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# Heap Data Structure

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# Outlines

- Heap
- Max/Min Heap
- Operations on Heap
- Build Heap
- Complexity Analysis of Heap
- Binomial Heap
- Fibonacci Heap
- Applications of Heap
  - Heap Sort
  - Priority Queue
  - Event-Driven Simulation

# Heap Data Structure

- Heap: A special form of complete binary tree that key value of each node is no smaller (larger) than the key value of its children (if any).
- Heaps are based on the notion of a complete tree
- A binary tree is **completely full** if it is of height, *h*, and has  $2^{h+1}$ -1 nodes.

# **Complete Binary Tree**

- A binary tree of height, *h*, is complete *iff*:
  ➢ it is empty *OR*
  - > its left subtree is complete of height h-1 and its right subtree is completely full of height h-2 or
  - > its left subtree is completely full of height h-1and its right subtree is complete of height h-1.
- A complete tree is filled from the left

### A complete binary tree in nature



## Binary tree in Computing



## Max/Min Tree

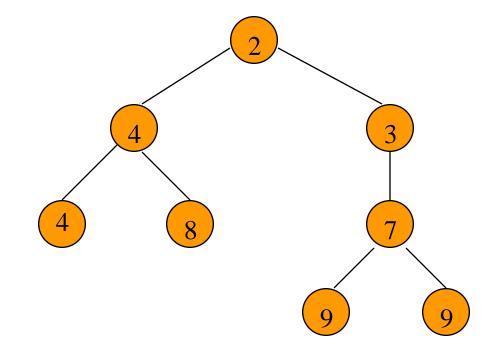
#### **Max-Tree:**

A *max tree* is a tree in which the key value in each node is no smaller than the key values in its children.

**Min-Tree:** 

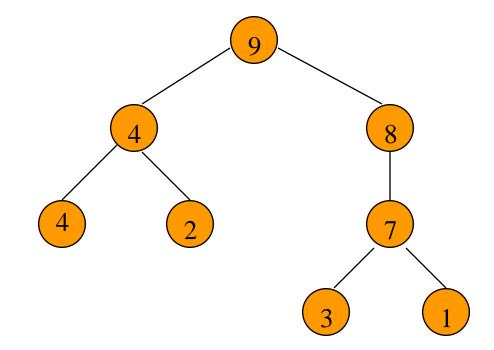
A *min tree* is a tree in which the key value in each node is no larger than the key values in its children.

### Min Tree Example



Root has minimum element.

### Max Tree Example



Root has maximum element.

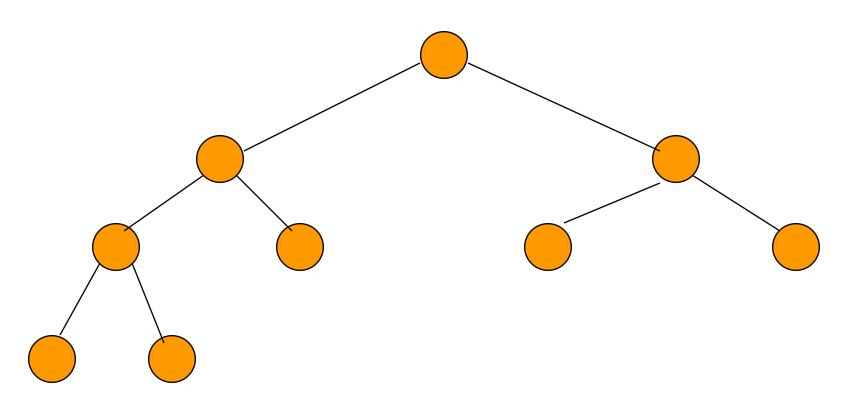
# Max/Min Heap

Max-Heap: root node has the largest key. A *max heap* is a complete binary tree that is also a max tree.

Min-Heap: root node has the smallest key.

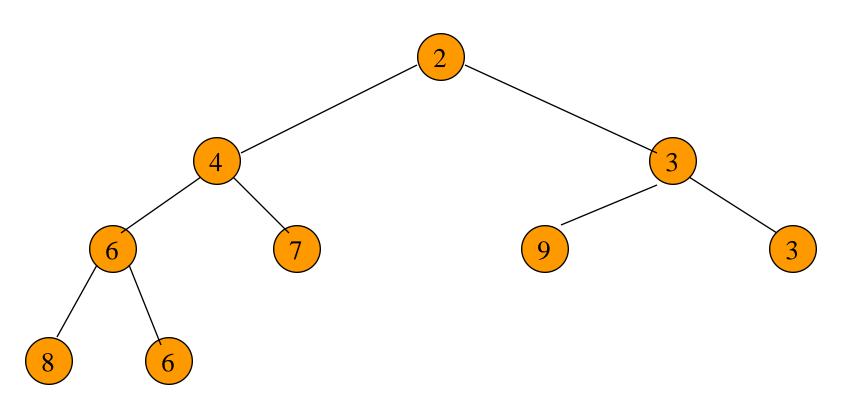
A *min heap* is a complete binary tree that is also a min tree.

# Min Heap With 9 Nodes



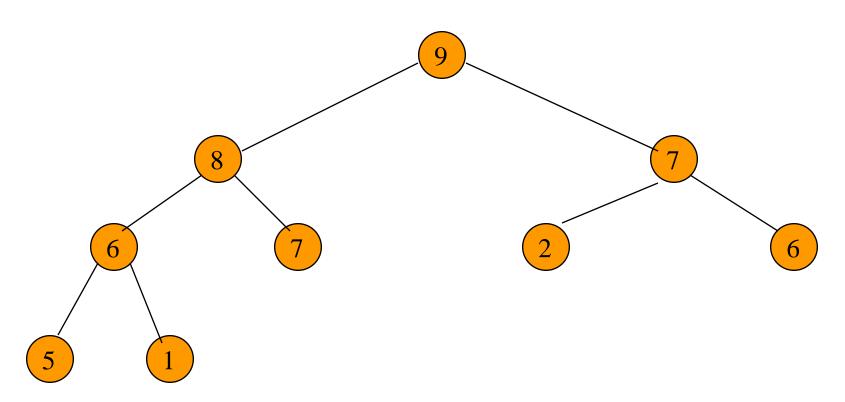
Complete binary tree with 9 nodes.

# Min Heap With 9 Nodes



Complete binary tree with 9 nodes that is also a min tree.

# Max Heap With 9 Nodes

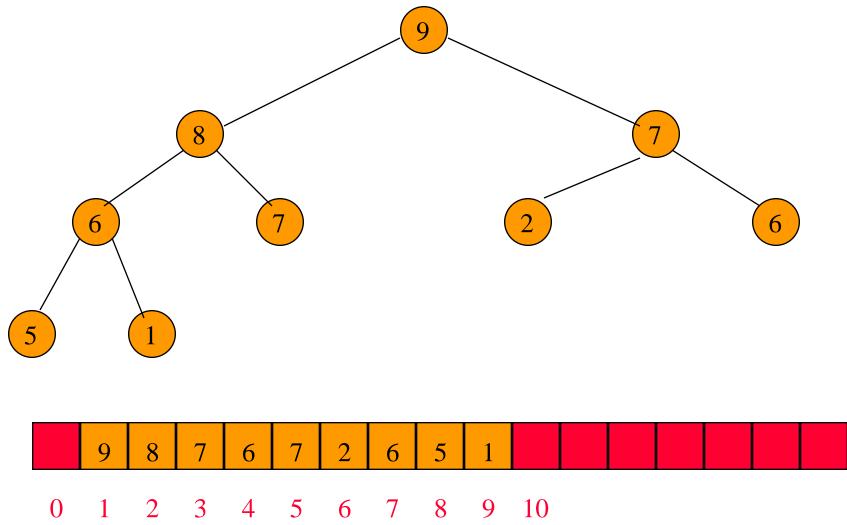


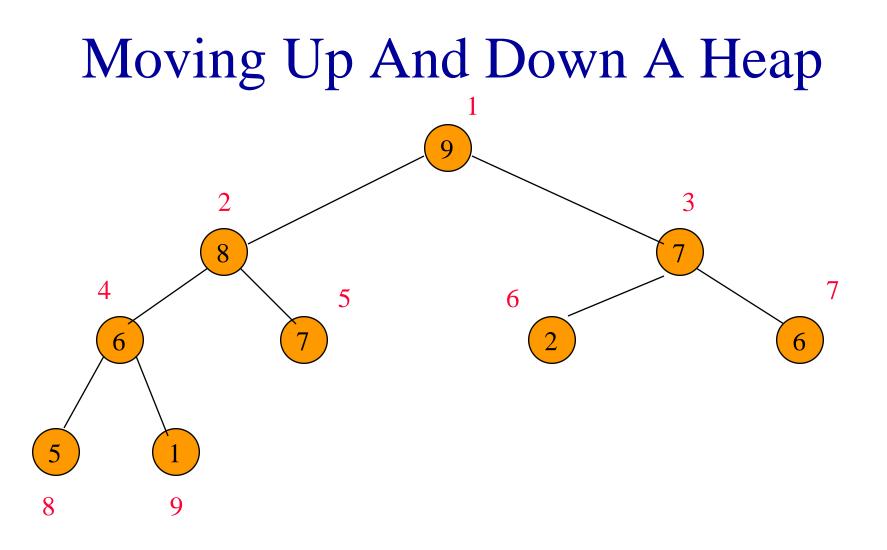
Complete binary tree with 9 nodes that is also a max tree.

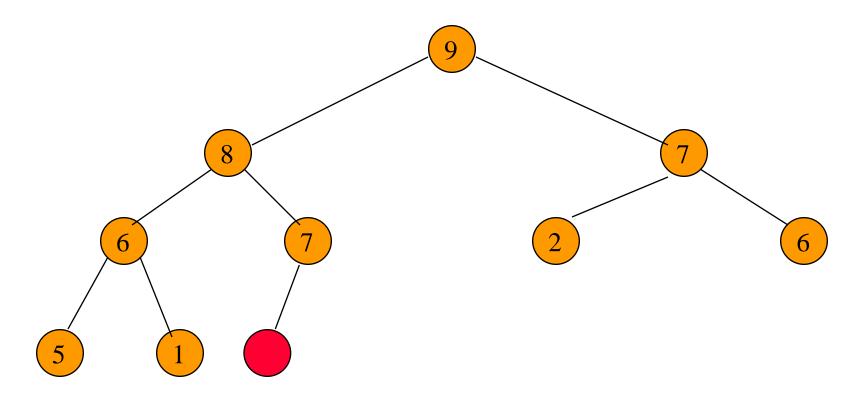
# Heap Height

Since a heap is a complete binary tree, the height of an n node heap is log<sub>2</sub> (n+1).

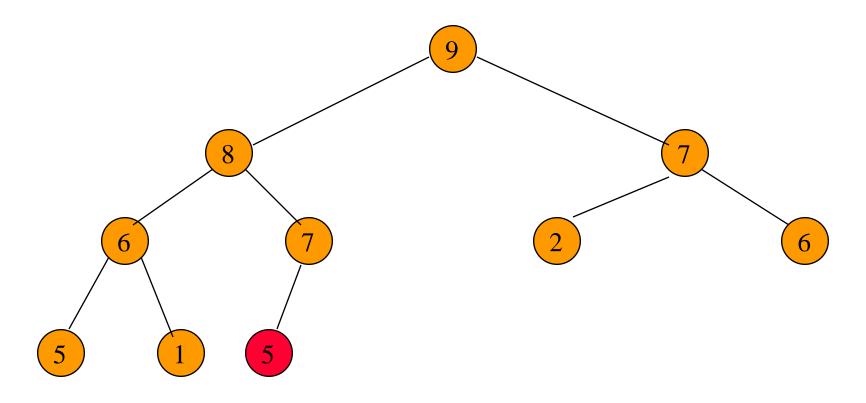
#### A Heap Is Efficiently Represented As An Array

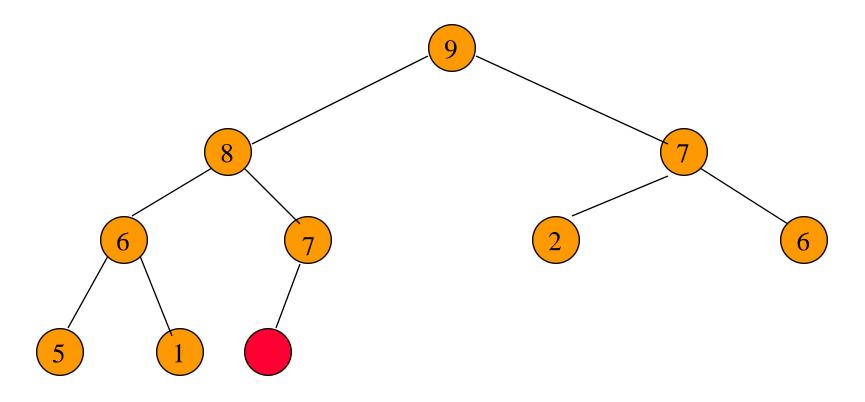


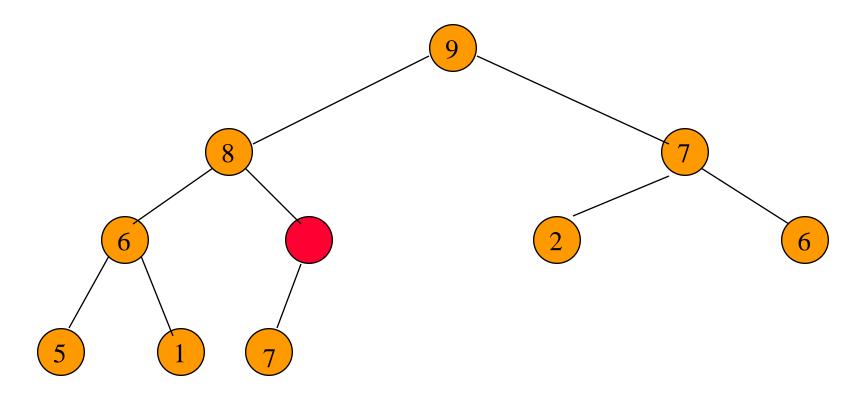


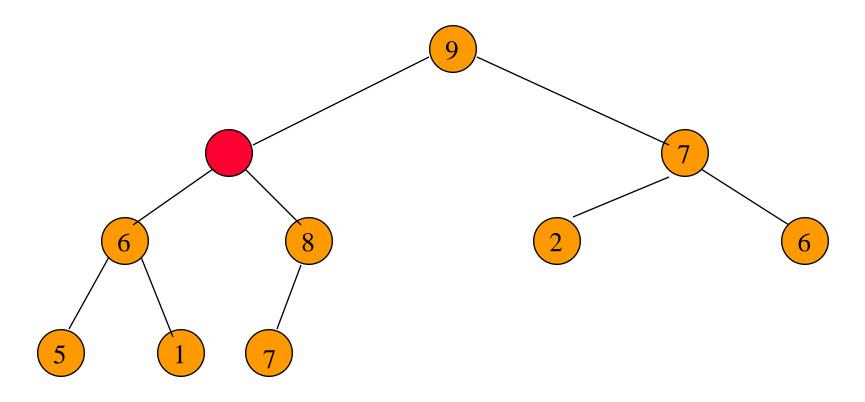


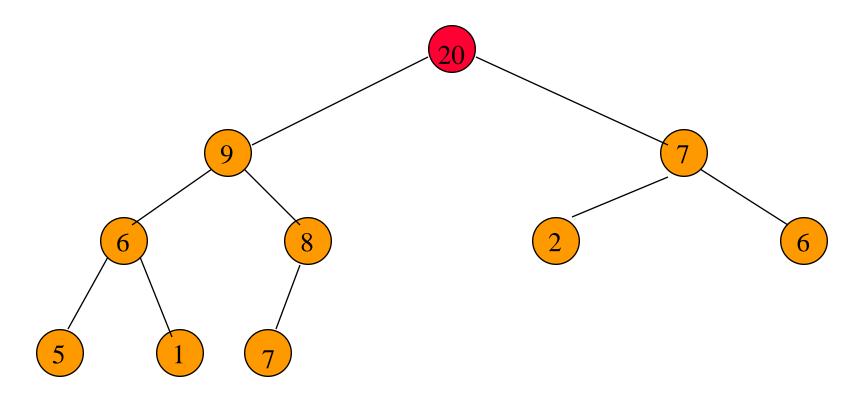
Complete binary tree with 10 nodes.

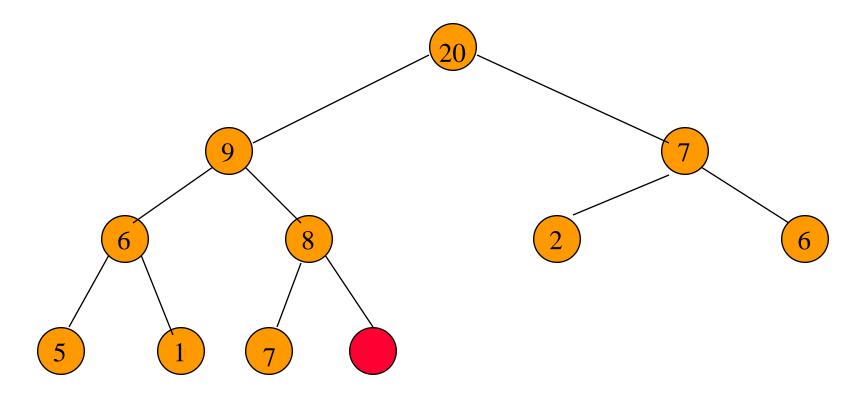




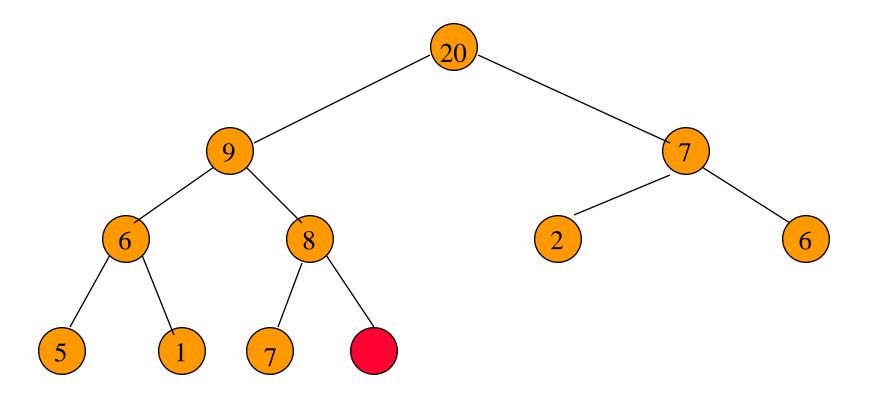




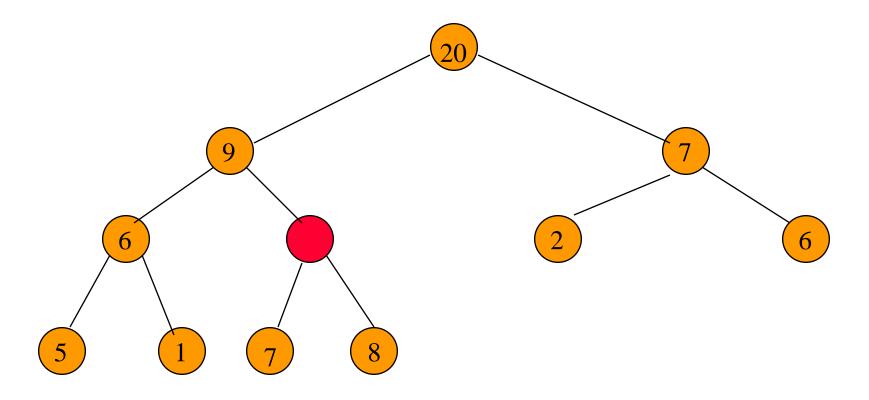




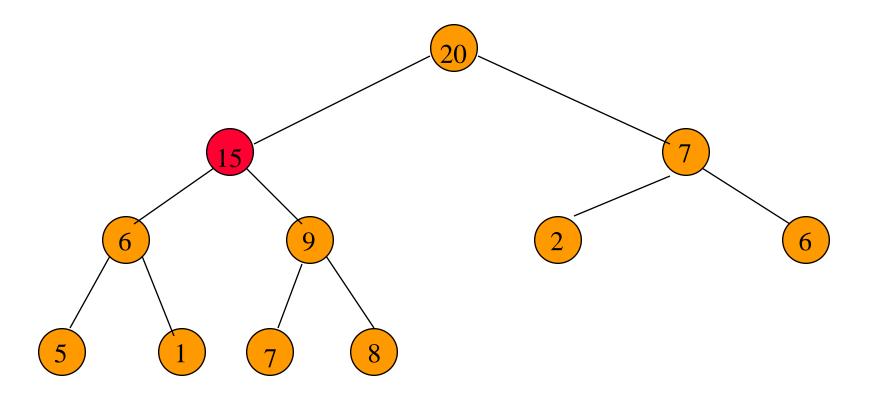
Complete binary tree with 11 nodes.



New element is 15.

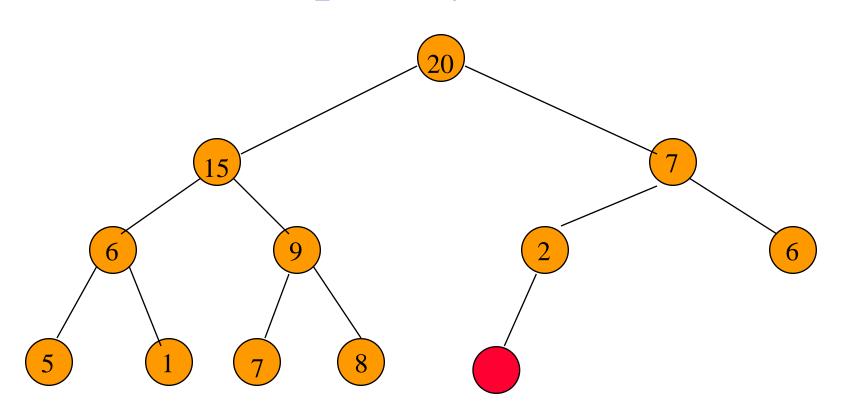


New element is 15.

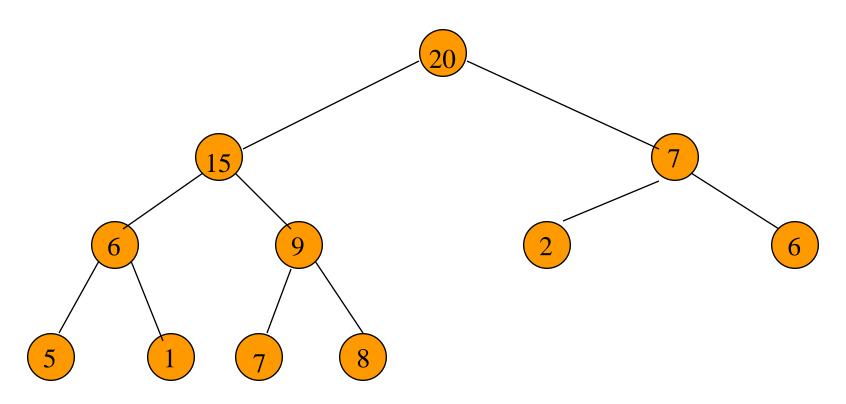


New element is 15.

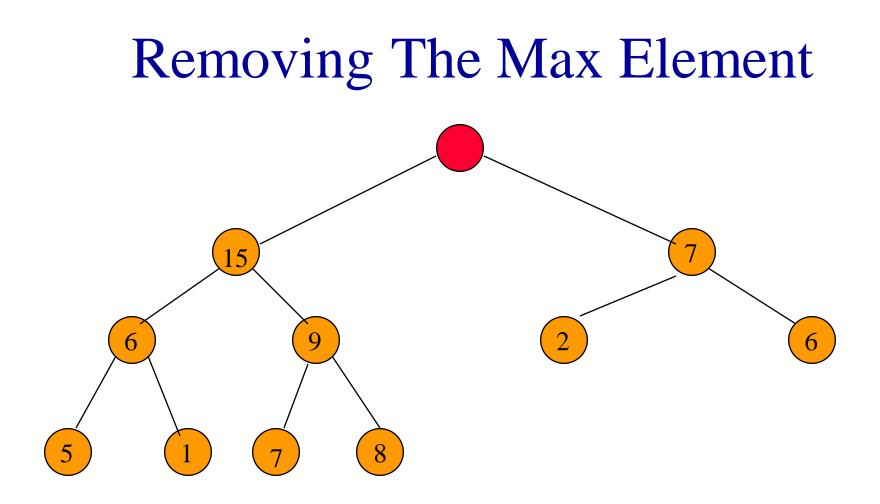
# **Complexity Of Insert**



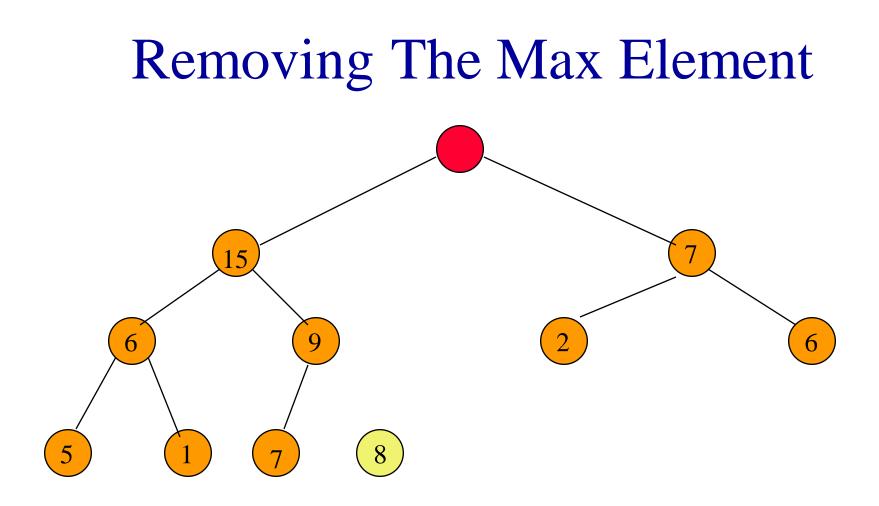
Complexity is O(log n), where n is heap size.



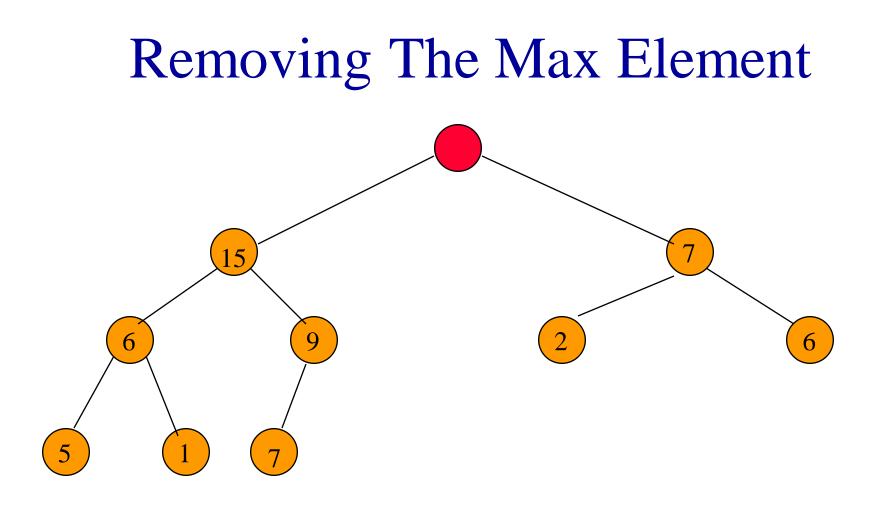
Max element is in the root.



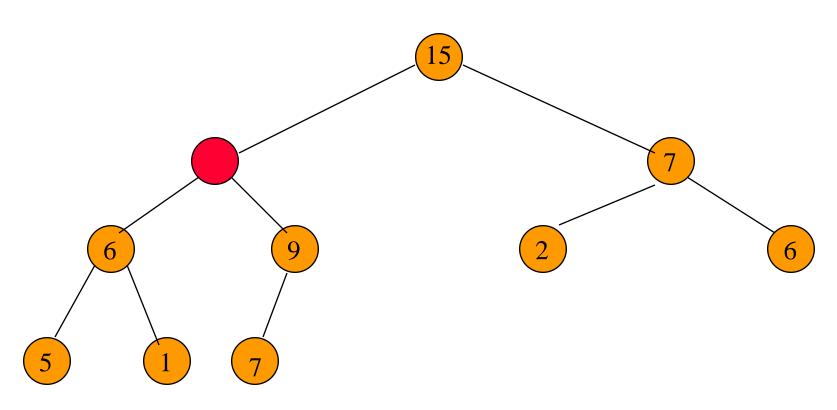
After max element is removed.



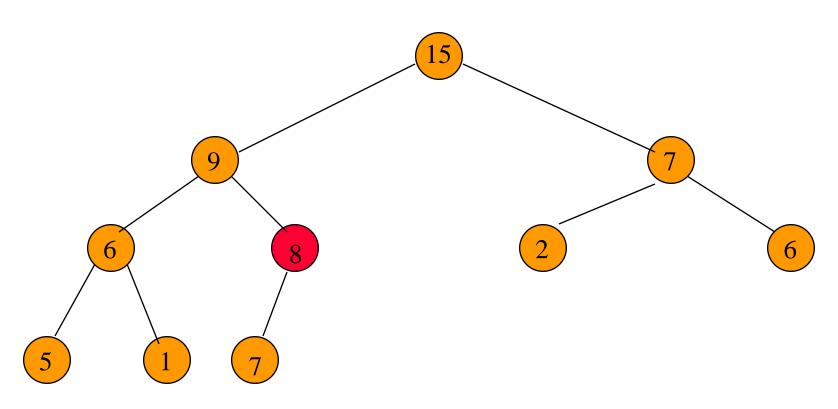
Heap with 10 nodes. Reinsert 8 into the heap.



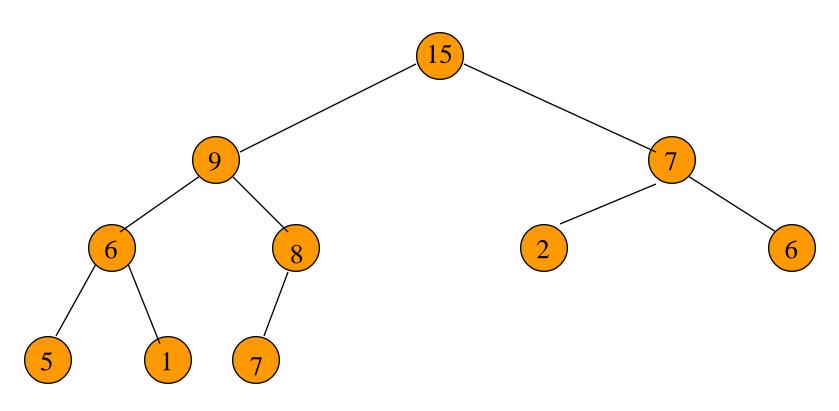
Reinsert 8 into the heap.



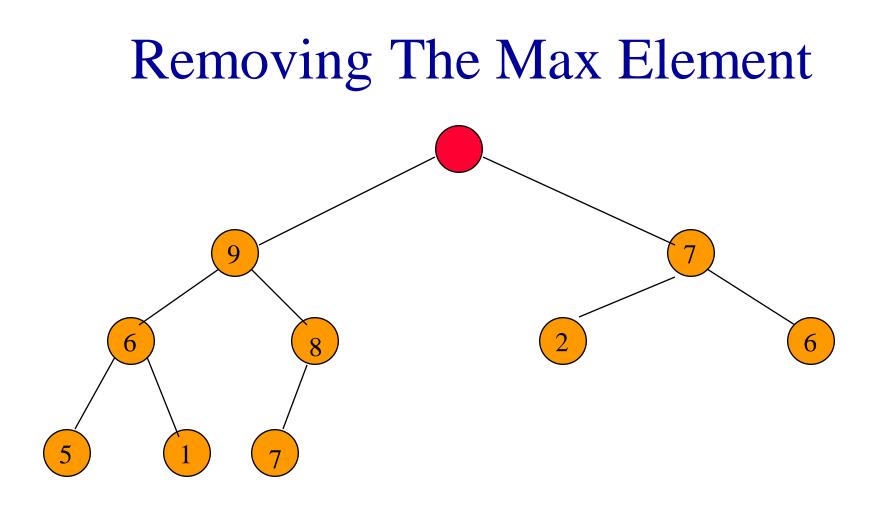
Reinsert 8 into the heap.



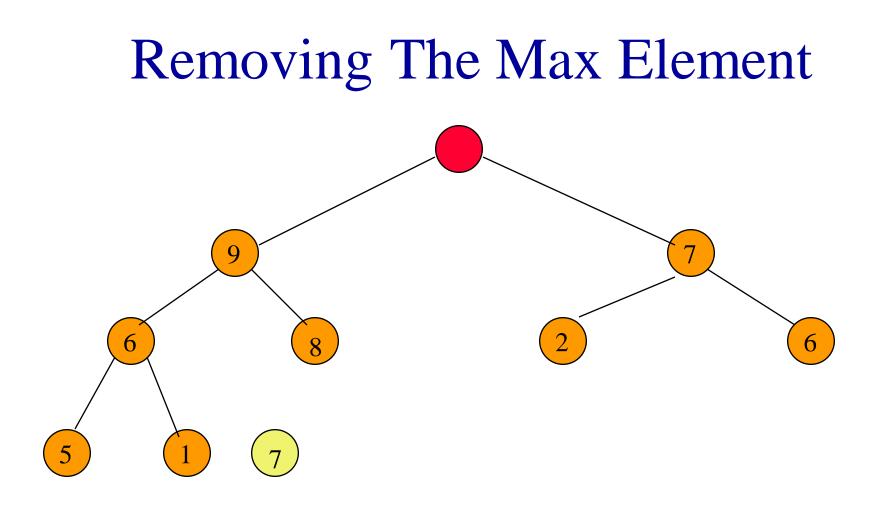
Reinsert 8 into the heap.



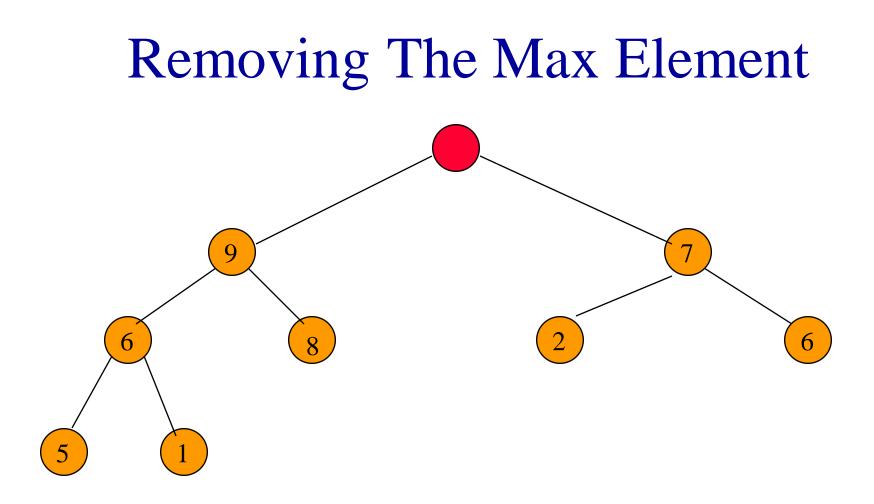
#### Max element is 15.



#### After max element is removed.

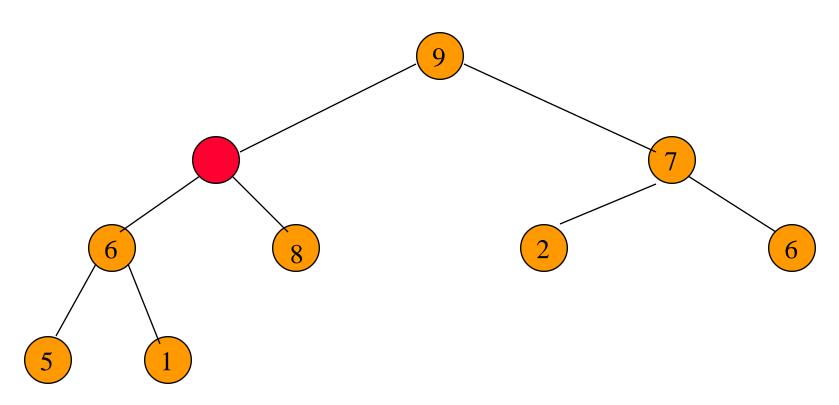


#### Heap with 9 nodes.



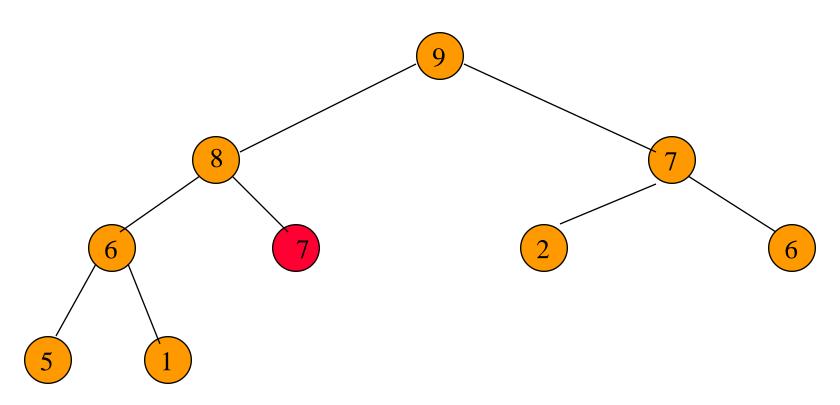
#### Reinsert 7.

### Removing The Max Element



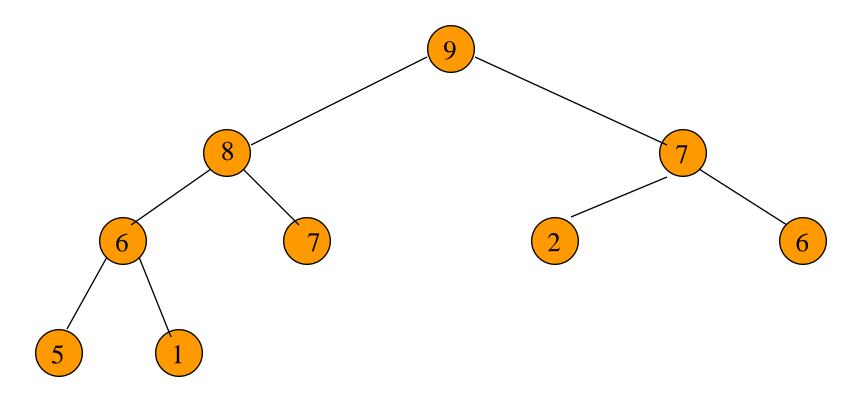
#### Reinsert 7.

### Removing The Max Element



#### Reinsert 7.

### Complexity Of Remove Max Element



#### Complexity is O(log n).

Construction, Insertion and Deletion of heap

• See <u>animation</u> of construction of heap

• See <u>animation</u> of insertion of heap

• See <u>animation</u> of deletion of heap

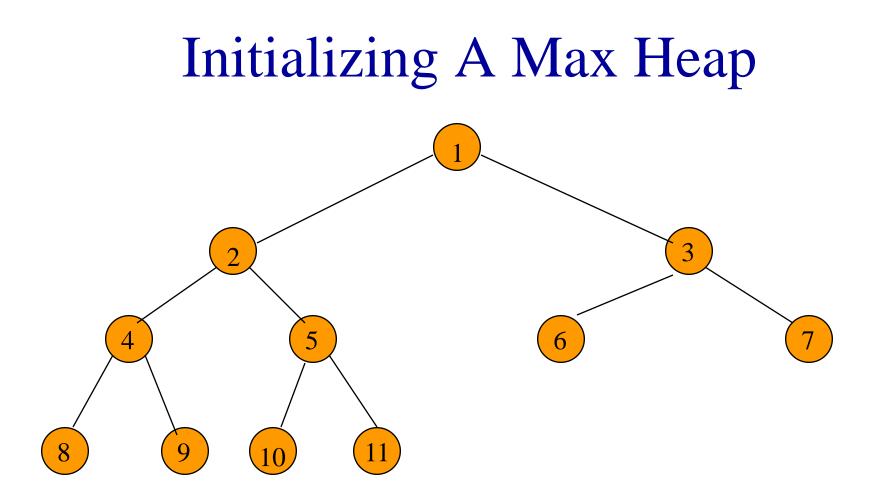
BUILD-MAX-HEAP(A)

 $1 \quad A.heap-size = A.length$ 

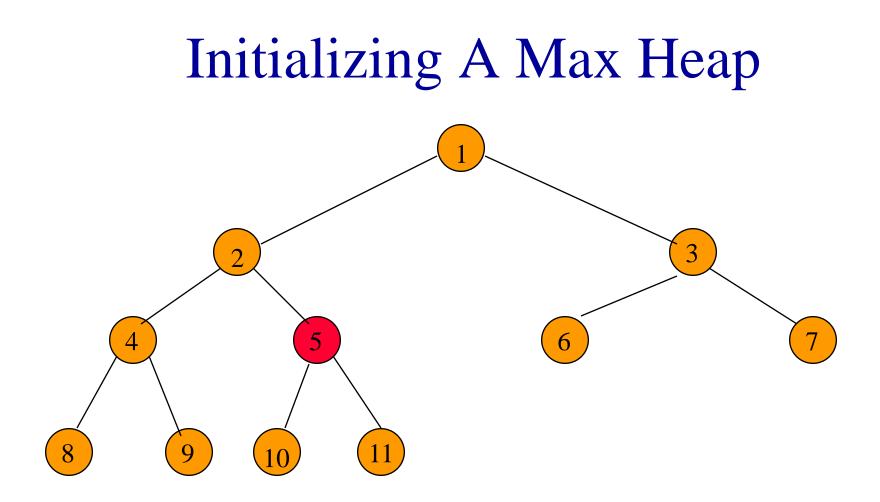
- 2 **for**  $i = \lfloor A \cdot length/2 \rfloor$  **downto** 1
- 3 MAX-HEAPIFY(A, i)

MAX-HEAPIFY(A, i)

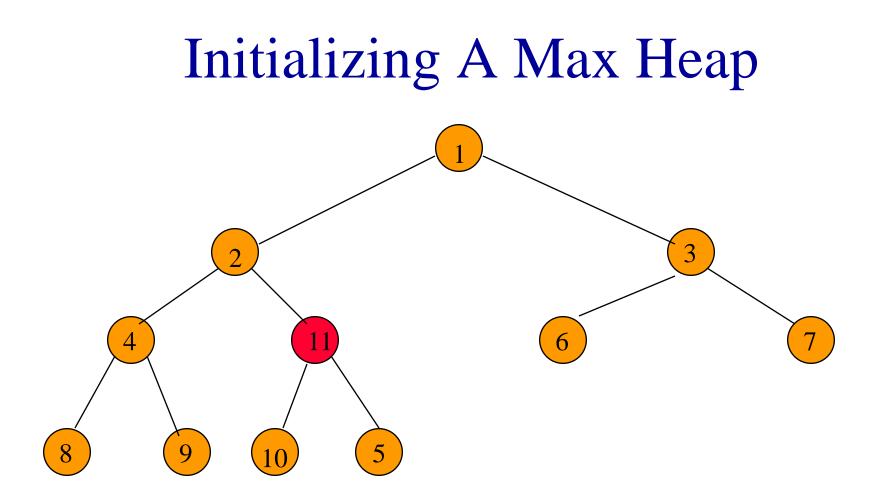
- 1 l = LEFT(i)2 r = RIGHT(i)3  $\text{if } l \leq A.heap\text{-size and } A[l] > A[i]$ 4 largest = l5 else largest = i6  $\text{if } r \leq A.heap\text{-size and } A[r] > A[largest]$ 7 largest = r8  $\text{if } largest \neq i$ 9 exchange A[i] with A[largest]
- 10 MAX-HEAPIFY (A, largest)



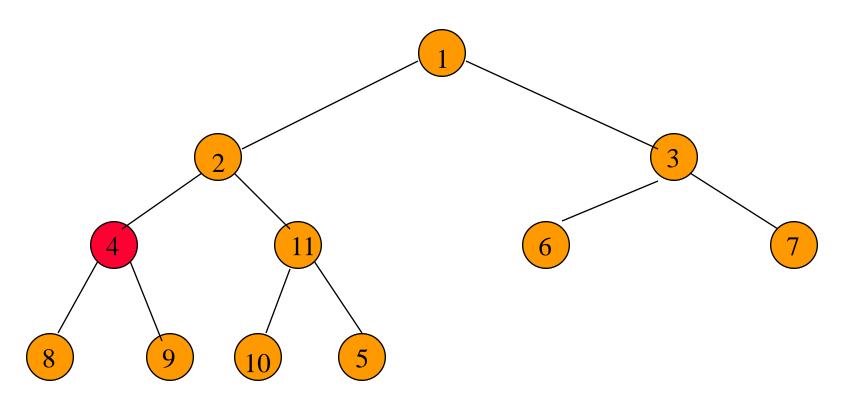
input array = [-, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11]

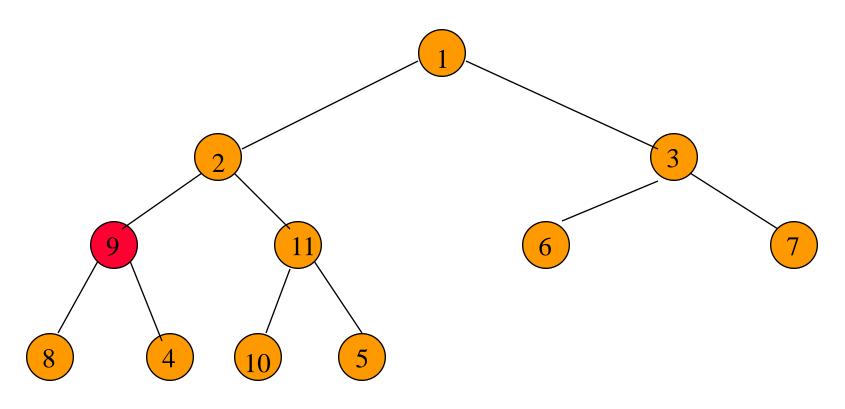


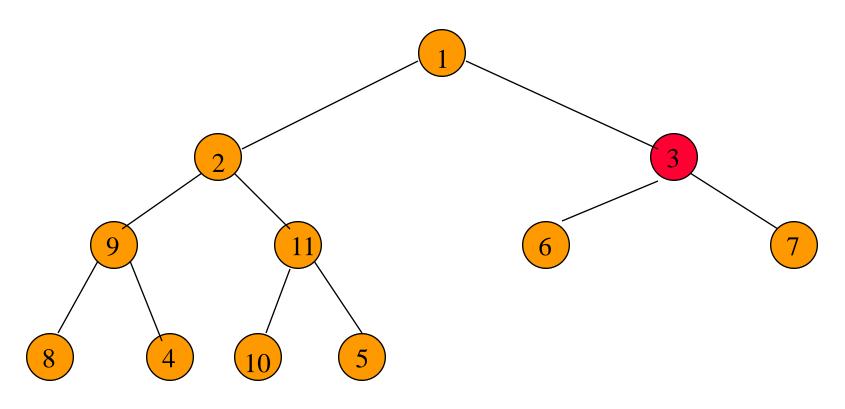
Start at rightmost array position that has a child. Index is n/2.

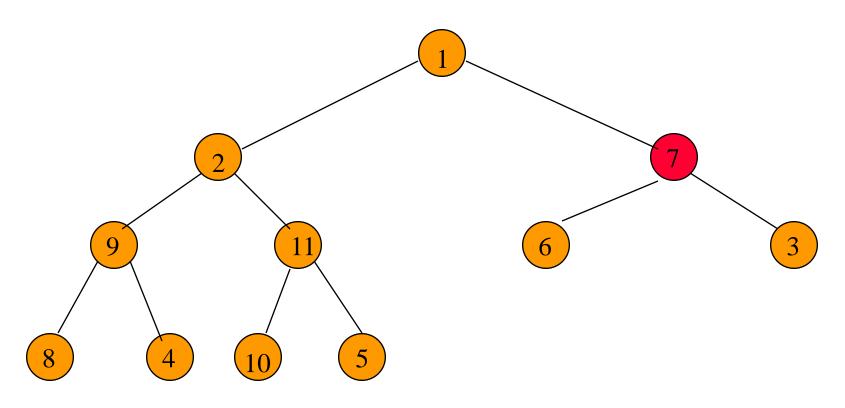


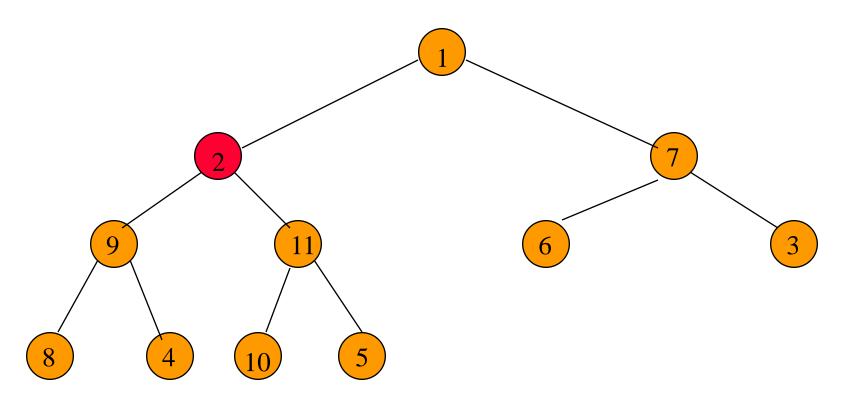
#### Move to next lower array position.





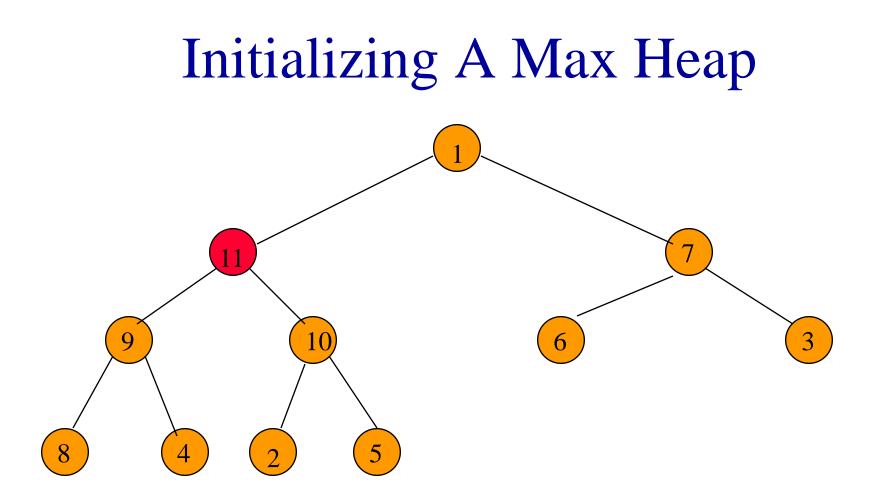




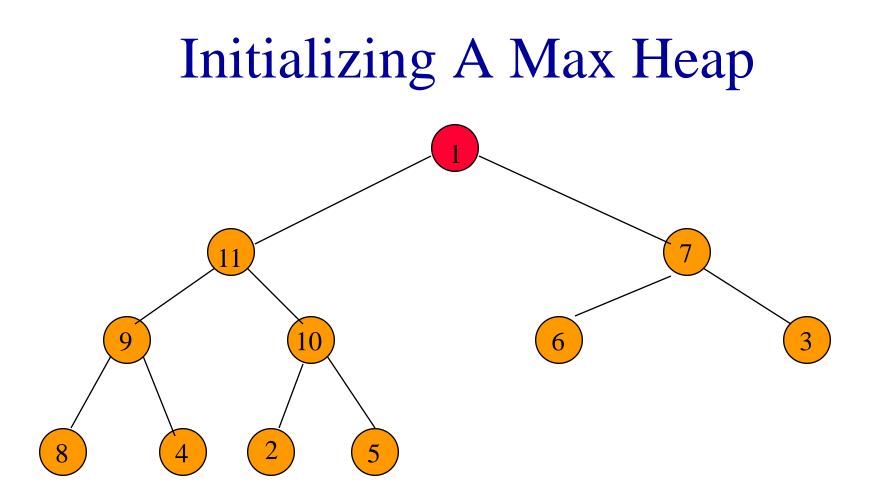


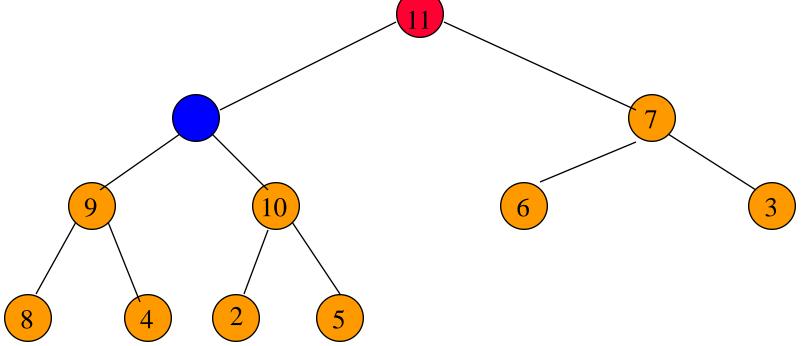
Find a home for 2.

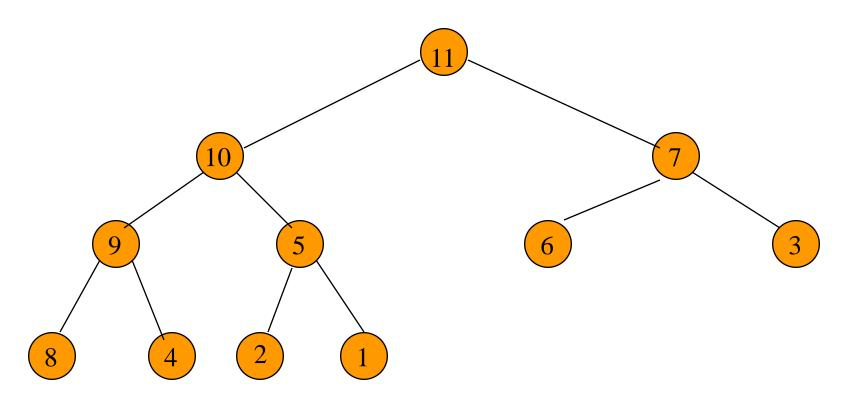
Find a home for 2.



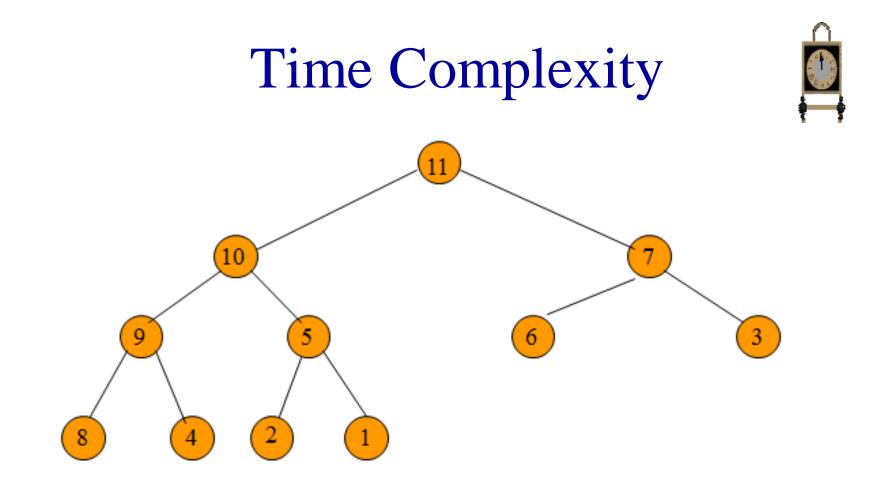
Done, move to next lower array position.







#### Done.



Cost of Max-Heapify (A, i) is O(log n)

Number of node/elements to be processed is n.

Total Time Complexity is **O(n log n)**.

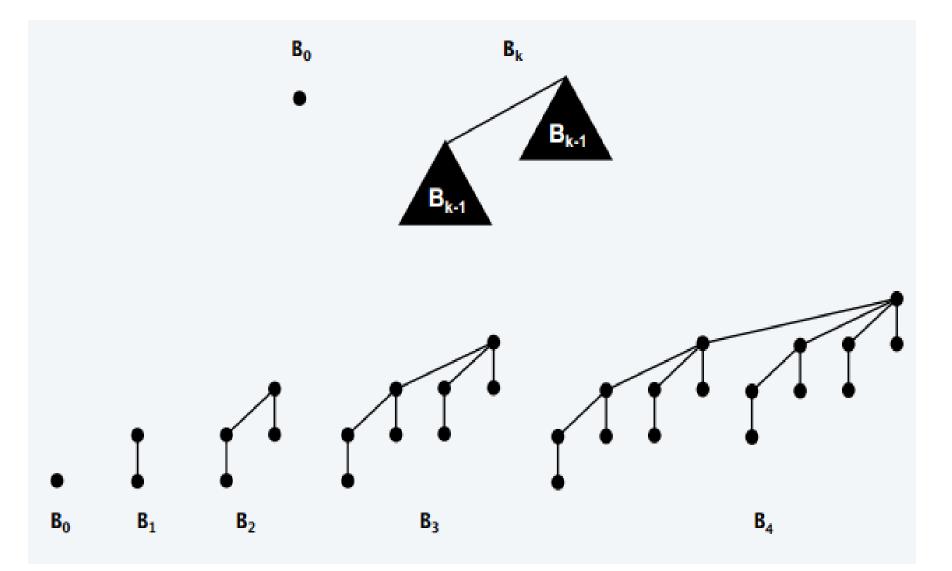
#### **BINOMIAL HEAPS**

### **Binomial Tree**

**Def.** A binomial tree of order k is defined recursively:

- Order 0: single node.
- Order k: one binomial tree of order k –1 linked to another of order k – 1.

#### **Binomial Tree**

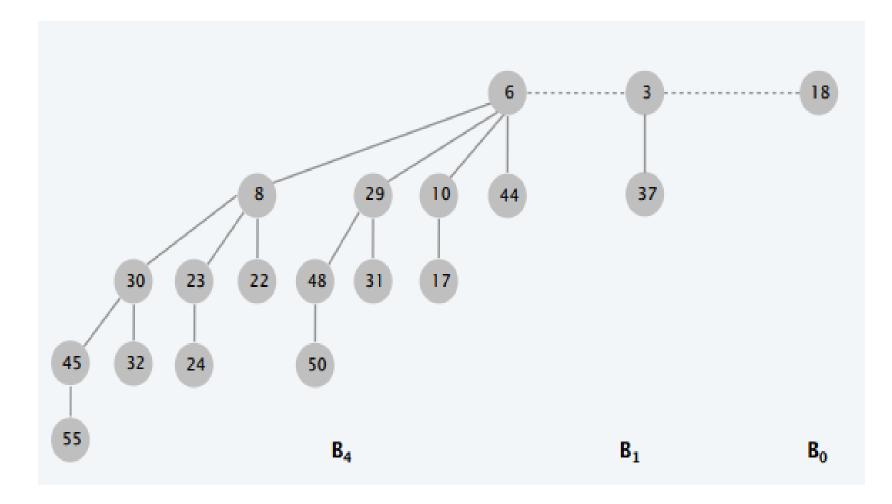


### **Binomial Heap**

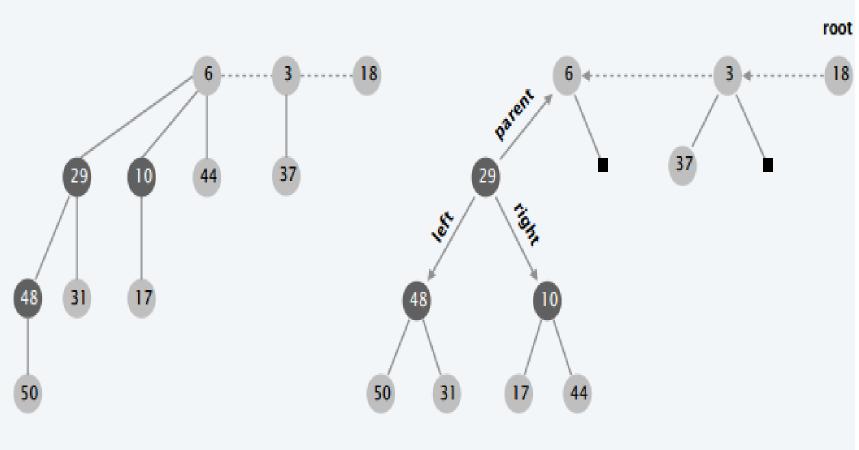
**Def**. A binomial heap is a sequence of binomial trees such that:

- Each tree is heap-ordered
- There is either 0 or 1 binomial tree of order k

### **Binomial Heap**



### **Binomial Heap**



binomial heap

#### leftist power-of-2 heap representation

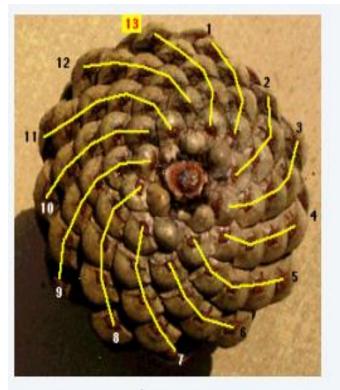
#### FIBONACCI HEAPS

### Fibonacci Heap

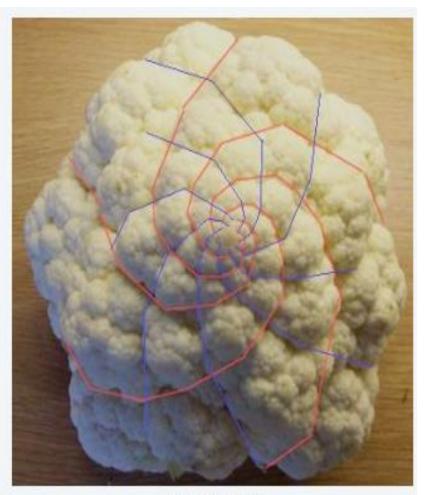
#### Basic Idea

- Similar to binomial heaps, but less rigid structure
- **Binomial heap:** eagerly consolidate trees after each INSERT; implement DECREASE-KEY by repeatedly exchanging node with its parent

### FIBONACCI HEAPS IN NATURE



pinecone



cauliflower

## Application of Heap

#### Sorting(Heap Sort)

#### Priority Queues

- Event-driven simulation.
- Numerical computation.
- Data compression.
- Graph searching.
- Number theory.
- Artificial intelligence.
- Statistics.
- Operating systems.
- Discrete optimization.
- Spam filtering.

[customers in a line, colliding particles] [reducing roundoff error] [Huffman codes] [Dijkstra's algorithm, Prim's algorithm] [sum of powers] [A\* search] [maintain largest M values in a sequence] [load balancing, interrupt handling] [bin packing, scheduling] [Bayesian spam filter]

### Heap Sort

• Algorithm for Heap Sort

HEAPSORT(A)

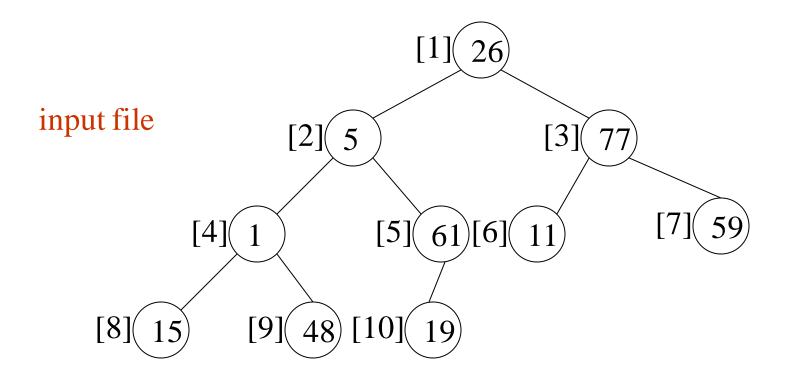
- 1 BUILD-MAX-HEAP(A)
- 2 **for** i = A. length **downto** 2
- 3 exchange A[1] with A[i]
- 4 A.heap-size = A.heap-size 1
- 5 MAX-HEAPIFY(A, 1)
- Time Complexity is **O(n log n)**.

#### Heap Sort

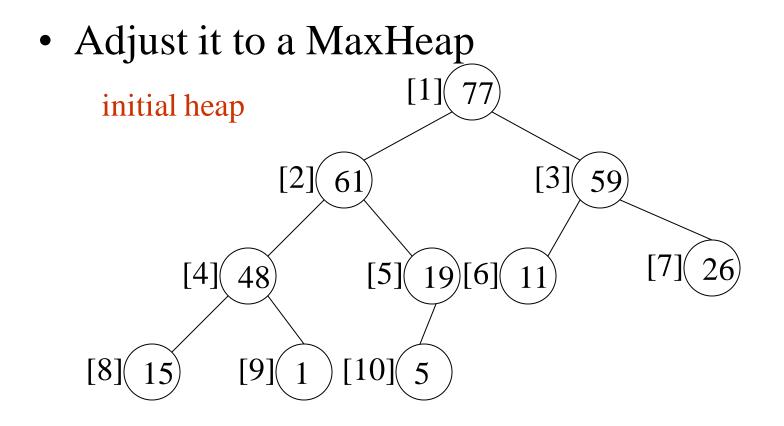
• Array interpreted as a binary tree

 1
 2
 3
 4
 5
 6
 7
 8
 9
 10

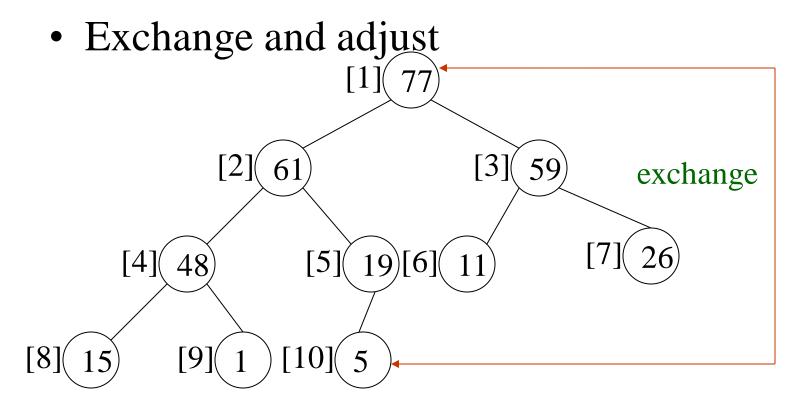
 26
 5
 77
 1
 61
 11
 59
 15
 48
 19

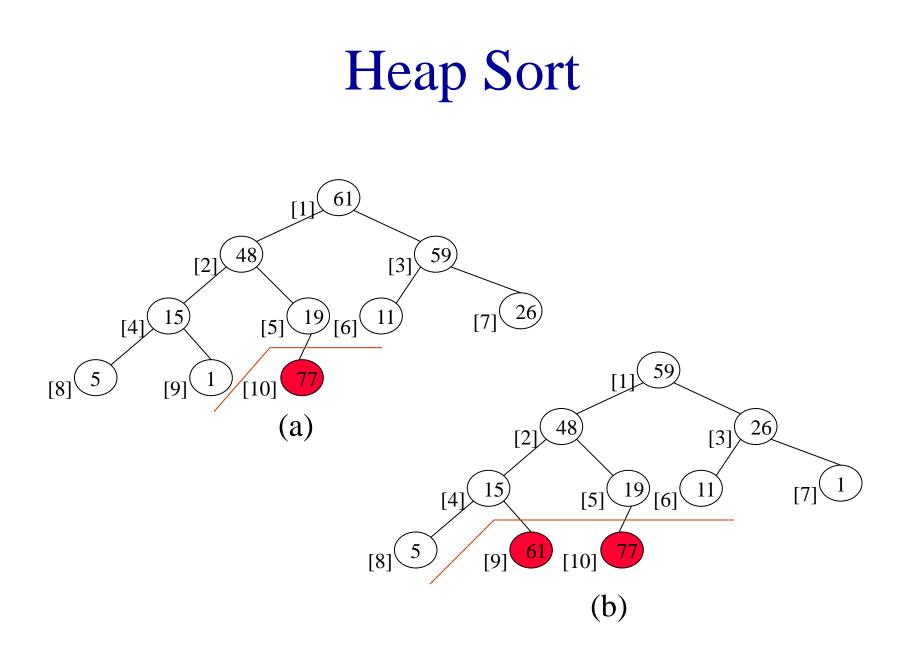


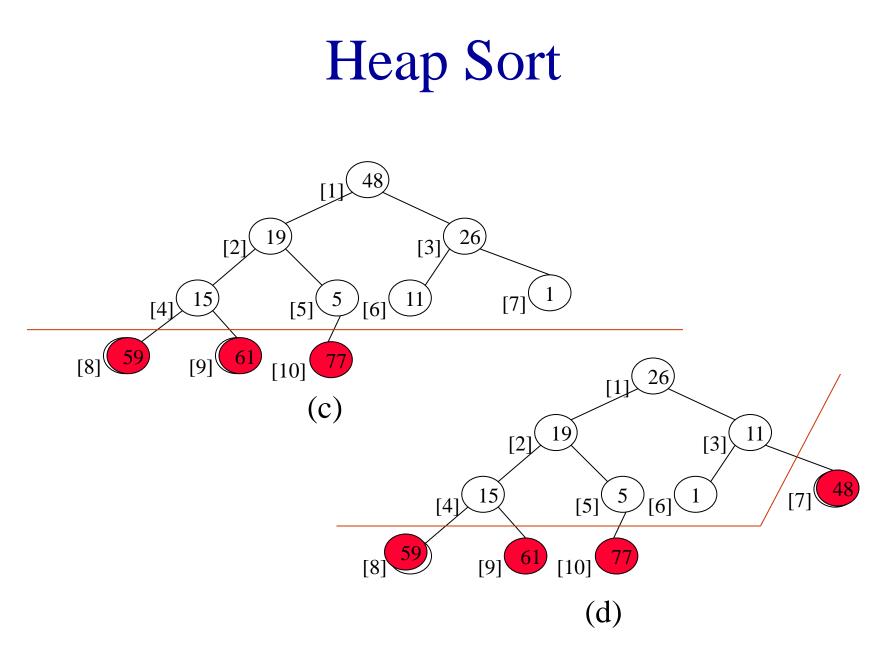
### Heap Sort

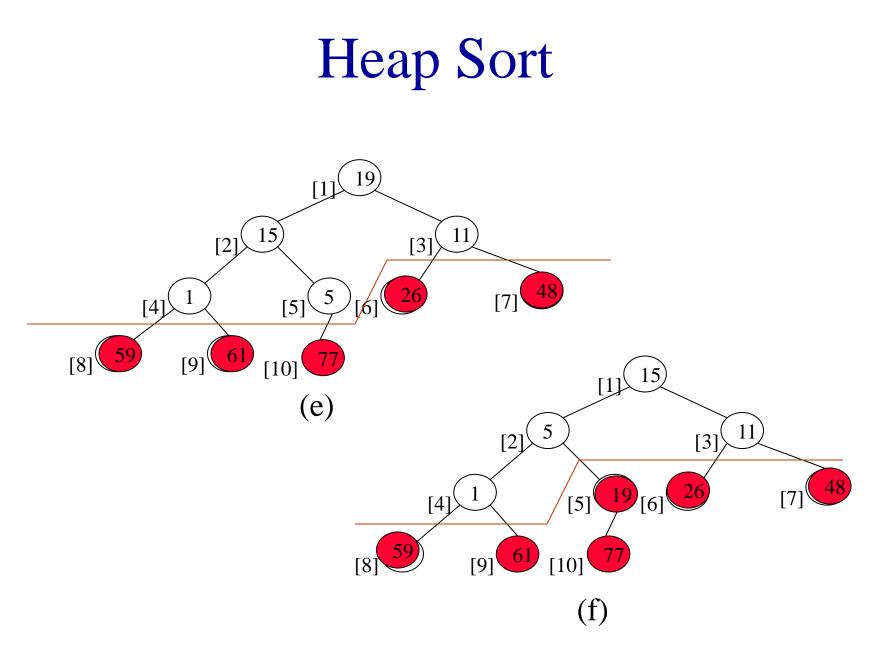


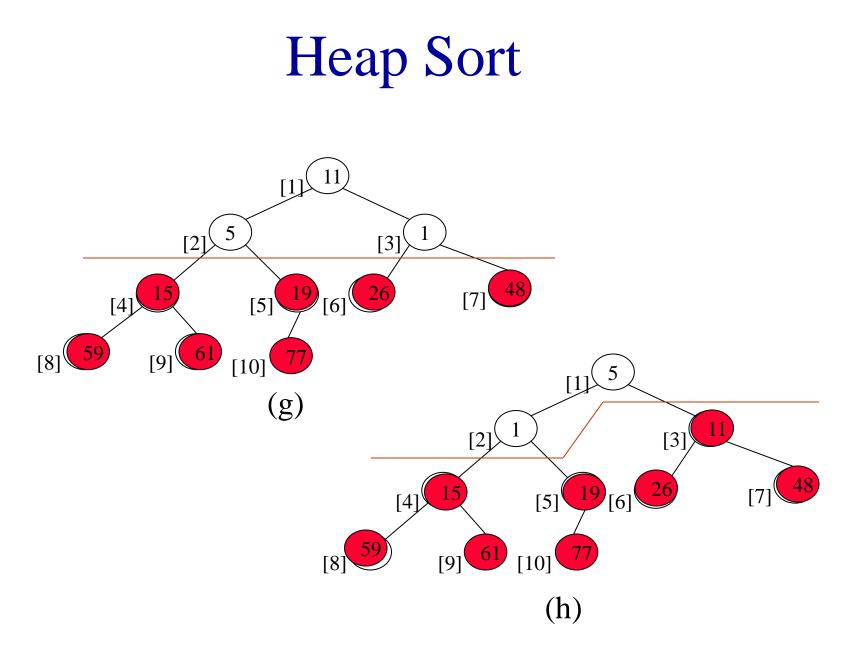
#### Heap Sort

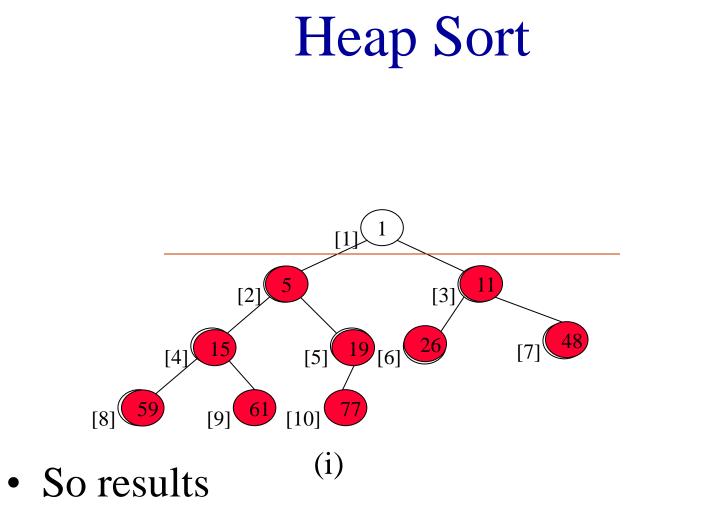












#### 77 61 59 48 26 19 15 11 5 1

## Priority Queue

- A priority queue is a data structure for maintaining a set S of elements, each with an associated value called a key.
- Two kinds of priority queues:
  - Min priority queue
  - Max priority queue

# Min Priority Queue

- Collection of elements.
- Each element has a priority or key.
- Supports following operations:
  - empty
  - size
  - insert an element into the priority queue (push)
  - get element with min priority (top)
  - remove element with min priority (pop)

# Max Priority Queue

- Collection of elements.
- Each element has a priority or key.
- Supports following operations:
  - empty
  - size
  - insert an element into the priority queue (push)
  - get element with max priority (top)
  - remove element with max priority (pop)

### Priority Queue

- Algorithm for Priority Queue HEAP-EXTRACT-MAX(A)
  - 1 if A.heap-size < 1
  - 2 error "heap underflow"
  - 3 max = A[1]
  - $4 \quad A[1] = A[A.heap-size]$
  - 5 A.heap-size = A.heap-size 1
  - 6 MAX-HEAPIFY(A, 1)
  - 7 return max

### **Complexity Of Operations**

Using a heap:

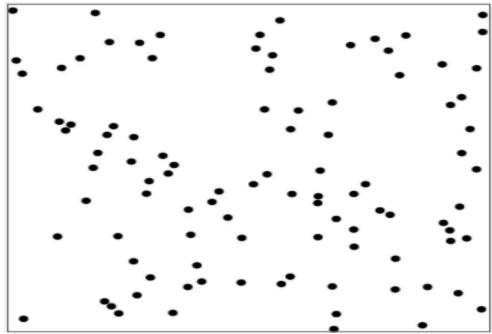
- empty, size, and top  $\Rightarrow O(1)$  time
- insert (push) and remove (pop) =>
   O(log n) time where n is the size of the priority queue

# Priority Queue

- Use max-priority queues to schedule jobs on a shared computer
- The max-priority queue keeps track of the jobs to be performed and their relative priorities
- When a job is finished or interrupted, the scheduler selects the highest-priority job from among those pending by calling EXTRACT-MAX
- The scheduler can add a new job to the queue at any time by calling INSERT

#### **Event-Driven Simulation**

• Goal: Simulate the motion of N moving particles that behave according to the laws of elastic collision.



#### **Event-Driven Simulation**

Significance: Relates macroscopic observables to microscopic dynamics

- Maxwell-Boltzmann: distribution of speeds as a function of temperature.
- Einstein: explain Brownian motion of pollen grains

## Over-All Analysis of Heap

operation	linked list	binary heap	binomial heap	Fibonacci heap †
ΜΑΚΕ-ΗΕΑΡ	<i>O</i> (1)	<i>O</i> (1)	<i>O</i> (1)	<i>O</i> (1)
IS-EMPTY	<i>O</i> (1)	<i>O</i> (1)	<i>O</i> (1)	<i>O</i> (1)
INSERT	<i>O</i> (1)	$O(\log n)$	$O(\log n)$	<i>O</i> (1)
EXTRACT-MIN	O(n)	$O(\log n)$	$O(\log n)$	$O(\log n)$
DECREASE-KEY	<i>O</i> (1)	$O(\log n)$	$O(\log n)$	<i>O</i> (1)
DELETE	<i>O</i> (1)	$O(\log n)$	$O(\log n)$	$O(\log n)$
Meld	<i>O</i> (1)	O(n)	$O(\log n)$	<i>O</i> (1)
Find-Min	O(n)	<i>O</i> (1)	$O(\log n)$	<i>O</i> (1)

#### Some More Food

#### Heaps of heaps

- b-heaps.
- Fat heaps.
- 2-3 heaps.
- Leaf heaps.
- Thin heaps.
- Skew heaps.
- Splay heaps.
- Weak heaps.
- Leftist heaps.
- Quake heaps.
- · Pairing heaps.
- Violation heaps.
- Run-relaxed heaps.
- Rank-pairing heaps.
- Skew-pairing heaps.
- Rank-relaxed heaps.
- Lazy Fibonacci heaps.

