

## Time Frequency Characteristics

$$X(j\omega) = |X(j\omega)|e^{j\angle X(j\omega)}$$

$$x(t) \rightarrow h(t) \rightarrow y(t) = x(t) * h(t)$$

$$X(j\omega)H(j\omega) = Y(j\omega)$$

$$|Y(j\omega)| = |X(j\omega)||H(j\omega)|$$

$$\angle Y(j\omega) = \angle X(j\omega) + \angle H(j\omega)$$

Changing the magnitude of the signal leads to amplification or suppression.

Altering the phase of the signal makes it unrecognizable.

## Linear Phase

$$\delta(t-t_0) \leftrightarrow e^{-j\omega t_0}$$

Information content at different frequencies is shifted by different amounts.

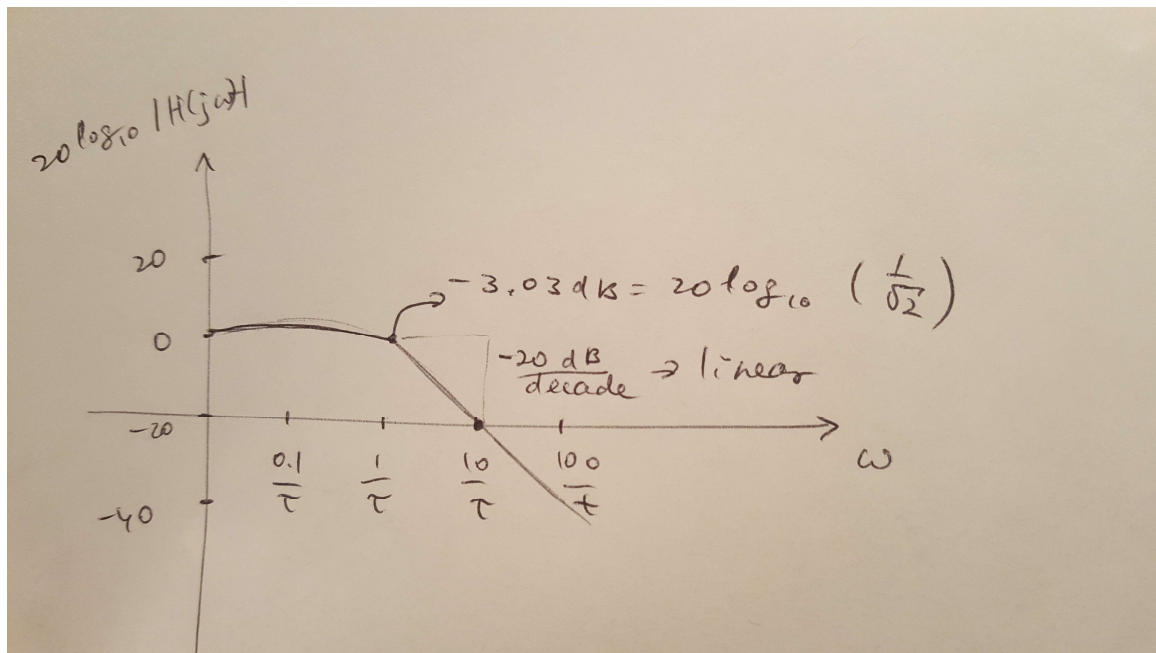
The shift in time by  $t_0$  is a function of frequency and leads to "group delay."

## Group Delay

$$\alpha(\omega) = -\frac{d}{d\omega} \angle H(j\omega)$$

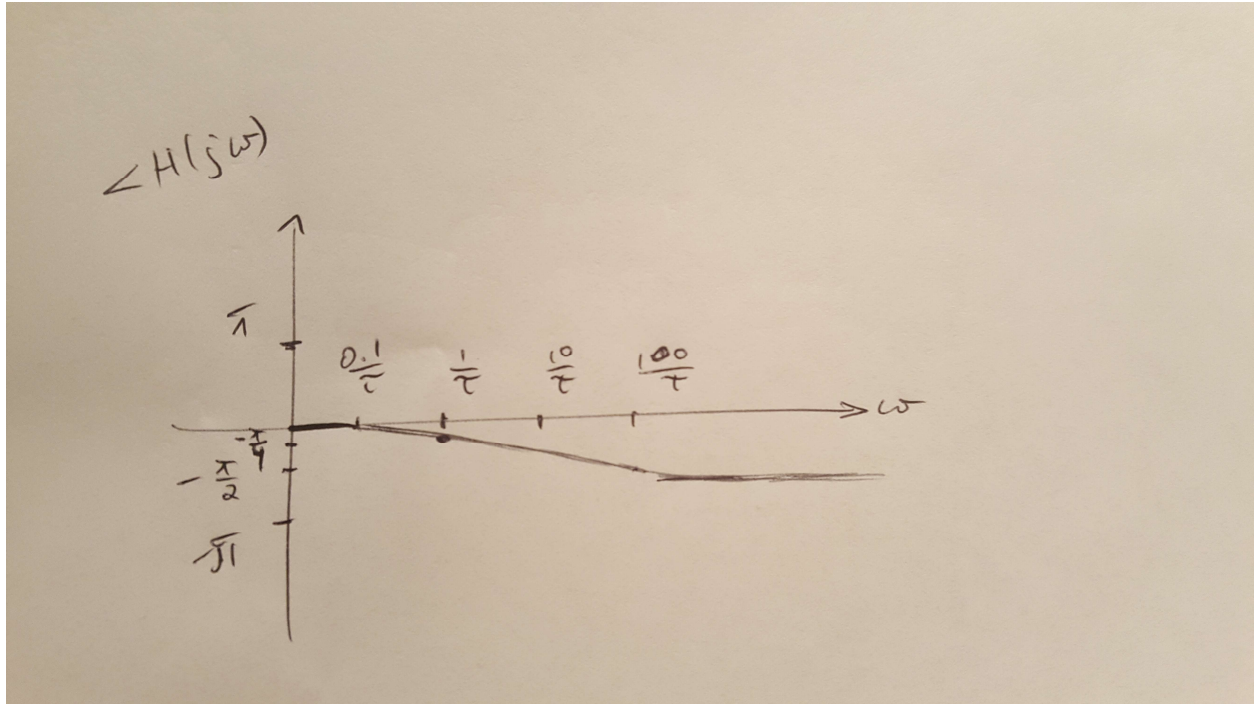
## Bode Plots

Bode plots are standard ways of drawing magnitude and phase response. The  $\omega$ -axis is on a logarithmic scale. Bode plots typically deal with real valued responses. Because of this, they only show the positive  $\omega$ -axis, since the negative one can be inferred by symmetry (same magnitude and opposite phase).



If  $20\log|H(j\omega)| > 0 \rightarrow$  The signal is amplified

If  $20\log|H(j\omega)| < 0 \rightarrow$  The signal is attenuated



### First Order System

$$\tau \frac{dy}{dt} + y(t) = x(t)$$

$$\tau j\omega Y(j\omega) + Y(j\omega) = X(j\omega)$$

$$(1 + \tau j\omega)Y(j\omega) = X(j\omega)$$

$$H(j\omega) = \frac{Y(j\omega)}{X(j\omega)} = \frac{1}{1 + \tau j\omega}$$

$$\text{At } \omega=0, H(j\omega)=1$$

$$20\log 1 = 0$$

$$\omega = \frac{1}{\tau}$$

$$H(j\omega) = \frac{1}{1 + \tau j \frac{1}{\tau}} = \frac{1}{1 + j}$$

$$\left| \frac{1}{1 + j} \right| = \frac{1}{\sqrt{2}}$$

$$\omega = \frac{10}{\tau}$$

$$H(j\omega) = \frac{1}{1+10} \rightarrow \text{the imaginary term dominates}$$

$$H(j\omega) \approx \frac{1}{10}$$

$$20\log(1/10) = -20$$

$$\omega = \frac{100}{\tau}$$

$$H(j\omega) = \frac{1}{1+100} \rightarrow \text{the imaginary term dominates}$$

$$H(j\omega) \approx \frac{1}{100}$$

$$\text{At } \omega = \frac{1}{\tau}$$

$$\angle H(j\omega) = -\frac{\pi}{4}$$

$$\text{If } \tau \text{ is big, } \angle H(j\omega) \approx -\frac{\pi}{2}$$

For 2<sup>nd</sup>, 3<sup>rd</sup> order systems perform a partial fraction expansion to get in the form of:

$$\left( \frac{1}{1 + \tau_1 j\omega} \right) \left( \frac{1}{1 + \tau_2 j\omega} \right) \dots$$

Multiplying magnitudes and adding phase.