of salt per liter of water enters the tank at a rate of 25 L/min. The solution is kept thoroughly mixed and drains from the tank at the same rate. How much salt is in the tank after half an hour?

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$$\text{rate in} = (\text{concentration in})(\text{rate of volume in})$$

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Example

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Example (Example 6, p. 621)

A tank contains 20 kg of salt dissolved in 5000 L of water. Brine that contains 0.03 kg of salt per liter of water enters the tank at a rate of 25 L/min. The solution is kept thoroughly mixed and drains from the tank at the same rate. How much salt is in the tank after half an hour?

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$$y(30) = 150 - 130e^{-30/200} \approx 38.1\text{kg}$$

The Law of Natural Growth

- Recall that differential equations could be used to model population growth.
- The Law of Natural Growth works in ideal cases, where populations are unconstrained by lack of food, or the environment.
- Let $P(t)$ be the population at time t .
- Then the Law of Natural Growth says:

$$\frac{dP}{dt} = kP$$

- The constant k is sometimes called the relative growth rate.

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$$P = \pm e^C e^{kt}$$

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$$P = \pm e^C e^{kt}$$

- Let $A = \pm e^C$. Then the solution is $P = Ae^{kt}$.

$$\frac{dP}{dt} = kP$$

This is a separable equation, so we can solve it.

$$\int \frac{dP}{P} = \int k dt$$

$$\ln |P| = kt + C$$

$$|P| = e^C e^{kt}$$

$$P = \pm e^C e^{kt}$$

- Let $A = \pm e^C$. Then the solution is $P = Ae^{kt}$.
- $A = \pm e^C$ can be any positive or negative number.

$$\frac{dP}{dt} = kP$$

This is a separable equation, so we can solve it.

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- Let $A = \pm e^C$. Then the solution is $P = Ae^{kt}$.
- $A = \pm e^C$ can be any positive or negative number.
- The function $P = 0$ is also a solution, so A can be any number.

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- $P(0) = Ae^{k \cdot 0} = A$.

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This is a separable equation, so we can solve it.

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The solution to the initial value problem

$$\begin{aligned}\frac{dP}{dt} &= kP, & P(0) &= P_0 \\ \text{is} && P(t) &= P_0 e^{kt}.\end{aligned}$$

The Logistic Model

- The Logistic Model works in cases when the population is constrained by its environment.
- Let $P(t)$ be the population at time t .
- Then the Logistic Equation is:

$$\frac{dP}{dt} = kP \left(1 - \frac{P}{K} \right)$$

- The constant K is called the carrying capacity. It represents how many individuals the environment can sustain in the long run.

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$$P = \frac{K}{1 + Ae^{-kt}}$$

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Plug in $P(0) = P_0$:

$$\frac{K - P_0}{P_0} = Ae^{-k \cdot 0} = A.$$

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$$K = P(1 + Ae^{-kt})$$

$$P = \frac{K}{1 + Ae^{-kt}}$$

The solution to the initial value problem

$$\frac{dP}{dt} = kP \left(1 - \frac{P}{K} \right), \quad P(0) = P_0$$

is

$$P = \frac{K}{1 + Ae^{-kt}}, \quad A = \frac{K - P_0}{P_0}.$$

Example

Write the solution of the initial value problem

$$\frac{dP}{dt} = 0.08P \left(1 - \frac{P}{1000} \right), \quad P(0) = 100$$

and use it to find when the population reaches 900.

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and use it to find when the population reaches 900.

$$P(t) = \frac{1000}{1 + Ae^{-0.08t}}, \quad A = \frac{1000 - 100}{100}$$

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