

Lecture 1: Motivation for linear algebra

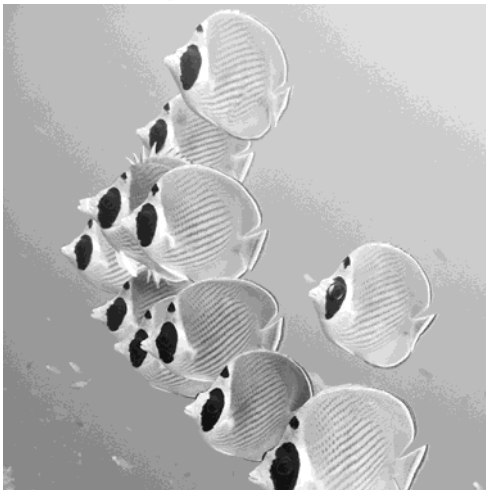
Tuesday, August 25, 2015 9:30 AM

Admin: Textbook, syllabus, homework, midterms, final, grading, office hours, ...

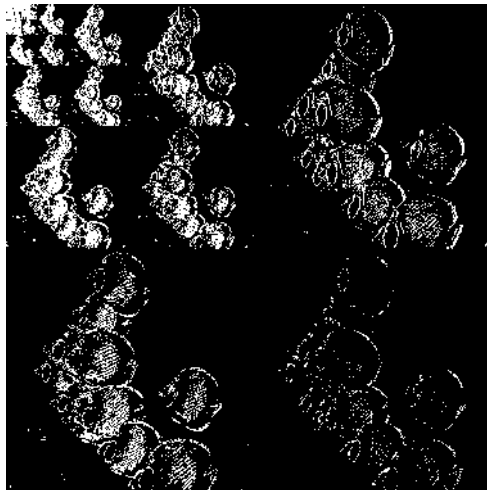
MOTIVATION FOR LINEAR ALGEBRA

- Linear transformations are everywhere!
 - Calculus: integration and differentiation are linear
 - Signals: Fourier transform is linear
 - Quantum physics: time evolution is linear
- Many applications
 - Solving systems of linear equations
$$\begin{cases} 2x - y = 3 \\ -x + y = -2 \end{cases}$$
 - Solving differential equations and recursions
$$\ddot{y} = \dot{y} + y \quad x_n = x_{n-1} + x_{n-2}$$
 - Image compression

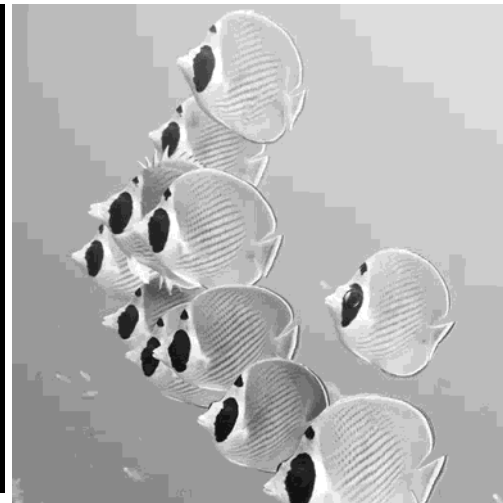
Original



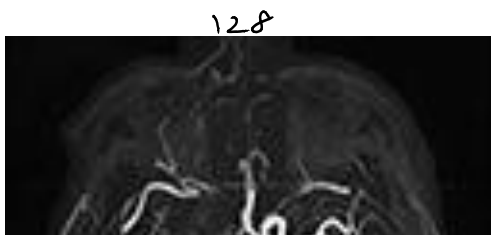
Keep 10% of coeffs



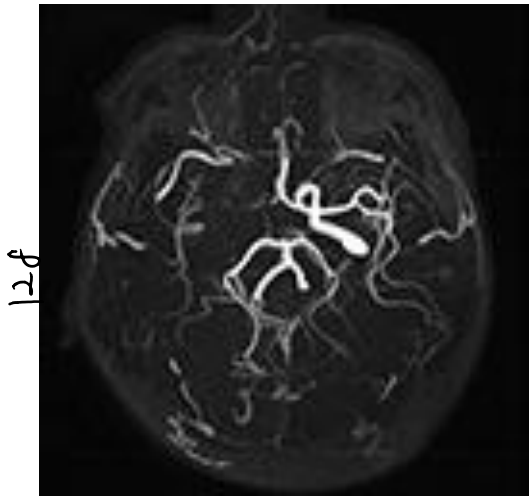
Result



- Compressed sensing



of variables
 $N = 128^2 = 16384$

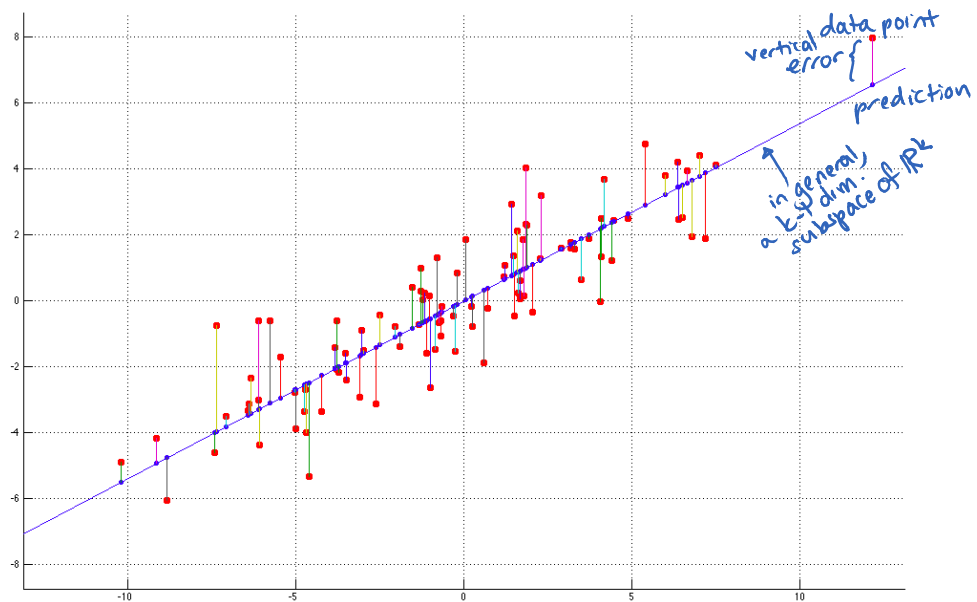


of variables
 $N = 128^2 = 16384$

of observations
 $d = 4480 = 0.27N$
 15 minutes
 in L₁ magic



- Machine learning and statistics:
 dimension reduction, least-squares fitting

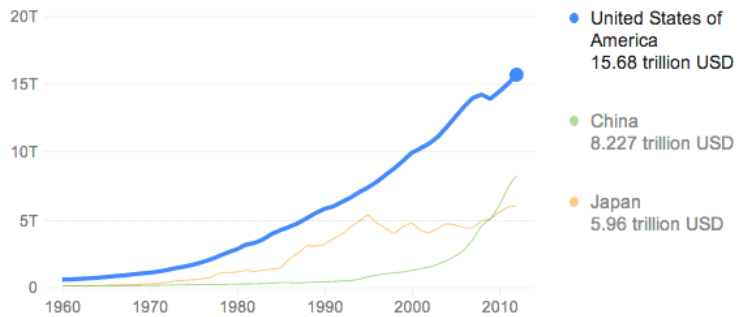


Example: Predict US gross domestic product (GDP) in 2050.
 Answer:

About 154,000,000 results (0.81 seconds)

15.68 trillion USD (2012)

United States of America, Gross domestic product

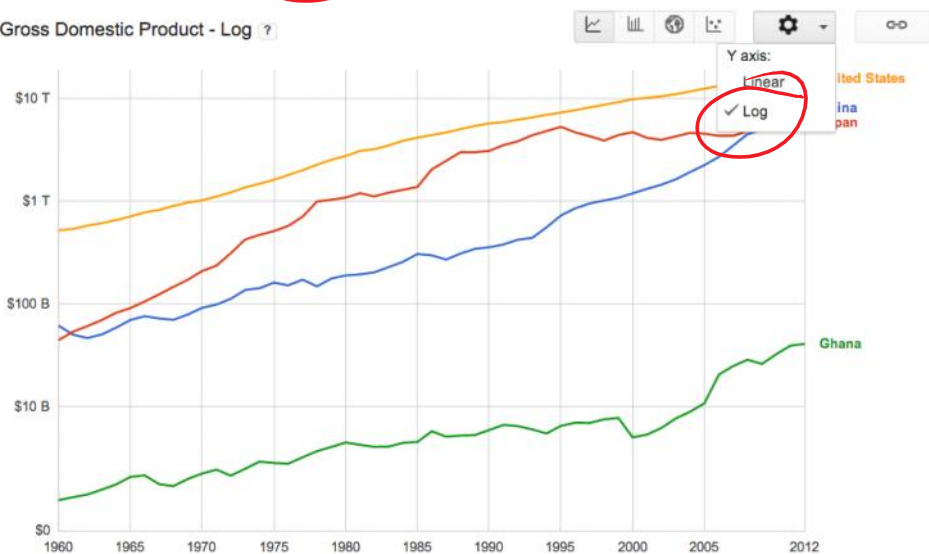


Explore more

Sources include: World Bank

Feedback / More info

Gross Domestic Product - Log ?



An exponential should fit the data better than a straight line.

```
USGDPdata = [1960, 5.20531e11; 1961, 5.39051e11; 1962, 5.79748e11; 1963, 6.1167e11; 1964, 6.56912e11; 1965, 7.12082e11; 1966, 7.80761e11; 1967, 8.25056e11; 1968, 9.01456e11; 1969, 9.73385e11; 1970, 1.0248e12; 1971, 1.1131e12; 1972, 1.225e12; 1973, 1.3693e12; 1974, 1.4859e12; 1975, 1.6234e12; 1976, 1.8091e12; 1977, 2.0136e12; 1978, 2.276e12; 1979, 2.5435e12; 1980, 2.7675e12; 1981, 3.1038e12; 1982, 3.2277e12; 1983, 3.5069e12; 1984, 3.9004e12; 1985, 4.1848e12; 1986, 4.425e12; 1987, 4.6989e12; 1988, 5.0619e12; 1989, 5.4397e12; 1990, 5.7508e12; 1991, 5.9307e12; 1992, 6.2618e12; 1993, 6.5829e12; 1994, 6.9933e12; 1995, 7.3384e12; 1996, 7.7511e12; 1997, 8.2565e12; 1998, 8.741e12; 1999, 9.301e12; 2000, 9.8988e12; 2001, 1.02339e13; 2002, 1.05902e13; 2003, 1.10893e13; 2004, 1.17978e13; 2005, 1.25643e13; 2006, 1.33145e13; 2007, 1.39618e13; 2008, 1.42193e13; 2009, 1.38983e13; 2010, 1.44194e13; 2011, 1.49913e13; 2012, 1.56848e13];
```



```
>> years = USGDPdata(:,1);
A = [ones(length(years),1), years];
USFit = pinv(A) * log(USGDP)
```

USFit =

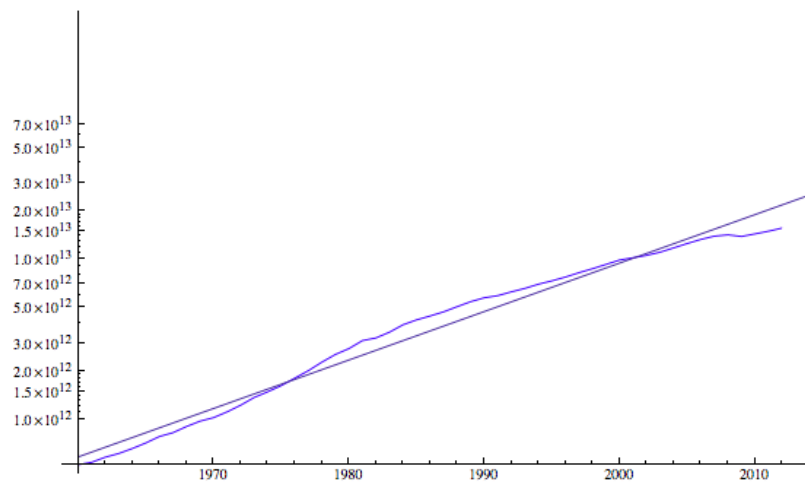
```
-1.096282320582321e+02
 6.975400397258215e-02
```

```
>> exp(USFit' * [1; 2050])
```

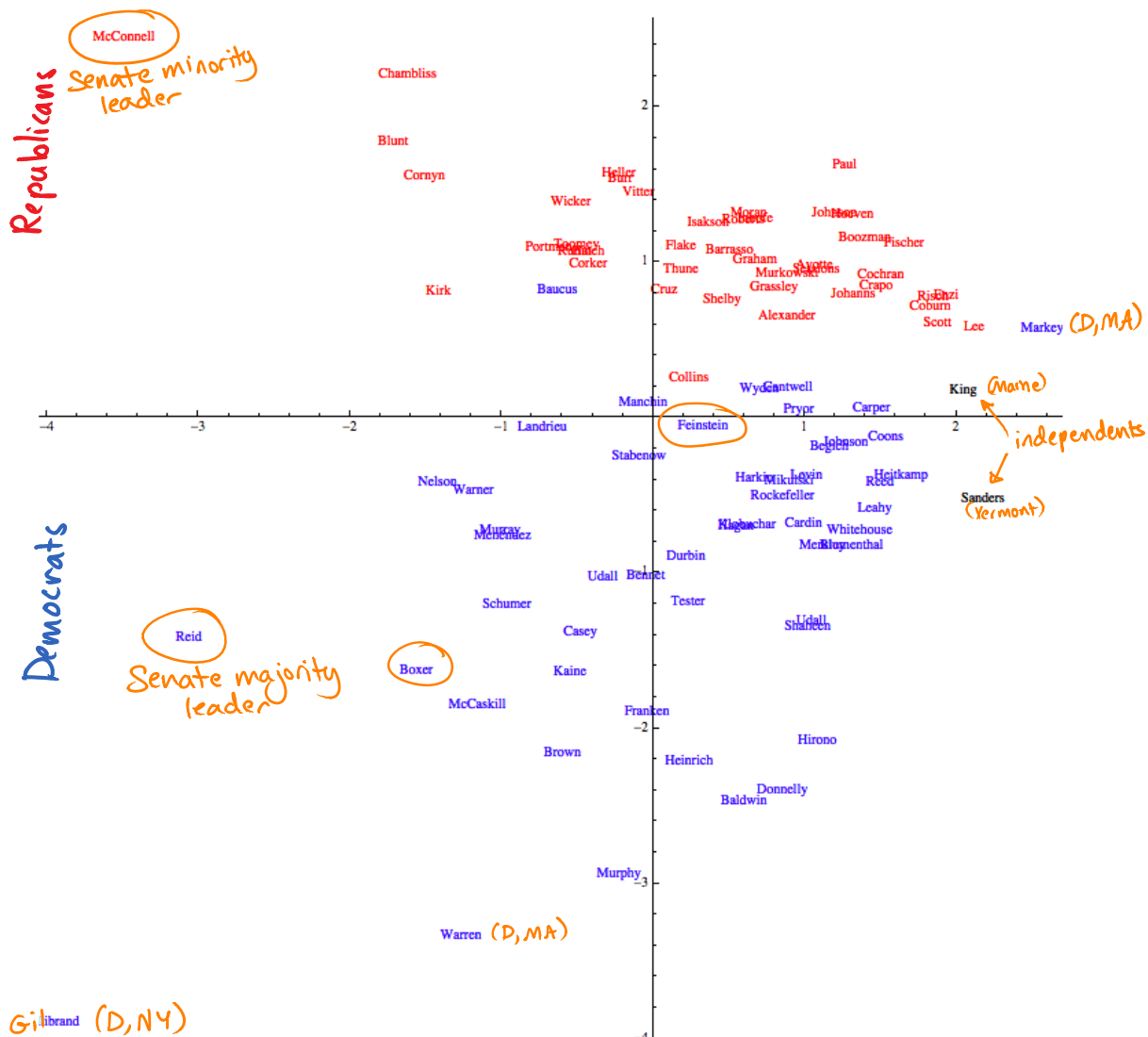
ans =

```
3.099636305012074e+14
```

= 30 trillion dollars



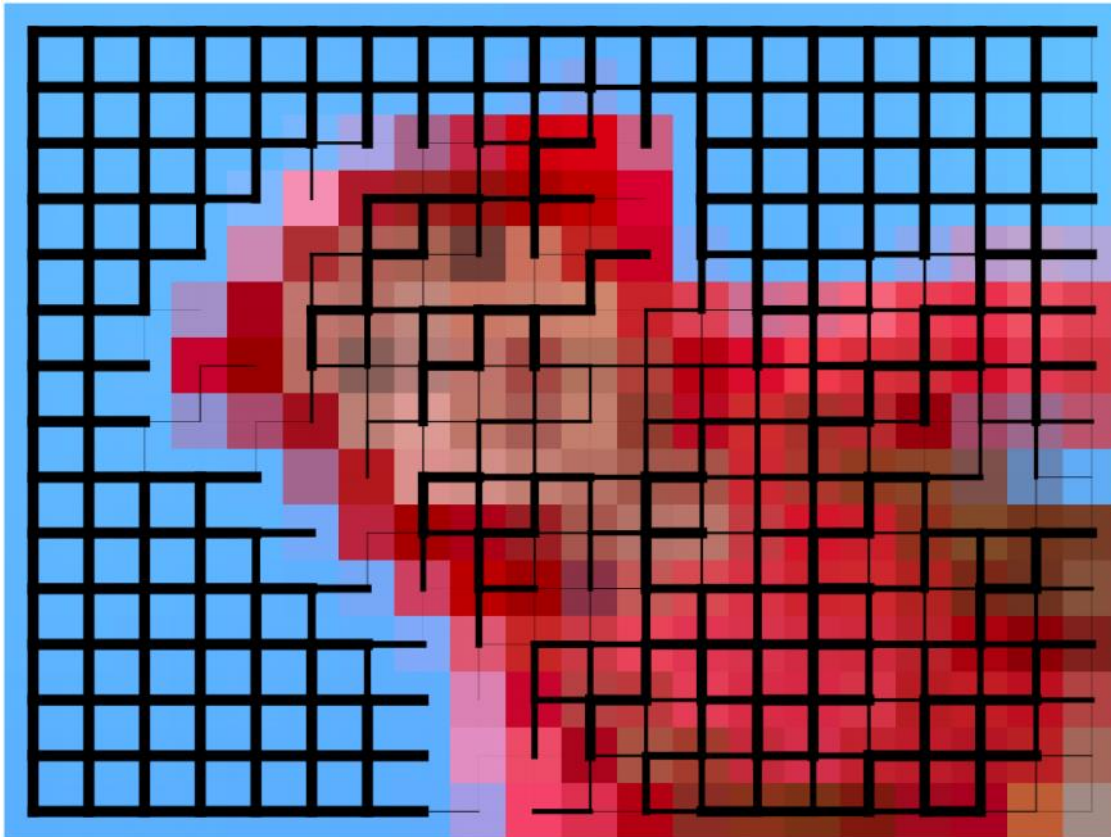
```
ListPlot[{#} & /@ dataprojectedmanually, AspectRatio -> 1, PlotMarkers -> data[[All, 1, 1],
PlotStyle -> (data[[All, 1, 3]]) /. {"D" -> Blue, "R" -> Red, "I" -> Black}]
{97, 17}
{17, 2}
```



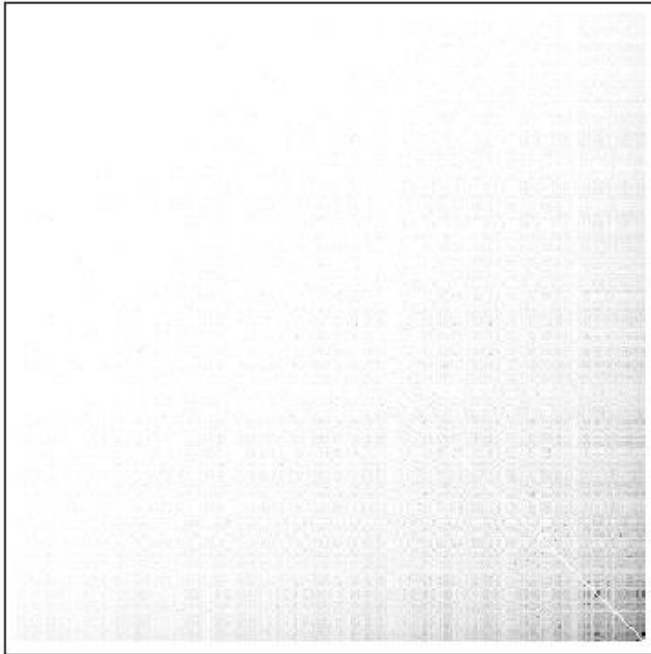
- Even purely combinatorial applications
 1. spectral clustering

APPLICATION 1: SPECTRAL IMAGE SEGMENTATION





```
matrix = Import["/Users/breic/Desktop/adjacencymatrix.txt", "Table"];
matrix += Transpose[matrix];
matrix // ArrayPlot
```



```
laplacian = DiagonalMatrix[Plus@@# & /@ matrix] - matrix // N;
di = DiagonalMatrix[(1 / Plus@@#) & /@ matrix // N];
evs = Eigensystem[ $\sqrt{\text{di}} \cdot \text{laplacian} \cdot \sqrt{\text{di}}$ ] // Transpose // Reverse;
```

```
coordinates = evs[[2 ;; 9, 2]] // Transpose;
```

```
numclusters = 16;
```

→ embedding into $\mathbb{R}^d$

```
ClusteringComponents[coordinates, numclusters, 1, Method -> "PAM"]
```

Indiana Jones and the L	A Walk to Remember	Bend It Like Beckham	Con Air
Lord of the Rings: The	Coyote Ugly	Bridget Jones's Diary	Double Jeopardy
Lord of the Rings: The	Dirty Dancing	Frida	Gone in 60 Seconds
Lord of the Rings: The	How to Lose a Guy in 10	Life Is Beautiful	Independence Day
Raiders of the Lost Ark,	Maid in Manhattan	Love Actually	Lethal Weapon 4
Star Wars: Episode IV:	Pretty Woman	, Moulin Rouge	, Men in Black II
Star Wars: Episode VI:	Sister Act	My Big Fat Greek Weddin	Pearl Harbor
Star Wars: Episode V: T	The Princess Diaries 2:	Pride and Prejudice	The Fast and the Furiou
The Lord of the Rings:	The Princess Diaries (W	Rabbit-Proof Fence	The Patriot
	The Wedding Planner	Shakespeare in Love	Tomb Raider
	What Women Want	Whale Rider	Twister
12 Angry Men	A Bug's Life	Amelie	2001: A Space Odyssey
Airplane!	Breakfast at Tiffany's	American Beauty	All the President's Men
American Pie	City of Angels	Being John Malkovich	Blade Runner
American Pie 2	Ever After: A Cinderell	Crouching Tiger	Gandhi
Austin Powers in Goldme	Finding Nemo (Widescree	Election	Jaws
Austin Powers: Internat	Grease	Eternal Sunshine of the	L.A. Confidential
Austin Powers: The Spy	Harry Potter and the Ch	High Fidelity	Lawrence of Arabia
Interview with the Vamp	Harry Potter and the Pr	Lock	Lord of the Rings: The
Liar Liar	Harry Potter and the So	Lost in Translation	, One Flew Over the Cucko
Meet the Parents	Runaway Bride	Magnolia	Seven Samurai
Ransom	The Lion King: Special	Run Lola Run	The Aviator
Spaceballs	The NeverEnding Story	Rushmore	The Exorcist
Spider-Man	The Princess Bride	Sideways	The Godfather
Wayne's World	The Sound of Music	The Royal Tenenbaums	The Godfather
	Willy Wonka & the Choco	Y Tu Mama Tambien	The Graduate
			The Great Escape
			The Maltese Falcon

Cold Mountain	A Fish Called Wanda	A Knight's Tale	Adaptation
Collateral	Alien: Collector's Edit	Ice Age	A Few Good Men
Crash	Back to the Future	Jurassic Park	Air Force One
Fahrenheit 9/11	Back to the Future Part	Lara Croft: Tomb Raider	Armageddon
Finding Neverland	Batman	Minority Report	Clear and Present Danger
Hotel Rwanda	Die Hard 2: Die Harder	Pirates of the Caribbean	Crimson Tide
Man on Fire	Die Hard With a Vengeance	Rush Hour	Enemy of the State
Master and Commander: The	Goldfinger	Rush Hour 2	Entrapment
Million Dollar Baby	Groundhog Day	Sleeping Beauty: Special	High Crimes
Ocean's Twelve	Indiana Jones and the Temple	Spider-Man 2	In the Line of Fire
Ray	Men in Black	Star Wars: Episode II: Attack	Lethal Weapon
Road to Perdition	Mission: Impossible	Star Wars: Episode I: The Phantom	Lethal Weapon 2
Runaway Jury	Predator: Collector's Edition	Terminator 3: Rise of the	Lethal Weapon 3
Seabiscuit	Rocky	The Fifth Element	Patriot Games
The Manchurian Candidate	Speed	The Incredibles	Rules of Engagement
The Notebook	Star Trek II: The Wrath of	The Matrix	Swordfish
The Phantom of the Opera	Terminator 2: Extreme Edition	The Matrix: Reloaded	The Bone Collector
The Pianist	The Hunt for Red October	The Matrix: Revolutions	The Client
	The Terminator	The Mummy	The Fugitive
	True Lies	The Mummy Returns	The Negotiator
		X2: X-Men United	The Pelican Brief
		X-Men	The Rock
			The Sum of All Fears
			Apollo 13
			As Good as It Gets
			Black Hawk Down
			Boys Don't Cry
			Cast Away
			Chocolat
			Dances With Wolves: Special
			Dead Man Walking
			Driving Miss Daisy
			Enemy at the Gates
			E.T. the Extra-Terrestrial
			Field of Dreams
			Forrest Gump
			Fried Green Tomatoes
			Gladiator
			Glory
			Good Will Hunting
			Jerry Maguire
			Moonstruck
			My Cousin Vinny
			October Sky
			Philadelphia
			Primal Fear
			Rain Man
			Remember the Titans
12 Monkeys	Ace Ventura: Pet Detective	50 First Dates	
Almost Famous	A League of Their Own	Anger Management	
American History X	A River Runs Through It	Bad Boys II	
Anchorman: The Legend of	Basic Instinct	Behind Enemy Lines	
Donnie Darko	Cheaper by the Dozen	Bruce Almighty	
Garden State	Daddy Day Care	Dodgeball: A True Underdog	
GoodFellas: Special Edition	Erin Brockovich	Harold and Kumar Go to	
Grosse Pointe Blank	Face/Off	Hero	
Heat: Special Edition	Father of the Bride	Hidalgo	
Kill Bill: Vol. 1	Kindergarten Cop	Hitch	
Kill Bill: Vol. 2	Legally Blonde	Hostage	
Memento	Mrs. Doubtfire	I Robot	
Napoleon Dynamite	Notting Hill	Meet the Fockers	
Office Space	Pay It Forward	National Treasure	
Pulp Fiction	Phenomenon	Ocean's Eleven	
Requiem for a Dream	Serendipity	Sahara	
Reservoir Dogs	Shall We Dance?	Shrek 2	
Seven	Sleepless in Seattle	The Bourne Identity	
Sin City	Steel Magnolias	The Bourne Supremacy	
		The Count of Monte Cristo	

2. algorithms based on fast SDD solvers

* max-flow & multi-commodity flow problems

- for decades, best algorithms were deterministic, combinatorial
[Goldberg-Rao '98]: $\tilde{O}(m\sqrt{n}/\epsilon)$ augmenting paths
blocking flows...
for $(1-\epsilon)$ -approx max flow

- recent breakthroughs based on numerical linear algebra,
spectral graph theory

[S-H, Teng et al. '11]: $\tilde{O}(mn^{1/3}/\epsilon^{1/3})$
'usc

[Kelner et al., '13; Sherman '13]:

$\tilde{O}(m/\epsilon^2)$ or $\tilde{O}(km/\epsilon^2)$ for k flows

- * generating random spanning trees
- * graph sparsification
- * sparsest cut
- * distributed routing

This week: Solving systems of linear equations

Linear systems of equations

- * Examples, non-examples
- * General problem
- * Solving by elimination — complexity analysis
- * Correspondence to matrices
- * Solving by computer
- Bigger examples
- When does a system of equations have a solution?
(# variables vs. # consistent, indep. equations)
- Compressed sensing
- Extensions: Stability, solving repeatedly,
Geometry Systems with a special form (eg., sparse)

Examples:

- $\{ x = 3 \}$ 1 linear equation in 1 variable
- $\{ 2x - y = 3 \}$ 1 linear equation in 2 variables
- $\{ \begin{array}{l} 2x - y = 3 \\ x - y = 2 \\ x + y = 0 \end{array} \}$ 3 linear equations, 2 variables
- $\{ \begin{array}{l} x^2 + xy = 2 \\ x + y = 3 \end{array} \}$ quadratic equation — not linear!
- $\{ \begin{array}{l} x + y + z = 0 \\ x + \cos(y) + z = 2 \end{array} \}$ transcendental equation — not linear!

General problem:

Given: The system of linear equations

$$\begin{aligned} a_{11}x_1 + a_{12}x_2 + a_{13}x_3 + \dots + a_{1n}x_n &= b_1 \\ a_{21}x_1 + a_{22}x_2 + a_{23}x_3 + \dots + a_{2n}x_n &= b_2 \\ \vdots &\vdots \\ a_{m1}x_1 + a_{m2}x_2 + a_{m3}x_3 + \dots + a_{mn}x_n &= b_m \end{aligned}$$

(m equations in n unknowns $x_1, \dots, x_n$)

Goal: Solve for the unknowns $x_1, \dots, x_n$

(-If there isn't a solution, then say so.
-If there are multiple solutions find them all!)

Note: We will see later that there is always either

- * one unique solution,
- * no solution, or
- * infinitely many solutions

Example: Solve

$$\begin{aligned} 2x - y &= 3 \\ x - y &= 2 \\ x + y &= 0 \end{aligned}$$

Answer:

Adding 3rd equation to 1st equation cancels out y , giving

$$3x = 3 \Rightarrow x = 1$$

Substituting this back into any other equation gives

$$\Rightarrow \boxed{(x, y) = (1, -1)} \text{ is the solution. } \checkmark$$

(Check this.)

Example: Solve

$$\begin{aligned} x + 3y - z &= 4 \\ 3x + 10y &= 8 \end{aligned}$$

Answer: To eliminate x , subtract 3 times the first equation from the 2nd one:

$$\Rightarrow \begin{cases} x + 3y - z = 4 \\ y + 3z = -4 \end{cases}$$

$$\Rightarrow y = -4 - 3z, \text{ where } z \text{ is arbitrary}$$

Substituting into the first equation,

$$\begin{aligned}
 x &= 4 - 3y + z \\
 &= 4 - 3(-4 - 3z) + z \\
 &= 16 + 10z
 \end{aligned}$$

⇒ Infinitely many solutions, all of the form

$$x = 16 + 10z, \quad y = -4 - 3z, \quad z \in \mathbb{R} \text{ arbitrary}$$

As a vector,

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 16 \\ -4 \\ 0 \end{pmatrix} + z \begin{pmatrix} 10 \\ -3 \\ 1 \end{pmatrix}, \quad z \in \mathbb{R}$$

↑ constant coefficients
 ↑ free variable

Observe:

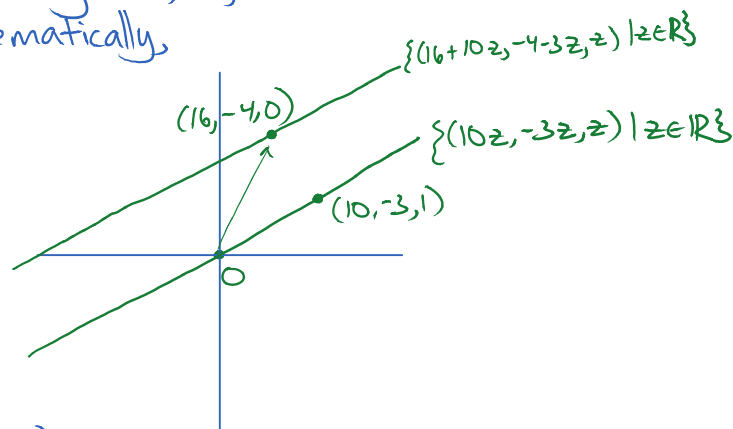
① The set of points

$$\{(10z, -3z, z) \mid z \in \mathbb{R}\}$$

is a line through the origin $(0, 0, 0)$.

Adding $(16, -4, 0)$ shifts this line.

Schematically,



② $(16, -4, 0)$ is one solution to

$$x + 3y - z = 4$$

$$3x + 10y = 8$$

while $(10, -3, 1)$ solves

$$x + 3y - z = 0$$

$$3x + 10y = 0$$

}"homogeneous equations"

⇒ The general solution for a set of nonhomogeneous equations is a particular solution plus the general solution to the homogeneous equations.

③ We didn't have to eliminate x first...

More goals: * Solve approximately, instead of exactly

More goals: * Solve approximately, instead of exactly

* How good is the solution? (stability)

* Solve the same system multiple times (different r.h.s.s)

* Perturbed systems

* Systems with a special form

* Understand both how the algorithms work and how to use them! (and when to use them)

Example: polynomial interpolation

2 points determine a line

3 points determine a quadratic curve

⋮

any $n-1$ points $(x_1, y_1), \dots, (x_{n-1}, y_{n-1})$ determine a polynomial of degree $\leq n$

① Find the equation $y = mx + b$ for the line passing through the points

$(1, 1)$ and $(6, 5)$

Answer: slope $m = \frac{5-1}{6-1} = \frac{4}{5}$
y-intercept $b = \frac{1}{5}$
(check this)

② Find the equation $y = ax^2 + bx + c$ for the parabola that goes through the points

$(1, 1)$, $(6, 5)$, $(-2, 3)$

Answer: Set up three equations:

$$\begin{aligned} 1 &= a \cdot 1^2 + b \cdot 1 + c = a + b + c \\ 5 &= a \cdot 6^2 + b \cdot 6 + c = 36a + 6b + c \\ 3 &= a \cdot (-2)^2 + b \cdot (-2) + c = 4a - 2b + c \end{aligned}$$

$$\hookrightarrow \begin{cases} a + b + c = 1 \\ -30b - 35c = -31 \\ -6b - 3c = -1 \end{cases} \rightarrow \begin{cases} a + b + c = 1 \\ 6b + 3c = 1 \\ 20c = 26 \end{cases}$$

$$\Rightarrow c = 13/10$$

Substituting into 2nd equation,

$$b = \frac{1}{6} \cdot \left(1 - 3 \cdot \frac{13}{10}\right) = -\frac{29}{60}$$

Substituting into 1st equation,

$$a = 1 - b - c = 1 - \frac{13}{10} + \frac{29}{60} = \frac{11}{60}$$

Substituting into 1st equation,

$$a = 1 - b - c = 1 - \frac{13}{10} + \frac{29}{60} = \frac{11}{60}$$

$$\Rightarrow (a, b, c) = \left(\frac{11}{60}, \frac{29}{60}, \frac{13}{10} \right)$$

check this. ✓

Solution method: Gaussian elimination

add multiples of the 1st equation to other equations
in order to eliminate one variable from them
add multiples of 2nd equations to following equations
to eliminate the next variable

⋮
with n equations in n unknowns, end up with equations

$$a_{11}x_1 + a_{12}x_2 + a_{13}x_3 + \dots + a_{1n}x_n = b_1$$

$$a_{22}x_2 + a_{23}x_3 + \dots + a_{2n}x_n = b'_2$$

$$a_{33}x_3 + \dots + a_{3n}x_n = b'_3$$

$$\vdots$$

$$a_{n-1,n-1}x_{n-1} + a_{n-1,n}x_n = b'_{n-1}$$

$$a_{nn}x_n = b'_n$$

Now work backwards

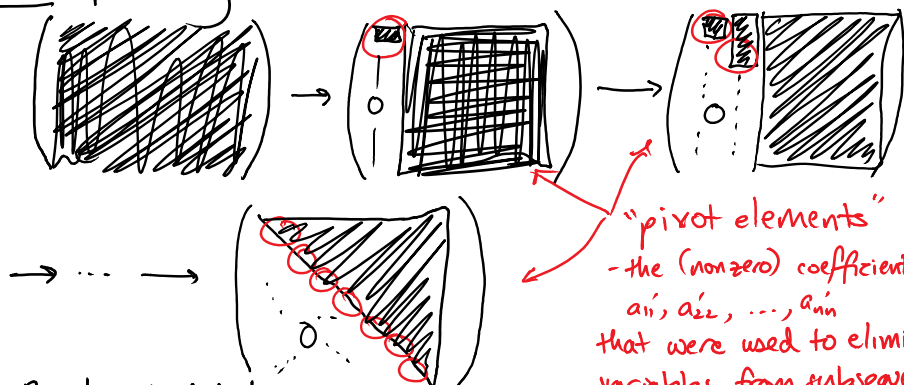
last equation $\Rightarrow x_n = \frac{b'_n}{a_{nn}}$

substitute into eq. $n-1 \Rightarrow a_{n-1,n-1}x_{n-1} = b'_{n-1} - a_{n-1,n} \frac{b'_n}{a_{nn}}$

Keep on substituting backwards, solving for variables

$$x_n, x_{n-1}, x_{n-2}, \dots, x_2, x_1$$

Picture: possibly nonzero entries in the matrix of coefficients



"pivot elements"
- the (nonzero) coefficients
 $a_{11}, a_{22}, \dots, a_{nn}$
that were used to eliminate
variables from subsequent equations

Back substitution...

Complexity analysis

Claim: G.E. on an $n \times n$ system of equations
uses $(\sim n^3)$ basic operations (multiplication, division, addition, etc)

Proof sketch:

Eliminating x_1 using the first equation, you need to update $n-1$ other equations, each with n coefficients $\Rightarrow O(n^2)$ steps

Repeating for the other variables $\Rightarrow O(n^3)$ conservatively
Back substitution takes $O(n^2)$ steps. Why? $\square$

Example

Solve
$$\begin{cases} -x_1 + 3x_2 - 2x_3 = 1 \\ -x_1 + 4x_2 - 3x_3 = 0 \\ -x_1 + 5x_2 - 4x_3 = 0 \end{cases}$$

$$\rightarrow \begin{pmatrix} 3 & -2 \\ 1 & -1 \\ 2 & -2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 1 \\ -1 \\ -1 \end{pmatrix}$$

$$\begin{pmatrix} 3 & -2 \\ 1 & -1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}$$

Stuck! 3rd equation is $0x_1 + 0x_2 + 0x_3 = 1$
 $\Rightarrow$ no solution.

Solving linear equations on your computer

① Mathematica:

$$A = \{\{1, 1, 1\}, \{36, 6, 1\}, \{4, -2, 1\}\};$$

$$b = \{1, 5, 3\}$$

use `LinearSolve[A, b]`

② Matlab/Octave:

```
>> A = [1 1 1; 36 6 1; 4 -2 1]
```

A =

```
1    1    1
36   6    1
4   -2    1
```

```
>> b = [1; 5; 3]
```

b =

```
1
5
3
```

```
>> x = A \ b
```

x =

```
>> A = [1 1 1; 36 6 1; 4 -2 1]
```

```
A =
```

```
    1    1    1
   36    6    1
    4   -2    1
```

```
>> b = [1; 5; 3]
```

```
b =
```

```
    1
    5
    3
```

```
>> x = A \ b
```

```
x =
```

```
    0.1833
   -0.4833
    1.3000
```

```
>> A*x - b
```

```
ans =
```

```
    1.0e-15 *
         0
    0.8882
    0.4441
```

(see also 'format rat')
(what if there's no solution?)

③ Numpy in python:

```
>>> import numpy as np
>>> A = np.array([[1,1,1],[36,6,1],[4,-2,1]])
>>> b = np.array([1,5,3])
>>> x = np.linalg.solve(A,b)
>>> x
array([ 0.18333333, -0.48333333,  1.3         ])
>>> np.dot(A,x) - b
array([ 0.00000000e+00,  0.00000000e+00,  4.44089210e-16])

>>> n = 800; A = np.random.randn(n,n); b = np.dot(A, np.random.randn(n));
>>> start = time.time(); x = np.linalg.solve(A,b); end = time.time(); end-start
0.029742002487182617
>>> n = 1600; A = np.random.randn(n,n); b = np.dot(A, np.random.randn(n));
>>> start = time.time(); x = np.linalg.solve(A,b); end = time.time(); end-start
0.17376208305358887
>>> n = 3200; A = np.random.randn(n,n); b = np.dot(A, np.random.randn(n));
>>> start = time.time(); x = np.linalg.solve(A,b); end = time.time(); end-start
1.0949180126190186
>>> n = 6400; A = np.random.randn(n,n); b = np.dot(A, np.random.randn(n));
>>> start = time.time(); x = np.linalg.solve(A,b); end = time.time(); end-start
7.7281270027160645
```