Math 141 Lecture 17

Greg Maloney

Todor Milev

University of Massachusetts Boston

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Outline

- Modeling with Differential Equations
 - Models of Population Growth
 - A Model for the Motion of a Spring
 - General Differential Equations
- Direction Fields and Euler's Method
 - Direction Fields
- Separable Equations
 - Orthogonal Trajectories
 - Mixing Problems
- Models for Population Growth
 - The Law of Natural Growth
 - The Logistic Model

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Modeling with Differential Equations

- When modeling real-world problems, we often have a relationship between an unknown function and some of its derivatives.
- Such a relationship is called a differential equation.
- It is not always possible to find an explicit solution to a differential equation, but sometimes a graphical or approximate answer can be good enough for applications.

Models of Population Growth

- One model for population growth assumes that the population grows at a rate proportional to its size.
- In other words, if a certain number of bacteria produce a certain number of offspring in a certain time, then ten times that many bacteria produce ten times that many offspring in the same time.
- This is plausible when the population has unlimited food and environment and no restrictions on its size.
- Name the variables:

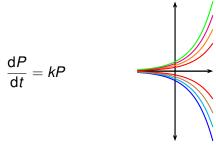
t = time

P = the number of individuals in the population

- The rate of growth is dP/dt.
- Then "rate of growth proportional to population size" means

$$\frac{\mathrm{d}P}{\mathrm{d}t}=kP$$

where k is the proportionality constant.



- This is a differential equation.
- Exponential functions satisfy this condition.
- Let $P(t) = Ce^{kt}$ (C is a constant). Then $\frac{dP}{dt} = \frac{d}{dt}(Ce^{kt}) = Cke^{kt} = kCe^{kt} = kP(t)$
- Therefore any function of the form $P(t) = Ce^{kt}$ satisfies the equation. We will see later that there is no other solution.
- Letting C vary over the real numbers gives a family of solutions.
- Since populations are non-negative, only solutions with C > 0 are relevant.

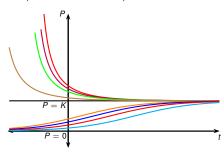
- This model works well under ideal conditions.
- In real life, most populations are constrained by the environment, the amount of food, etc.
- Many populations start by increasing exponentially, but then level off when they approach some upper bound, called the carrying capacity K.
- To take this into account, make two assumptions:
 - $\frac{dP}{dt} \approx kP$ if P is small (Initially, the growth rate is proportional to P). $\frac{dP}{dt} < 0$ if P > K (P decreases if it ever exceeds K).
- Here is an expression that takes both assumptions into account:

$$\frac{\mathrm{d}P}{\mathrm{d}t} = kP\left(1 - \frac{P}{K}\right)$$

This is called the logistic differential equation.

$$\frac{\mathrm{d}P}{\mathrm{d}t} = kP\left(1 - \frac{P}{K}\right)$$

- What do the solutions look like?
- P = 0 and P = K are special solutions, called equilibrium solutions.
- If P > K, then 1 P/K < 0, so dP/dt < 0, and P decreases.
- If P < K, then 1 P/K > 0, so dP/dt > 0, and P increases.
- As $P \to K$, $1 P/K \to 0$, so $dP/dt \to 0$ and P levels off.



A Model for the Motion of a Spring

- Suppose we have an object with mass m attached to a spring.
- Hooke's Law: if the spring is stretched or compressed x units from its natural length, then it exerts a force that is proportional to x.
- Force equals mass times acceleration.
- Acceleration is the second derivative of displacement with respect to time.

$$m\frac{\mathrm{d}^2x}{\mathrm{d}t^2} = -kx$$

- This is called a second-order differential equation because it involves second derivatives.
- Sine and cosine functions are solutions.

General Differential Equations

Definition (Differential Equation)

A differential equation is an equation that contains an unknown function and some of its derivatives.

Definition (Order of a Differential Equation)

The order of a differential equation is the highest derivative that appears in it.

Definition (Solution)

A function f is called a solution of a differential equation if the equation is satisfied when f and its derivatives are plugged in.

Definition (To Solve a Differential Equation)

When we are asked to solve a differential equation we are expected to find all possible solutions.

Show that every member of the family of functions

$$y = \frac{1 + ce^t}{1 - ce^t}$$

is a solution of the differential equation $y' = \frac{1}{2}(y^2 - 1)$.

LHS =
$$\frac{(1 - ce^t)(ce^t) - (1 + ce^t)(-ce^t)}{(1 - ce^t)^2}$$
$$= \frac{ce^t - c^2e^{2t} + ce^t + c^2e^{2t}}{(1 - ce^t)^2} = \frac{2ce^t}{(1 - ce^t)^2}$$

RHS =
$$\frac{1}{2} \left[\left(\frac{1 + ce^t}{1 - ce^t} \right)^2 - 1 \right] = \frac{1}{2} \left[\frac{(1 + ce^t)^2 - (1 - ce^t)^2}{(1 - ce^t)^2} \right]$$

= $\frac{1}{2} \left[\frac{1 + 2ce^t + c^2e^{2t} - 1 + 2ce^t - c^2e^{2t}}{(1 - ce^t)^2} \right]$
= $\frac{1}{2} \frac{4ce^t}{(1 - ce^t)^2} = \frac{2ce^t}{(1 - ce^t)^2} = \text{LHS}$

- Often we don't want to find all solutions (the general solution).
- Instead, we only want to find a single solution that satisfies some additional requirement.
- Often that requirement has the form $y(t_0) = y_0$.
- This is called an initial condition.
- This type of problem is called an initial value problem.

Find a solution of the differential equation $y' = \frac{1}{2}(y^2 - 1)$ that satisfies the initial condition y(0) = 2.

Substitute t = 0 and y = 2 into the formula

$$y = \frac{1 + ce^t}{1 - ce^t}$$

from Example 1.

$$2 = \frac{1 + ce^{0}}{1 - ce^{0}} = \frac{1 + c}{1 - c}$$

$$2(1 - c) = 1 + c$$

$$2 - 2c = 1 + c$$

$$c = 1/3$$

Therefore the solution to the initial-value problem is

$$y = \frac{1 + \frac{1}{3}e^t}{1 - \frac{1}{3}e^t} = \frac{3 + e^t}{3 - e^t}.$$

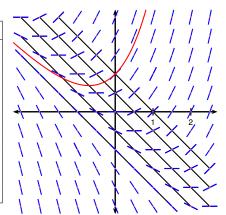
Direction Fields and Euler's Method

- Often we don't know how to find explicit solutions to a differential equation.
- Nevertheless, we can learn a lot about the solutions using:
 - A graphical approach (direction fields)
 - A numerical approach (Euler's method)
- Today we will discuss direction fields, but not Euler's method.

Direction Fields

- How do we sketch the graph of the solution to y' = x + y that satisfies the initial condition y(0) = 1?
- Make a table of values of y'.

Point	<i>y'</i>
(1,0)	1
(-1,0)	<u> </u>
(0,1)	1
(0,-1)	<u> </u>
(0,0)	0
(1,1)	2
(1,-1)	0
(-1,1)	0
(-1,-1)	– 2



Line	<i>y'</i>
y = -x	0
$y=-x+\tfrac{1}{2}$	$\frac{1}{2}$
y = -x + 1	1
$y=-x-\tfrac{1}{2}$	$-\frac{1}{2}$
$y = -x - \bar{1}$	$-\overline{1}$

Separable Equations

In this section, we will discuss a type of differential equation, called a separable equation, for which it is possible to find an explicit solution.

Definition (Separable Equation)

A separable equation is a first-order equation in which the expression for dy/dx can be factored as a function of x times a function of y. In other words.

$$\frac{\mathrm{d}y}{\mathrm{d}x} = g(x)f(y).$$

Let f(y) = 1/h(y). Then

$$\frac{\mathrm{d}y}{\mathrm{d}x} = \frac{g(x)}{h(y)}.$$

$$\frac{\mathrm{d}y}{\mathrm{d}x} = \frac{g(x)}{h(y)}$$

To solve, write this in differential form:

$$h(y)dy = g(x)dx$$

Now integrate:

$$\int h(y)\mathrm{d}y = \int g(x)\mathrm{d}x$$

- This defines y implicitly as a function of x.
- Sometimes we might be able to solve explicitly for y in terms of x.

Why does this process yield a function that satisfies the original differential equation? Suppose that $\int h(y) dy = \int g(x) dx$. Then we will use the Chain Rule to show that y satisfies the original equation.

$$\int h(y)dy = \int g(x)dx$$

$$\frac{d}{dx} \left(\int h(y)dy \right) = \frac{d}{dx} \left(\int g(x)dx \right)$$

$$\frac{d}{dy} \left(\int h(y)dy \right) \frac{dy}{dx} = \frac{d}{dx} \left(\int g(x)dx \right)$$

$$h(y)\frac{dy}{dx} = g(x)$$

$$\frac{dy}{dx} = \frac{g(x)}{h(y)}$$

Solve the differential equation $\frac{dy}{dx} = \frac{x^2}{y^2}$, and find the solution that satisfies the intial condition y(0) = 2.

$$y^{2}dy = x^{2}dx$$

$$\int y^{2}dy = \int x^{2}dx$$

$$\frac{y^{3}}{3} = \frac{x^{3}}{3} + C$$

$$y = \sqrt[3]{x^{3} + 3C}$$

$$y = \sqrt[3]{x^{3} + K}$$

To find the solution satisfying the initial condition, set $2 = y(0) = \sqrt[3]{0^3 + K} = \sqrt[3]{K}$. Then $\sqrt[3]{K} = 2$, so K = 8. $y = \sqrt[3]{x^3 + 8}$.

Solve the equation $y' = x^2y$.

$$\frac{dy}{dx} = x^2y$$

$$\frac{1}{y}dy = x^2dx \quad y \neq 0$$

$$\int \frac{1}{y}dy = \int x^2dx$$

$$\ln|y| = \frac{1}{3}x^3 + C$$

$$e^{\ln|y|} = e^{x^3/3 + C}$$

$$|y| = e^C e^{x^3/3}$$

$$y = \pm e^C e^{x^3/3}$$

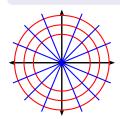
The function y = 0 satisfies the equation. General solution:

$$y = Ae^{x^3/3}$$

Orthogonal Trajectories

Definition (Orthogonal Trajectory)

An orthogonal trajectory to a family of curves is a curve that intersects each curve of the family orthogonally (that is, at right angles).



Each member of the family y = mx of straight lines passing through the origin is an orthogonal trajectory to the family $x^2 + y^2 = r^2$ of circles centered at the origin.

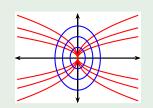
Find the orthogonal trajectories of the family $x = ky^2$, where k is an arbitrary constant. Differentiate implicitly:

$$x = ky^{2}$$

$$1 = 2ky\frac{dy}{dx}$$

$$1 = 2\left(\frac{x}{y^{2}}\right)y\frac{dy}{dx}$$

$$dy \qquad y$$



An orthogonal trajectory will have a slope that is the negative reciprocal of the slope of the curve.

$$\frac{dy}{dx} = -\frac{2x}{y}$$

$$\int y dy = -\int 2x dx$$

$$\frac{y^2}{2} = -x^2 + C$$

$$x^2 + \frac{y^2}{2} = C$$

The ellipses $x^2 + \frac{y^2}{2} = C$ are all orthogonal trajectories to $x = ky^2$.

Mixing Problems

- Typical mixing problems involve:
- A tank of fixed capacity.
- A completely mixed solution of some substance in the tank.
- A solution of a certain concentration enters the tank at a fixed rate.
- In the tank, the solution immediately becomes completely stirred.
- The mixture leaves at the other end at a fixed rate (possibly a different rate).
- Let y(t) denote the amount of substance in the tank at time t.
- Then y'(t) denotes the rate at which the substance is being added minus the rate at which it is being removed.
- This often gives a differential equation.

A tank contains 20 kg of salt dissolved in 5000 L of water. Brine that contains 0.03 kg of salt per liter of water enters the tank at a rate of 25 L/min. The solution is kept thoroughly mixed and drains from the tank at the same rate. How much salt is in the tank after half an hour?

- Let y(t) denote the amount of salt (in kg) after t minutes.
- Given: y(0) = 20. We want to know: y(30).

$$\frac{dy}{dt} = (\text{rate in}) - (\text{rate out}) = 0.75 - \frac{y(t)}{200} = \frac{150 - y(t)}{200}$$

$$\text{rate in} = (\text{concentration in})(\text{rate of volume in})$$

$$= \left(0.03 \frac{\text{kg}}{\text{L}}\right) \left(25 \frac{\text{L}}{\text{min}}\right) = 0.75 \frac{\text{kg}}{\text{min}}$$

$$\text{rate out} = (\text{concentration out})(\text{rate of volume out})$$

$$= \left(\frac{y(t)}{5000} \frac{\text{kg}}{\text{L}}\right) \left(25 \frac{\text{L}}{\text{min}}\right) = \frac{y(t)}{200} \frac{\text{kg}}{\text{min}}$$

Example (Example 6, p. 621)

A tank contains 20 kg of salt dissolved in 5000 L of water. Brine that contains 0.03 kg of salt per liter of water enters the tank at a rate of 25 L/min. The solution is kept thoroughly mixed and drains from the tank at the same rate. How much salt is in the tank after half an hour?

$$\frac{dy}{dt} = \frac{150 - y(t)}{200}$$

$$\int \frac{dy}{150 - y} = \int \frac{dt}{200}$$

$$-\ln|150 - y| = t/200 + C \quad y(0) = 20, \text{ so } C = -\ln 130$$

$$-\ln|150 - y| = t/200 - \ln 130$$

$$|150 - y| = 130e^{-t/200}$$

$$y < 150 = (0.03)(5000), \text{ so } |150 - y| = 150 - y$$

$$y = 150 - 130e^{-t/200}$$

$$y(30) = 150 - 130e^{-30/200} \approx 38.1 \text{kg}$$

The Law of Natural Growth

- Recall that differential equations could be used to model population growth.
- The Law of Natural Growth works in ideal cases, where populations are unconstrained by lack of food, or the environment.
- Let P(t) be the population at time t.
- Then the Law of Natural Growth says:

$$\frac{\mathrm{d}P}{\mathrm{d}t}=kP$$

• The constant *k* is sometimes called the relative growth rate.

$$\frac{\mathrm{d}P}{\mathrm{d}t}=kP$$

This is a separable equation, so we can solve it.

$$\int \frac{dP}{P} = \int kdt$$

$$\ln |P| = kt + C$$

$$|P| = e^{C}e^{kt}$$

$$P = \pm e^{C}e^{kt}$$

- Let $A = \pm e^C$. Then the solution is $P = Ae^{kt}$.
- $A = \pm e^C$ can be any positive or negative number.
- The function P = 0 is also a solution, so A can be any number.
- $P(0) = Ae^{k \cdot 0} = A$.

The solution to the initial value problem

$$\frac{dP}{dt} = kP, \qquad P(0) = P_0$$
is
$$P(t) = P_0 e^{kt}.$$

The Logistic Model

- The Logistic Model works in cases when the population is constrained by its environment.
- Let P(t) be the population at time t.
- Then the Logistic Equation is:

$$\frac{\mathrm{d}P}{\mathrm{d}t} = kP\left(1 - \frac{P}{K}\right)$$

 The constant K is called the carrying capacity. It represents how many individuals the environment can sustain in the long run.

$$\frac{dP}{dt} = kP\left(1 - \frac{P}{K}\right)$$

$$\int \frac{1}{P(1 - P/K)} dP = \int kdt$$

$$\int \frac{K}{P(K - P)} dP = \int kdt$$

$$\int \left(\frac{1}{P} + \frac{1}{K - P}\right) dP = \int kdt$$

$$\ln |P| - \ln |K - P| = kt + C$$

$$\ln \left|\frac{K - P}{P}\right| = -kt - C$$

$$\frac{K - P}{P} = \pm e^{-C}e^{-kt} = Ae^{-kt}$$

$$K = P(1 + Ae^{-kt})$$

$$P = \frac{K}{1 + Ae^{-kt}}$$

The solution to the initial value problem

$$\frac{dP}{dt} = kP\left(1 - \frac{P}{K}\right), \qquad P(0) = P_0$$

is

$$P = \frac{K}{1 + Ae^{-kt}}, \qquad A = \frac{K - P_0}{P_0}.$$

Write the solution of the initial value problem

$$\frac{dP}{dt} = 0.08P \left(1 - \frac{P}{1000} \right), \qquad P(0) = 100$$

and use it to find when the population reaches 900.

$$P(t) = \frac{1000}{1 + Ae^{-0.08t}}, \qquad A = \frac{1000 - 100}{100} = 9$$
Therefore
$$P(t) = \frac{1000}{1 + 9e^{-0.08t}}.$$

Set
$$P(t) = 900$$
:
$$\frac{1000}{1 + 9e^{-0.08t}} = 900$$
$$1 + 9e^{-0.08t} = 1000/900$$
$$e^{-0.08t} = \frac{1000/900 - 1}{9} = \frac{1}{81}$$
$$-0.08t = -\ln 81$$
$$t = \frac{\ln 81}{0.08} \approx 54.9$$