

Homework 4

Thursday, September 24, 2015 9:30 AM

Due in class Thursday 10/1.

- ① For a general vector space, let U and V be two subspaces with respective bases $B_U = \{\vec{u}_1, \dots, \vec{u}_m\}$ and $B_V = \{\vec{v}_1, \dots, \vec{v}_n\}$. Prove that

$U \cap V = \{\vec{0}\}$ if and only if $\{\vec{u}_1, \dots, \vec{u}_m, \vec{v}_1, \dots, \vec{v}_n\}$ is a linearly independent set.

- ② Find two different unit vectors (i.e., length-one vectors) that are orthogonal to $\vec{u} = \begin{pmatrix} 3 \\ -2 \end{pmatrix} \in \mathbb{R}^2$.

- ③ Let

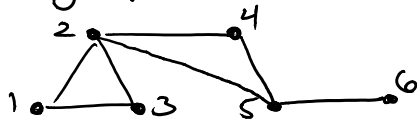
$$A = \begin{pmatrix} 2 & 2 & 5 & 0 & 1 \\ 3 & 4 & 8 & 1 & 2 \\ 1 & 6 & 5 & 5 & 3 \end{pmatrix}, \quad v = \begin{pmatrix} 3 \\ 1 \\ 0 \\ 3 \\ -8 \end{pmatrix}.$$

Verify that $v \in N(A)$, and then extend $\{v\}$ to a basis for $N(A)$. (That is, find a basis for $N(A)$ that includes v as one of its elements.)

- ④ Recall from Lecture 9 the edge incidence matrix E_G for a graph G .

(If G has n vertices, m edges, then E_G is an $n \times m$ matrix.)

- ② For the graph G



what is E_G ? (Orient the edges whichever way you like.)

- ⑥ For the same graph, what is $E_G E_G^T$?

What is the rank of $E_G E_G^T$? Feel free to use Matlab/Mathematica.

What is the nullspace of $E_G E_G^T$?

(Hint: Recall Homework 2 #9.)

- ⑦ For a general graph G , compute the $n \times n$ matrix $E_G E_G^T$. There should be 3 cases:

1) If vertex i is not adjacent to vertex j ,
argue that $(E_G E_G^T)_{i,j} = 0$.

2) What is $(E_G E_G^T)_{i,i}$?

3) What is $(E_G E_G^T)_{i,j}$ when i is adjacent to j ?

If G is connected, what is $R(E_G E_G^T)$?

⑤ What is the projection of $b = (2, 1, 2)$ onto the plane spanned by $(0, 1, 0)$ and $(0, 1, 1)$?

⑥ Let $f: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be the linear transformation that

- First rotates the xz -plane by $\pi/3$ radians counterclockwise about the y -axis,
- Then reflects everything about the yz -plane (i.e., switching the sign of the x coordinate),
- Then rotates the xy -plane by $\pi/6$ radians counterclockwise about the z -axis.

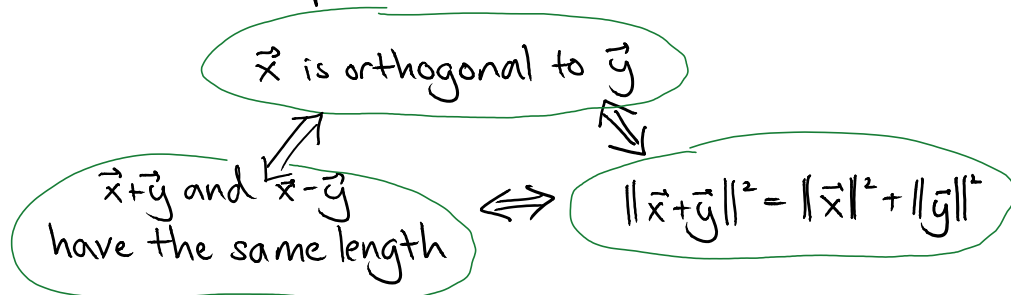
What is the 3×3 matrix representing f ?

What is the determinant of this matrix?

⑦ a) Prove the "parallelogram law":

$$\|\vec{x} + \vec{y}\|^2 + \|\vec{x} - \vec{y}\|^2 = 2(\|\vec{x}\|^2 + \|\vec{y}\|^2).$$

b) Show the implications:



⑧ Consider the 2×2 complex matrix

$$A = \begin{pmatrix} e^{i\theta} & 0 \\ 0 & e^{-i\theta} \end{pmatrix}.$$

Rewrite this matrix in the basis $\{(1, i), (1, -i)\}$.

Simplify your answer as much as possible.

That is, give a 2×2 matrix that corresponds to the same linear transformation as A , but in the basis $\{(1, i), (1, -i)\}$ instead of the standard basis $\{e_1, e_2\}$.

