SYS 6003: Optimization

Lecture 15

In last lecture, we introduced L-smooth functions and proved an important property of those functions. We summarize and show more properties of L-smooth function as follows.

Lemma 1 (Properties of Smooth Functions) If f is L-smooth, then for any $\mathbf{x}, \mathbf{y} \in \mathbb{R}^d$, we have

(1)
$$f(\mathbf{x}) \leq f(\mathbf{y}) + \nabla f(\mathbf{y})^{\top} (\mathbf{x} - \mathbf{y}) + \frac{L}{2} \|\mathbf{x} - \mathbf{y}\|_{2}^{2};$$

(2) $(\nabla f(\mathbf{x}) - \nabla f(\mathbf{y}))^{\top} (\mathbf{x} - \mathbf{y}) \leq L \|\mathbf{x} - \mathbf{y}\|_{2}^{2}.$

If f is in addition convex, we have

(3)
$$f(\mathbf{x}) \ge f(\mathbf{y}) + \nabla f(\mathbf{y})^{\top} (\mathbf{x} - \mathbf{y}) + \frac{1}{2L} \|\nabla f(\mathbf{x}) - \nabla f(\mathbf{y})\|_{2}^{2}$$

(4) $(\nabla f(\mathbf{x}) - \nabla f(\mathbf{y}))^{\top} (\mathbf{x} - \mathbf{y}) \ge \frac{1}{L} \|\nabla f(\mathbf{x}) - \nabla f(\mathbf{y})\|_{2}^{2}$.

Remark 1 If f is twice differentiable, then there is an equivalent, and perhaps easier, definition of smoothness: f is smooth if there exists a constant L > 0 such that $\nabla^2 f(x) \prec L\mathbf{I}$, where I is an identity matrix. In other words, the largest eigenvalue of the Hessian of f is uniformly upper bounded by L everywhere.

Now we introduce strongly convex functions, which basically are convex functions that subtracting a quadratic function from it remains convex.

Definition 1 (Strongly Convex Function) $f(\mathbf{x})$ is μ -strongly convex if $f(\mathbf{x}) - \mu \|\mathbf{x}\|_2^2/2$ is convex, where $\mu > 0$. The positive constant μ is called the modulus of strong convexity of f.

Strongly convex functions also have several properties. We summarize them in the following lemma.

Lemma 2 (Properties of Strongly Convex Functions) If f is a μ -strongly convex function, then for any $\mathbf{x}, \mathbf{y} \in \mathbf{dom} f$, we have

(1)
$$f(\alpha \mathbf{x} + (1 - \alpha)\mathbf{y}) \le \alpha f(\mathbf{x}) + (1 - \alpha)\mathbf{y} - \frac{\mu}{2}\alpha(1 - \alpha)\|\mathbf{x} - \mathbf{y}\|_{2}^{2}, \text{ for any } \alpha \in [0, 1];$$

(2)
$$f(\mathbf{x}) \ge f(\mathbf{y}) + \nabla f(\mathbf{y})^{\top} (\mathbf{x} - \mathbf{y}) + \frac{\mu}{2} \|\mathbf{x} - \mathbf{y}\|_{2}^{2};$$

(3)
$$(\nabla f(\mathbf{x}) - \nabla f(\mathbf{y}))^{\top} (\mathbf{x} - \mathbf{y}) \ge \mu \|\mathbf{x} - \mathbf{y}\|_{2}^{2};$$

(4)
$$f(\mathbf{x}) \leq f(\mathbf{y}) + \nabla f(\mathbf{y})^{\top} (\mathbf{x} - \mathbf{y}) + \frac{1}{2\mu} \|\nabla f(\mathbf{x}) - \nabla f(\mathbf{y})\|_{2}^{2};$$

(5)
$$(\nabla f(\mathbf{x}) - \nabla f(\mathbf{y}))^{\top} (\mathbf{x} - \mathbf{y}) \leq \frac{1}{\mu} \|\nabla f(\mathbf{x}) - \nabla f(\mathbf{y})\|_{2}^{2}.$$

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As we can see, these properties are analogous to those of smooth functions, hence we omit the proof here.

Remark 2 If f is twice differentiable, then there is an equivalent, and perhaps easier, definition of strong convexity: f is strongly convex if there exists a constant $\mu > 0$ such that $\nabla^2 f(x) \succeq \mu \mathbf{I}$, where \mathbf{I} is an identity matrix. In other words, the smallest eigenvalue of the Hessian of f is uniformly lower bounded by μ everywhere.

Remark 3 Recall that if a function is L-smooth, the largest eigenvalue of the Hessian of f is uniformly upper bounded by L everywhere. Thus, strongly convexity can be deemed as an analogy to smoothness. By imposing strongly convexity and smoothness together, we basically require that the smallest eigenvalue of the Hessian of f is bounded away from zero, and the largest eigenvalue of the Hessian of f is bounded from above, i.e., $\mu \mathbf{I} \preceq \nabla^2 f(\mathbf{x}) \preceq L\mathbf{I}$. In particular, we must have $\mu \leq L$ for the same function f.

Recall that we have proved the following theorem regarding the convergence rate of gradient descent method for L-smooth functions.

Theorem 1 If f is convex and L-smooth, then the gradient descent with stepsize $\eta = 1/L$ satisfies

$$f(\mathbf{x}_{t+1}) - f(\mathbf{x}^*) \le \frac{L \|\mathbf{x}_1 - \mathbf{x}^*\|}{2t}.$$

In the proof of this theorem, we have also showed that the function value is monotonically decreasing. We summarize it in the following lemma.

Lemma 3 Under the same conditions of Theorem 1, we have

$$f(\mathbf{x}_{t+1}) - f(\mathbf{x}_t) \le -\frac{1}{2L} \|\nabla f(\mathbf{x}_t)\|_2^2$$

In fact, we can show that not only the function value is monotonically decreasing, but also the estimation error of the iterate is monotonically decreasing.

Lemma 4 Under the same conditions of Theorem 1, we have

$$\|\mathbf{x}_{t+1} - \mathbf{x}^*\|_2 \le \|\mathbf{x}_t - \mathbf{x}^*\|_2 - 1/L^2 \cdot \|\nabla f(\mathbf{x}_t)\|_2^2$$

We are going to prove it next time.