

QP Solution to Hard SVM

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We can present SVM as the following optimization problem

$$\max \quad \rho = \frac{2}{\|\mathbf{w}\|}$$
s.t.
$$\mathbf{w}^T \mathbf{x}^{(i)} + b \le -1, \qquad \forall i \text{ s.t. } y_i = -1$$

$$\mathbf{w}^T \mathbf{x}^{(i)} + b \ge +1, \qquad \forall i \text{ s.t. } y_i = +1$$
OR
$$\min \quad \rho = \frac{1}{2} \mathbf{w}^T \mathbf{w}$$
s.t.
$$y_i \left(\mathbf{w}^T \mathbf{x}^{(i)} + b \right) \ge +1$$

 Combining the objective function and the constraints (represented as losses) as follows

$$\min_{\mathbf{w},b} \qquad M = \frac{1}{2} \mathbf{w}^T \mathbf{w} + \sum_{i=1}^{N} L_i$$

Produces a large +ive value when the ith constraint is violated

The constraint cost function can be written as

$$L_i = \max_{\alpha_i} \quad \alpha_i \left\{ 1 - y_i \left(\mathbf{w}^T \mathbf{x}^{(i)} + b \right) \right\} = \begin{bmatrix} 0 & 1 - y_i \left(\mathbf{w}^T \mathbf{x}^{(i)} + b \right) \leq 0 \\ & else \end{bmatrix}$$

$$\alpha_i \geq 0$$
When the constraint is being strictly satisfied, α_i must be constraint is being violated

zero

Combining

Let
$$P = \min_{\mathbf{w},b} \left\{ \frac{1}{2} \mathbf{w}^T \mathbf{w} + \sum_{i=1}^{N} \left[\max_{\alpha_i \ge 0} \alpha_i \left\{ 1 - y_i \left(\mathbf{w}^T \mathbf{x}^{(i)} + b \right) \right\} \right] \right\}$$
$$= \min_{\mathbf{w},b} \max_{\alpha_i \ge 0} \left\{ \frac{1}{2} \mathbf{w}^T \mathbf{w} + \sum_{i=1}^{N} \left[\alpha_i \left\{ 1 - y_i \left(\mathbf{w}^T \mathbf{x}^{(i)} + b \right) \right\} \right] \right\}$$

This is the Lagrangian (α_i are the Lagrange Multipliers)

- This is called the primal form of the optimization problem
- The corresponding dual can be written as

$$Let \qquad D = \max_{\alpha_i \ge 0} \min_{\mathbf{w}, b} \left\{ \frac{1}{2} \mathbf{w}^T \mathbf{w} + \sum_{i=1}^{N} \left[\alpha_i \left\{ 1 - y_i \left(\mathbf{w}^T \mathbf{x}^{(i)} + b \right) \right\} \right] \right\}$$

- Since the optimization is convex therefore if the Karush-Kuhn-Tucker conditions are satisfied then the primal and dual optimal values will be equal
- In simple words the optimization problem in SVM can be interpreted as

$$\max_{\alpha_i \ge 0} \min_{\mathbf{w}, b} \left\{ \frac{1}{2} \mathbf{w}^T \mathbf{w} + \sum_{i=1}^{N} \left[\alpha_i \left\{ 1 - y_i \left(\mathbf{w}^T \mathbf{x}^{(i)} + b \right) \right\} \right] \right\}$$
s.t. $\alpha_i \ge 0$

$$\max_{\alpha_{i} \geq 0} \min_{\mathbf{w}, b} \left\{ \frac{1}{2} \mathbf{w}^{T} \mathbf{w} + \sum_{i=1}^{N} \left[\alpha_{i} \left\{ 1 - y_{i} \left(\mathbf{w}^{T} \mathbf{x}^{(i)} + b \right) \right\} \right] \right\} = \max_{\alpha_{i} \geq 0} \left\{ \theta_{D} \left(\mathbf{w}, b \right) \right\}$$

s.t.
$$\alpha_i \geq 0$$

$$\theta_D(\mathbf{w},b) = \min_{\mathbf{w},b} \left\{ \frac{1}{2} \mathbf{w}^T \mathbf{w} + \sum_{i=1}^N \left[\alpha_i \left\{ 1 - y_i \left(\mathbf{w}^T \mathbf{x}^{(i)} + b \right) \right\} \right] \right\}$$
[1]

Finding the saddle point of $\theta_D(\mathbf{w},b)$

$$\frac{\partial \theta_{D}(\mathbf{w}, b)}{\partial \mathbf{w}} = \mathbf{w} + \sum_{i=1}^{N} \left[\alpha_{i} \left\{ -y_{i} \mathbf{x}^{(i)} \right\} \right] = 0 \qquad \Rightarrow \mathbf{w}^{*} = \sum_{i=1}^{N} \alpha_{i} y_{i} \mathbf{x}^{(i)}$$

$$\frac{\partial \theta_{D}(\mathbf{w}, b)}{\partial b} = -\sum_{i=1}^{N} \alpha_{i} y_{i} = 0 \qquad \Rightarrow \sum_{i=1}^{N} \alpha_{i} y_{i} = 0$$

Putting in [1]

$$\begin{split} &\theta_{D}\left(\mathbf{w}^{*},b^{*}\right) = \frac{1}{2}\mathbf{w}^{*T}\mathbf{w}^{*} + \sum_{i=1}^{N}\left[\alpha_{i}\left\{1 - y_{i}\left(\mathbf{w}^{*T}\mathbf{x}^{(i)} + b^{*}\right)\right\}\right] \\ &= \frac{1}{2}\left(\sum_{i=1}^{N}\alpha_{i}y_{i}\mathbf{x}^{(i)}\right)^{T}\left(\sum_{j=1}^{N}\alpha_{j}y_{j}\mathbf{x}^{(j)}\right) + \sum_{i=1}^{N}\left[\alpha_{i}\left\{1 - y_{i}\left(\sum_{j=1}^{N}\alpha_{j}y_{j}\mathbf{x}^{(j)}\right)^{T}\mathbf{x}^{(i)} + b^{*}\right)\right\}\right] \\ &= \frac{1}{2}\sum_{i=1}^{N}\sum_{j=1}^{N}\alpha_{i}y_{i}\mathbf{x}^{(i)^{T}}\alpha_{j}y_{j}\mathbf{x}^{(j)} + \sum_{i=1}^{N}\alpha_{i} - \sum_{i=1}^{N}\left[\alpha_{i}y_{i}\left(\sum_{j=1}^{N}\alpha_{j}y_{j}\mathbf{x}^{(j)}\right)^{T}\mathbf{x}^{(i)} + b^{*}\right] \\ &= \frac{1}{2}\sum_{i=1}^{N}\sum_{j=1}^{N}\alpha_{i}\alpha_{j}y_{i}y_{j}\mathbf{x}^{(i)^{T}}\mathbf{x}^{(j)} + \sum_{i=1}^{N}\alpha_{i} - \sum_{i=1}^{N}\sum_{j=1}^{N}\alpha_{i}\alpha_{j}y_{i}y_{j}\mathbf{x}^{(i)^{T}}\mathbf{x}^{(j)} + b^{*}\sum_{i=1}^{N}\alpha_{i}y_{i} \\ &= \sum_{i=1}^{N}\alpha_{i} - \frac{1}{2}\sum_{i=1}^{N}\sum_{j=1}^{N}\alpha_{i}\alpha_{j}y_{i}y_{j}\mathbf{x}^{(i)^{T}}\mathbf{x}^{(j)} \end{split}$$

Thus the problem can be written as

$$\max_{\alpha_{i} \ge 0} \left\{ \sum_{i=1}^{N} \alpha_{i} - \frac{1}{2} \sum_{i=1}^{N} \sum_{j=1}^{N} \alpha_{i} \alpha_{j} y_{i} y_{j} \mathbf{x}^{(i)^{T}} \mathbf{x}^{(j)} \right\}$$

$$s.t \qquad \alpha_{i} \ge 0$$

$$\sum_{i=1}^{N} \alpha_{i} y_{i} = 0$$

• This quadratic optimization problem can be solved for α_i using standard optimization packages

- The training points with their corresponding α_i greater than zero lie on the boundary and are thus called support vectors as they support the boundary
- Once α_i have been found, the weight can be calculated as

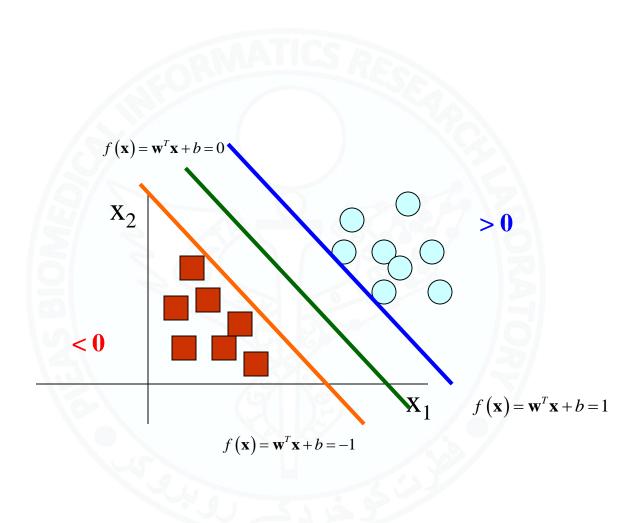
$$\mathbf{w}^* = \sum_{i=1}^{N} \alpha_i^* y_i \mathbf{x}^{(i)}$$

$$\mathbf{w}^* \mathbf{x} + b^* = y \implies b^* = y - \mathbf{w}^{*T} \mathbf{x}$$

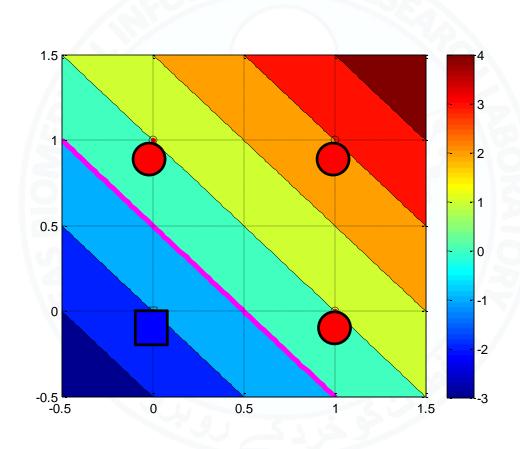
$$or \qquad b^* = \frac{1}{n_{SV}} \sum_{\alpha_i > 0} \left(y_i - \mathbf{w}^{*T} \mathbf{x}^{(i)} \right)$$
scification

- Classification
 - The label of an unknown point can be determined by

$$y = \operatorname{sgn}\left(w^{*^{T}} x + b^{*}\right)$$



Example problem



Matrix formulation of SVM Problem

$$\begin{aligned} & \max_{\alpha_i \ge 0} \left\{ \sum_{i=1}^N \alpha_i - \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \alpha_i \alpha_j y_i y_j \mathbf{x}^{(i)^T} \mathbf{x}^{(j)} \right\} \\ & s.t \qquad \alpha_i \ge 0 \\ & \qquad \sum_{i=1}^N \alpha_i y_i = 0 \end{aligned}$$

$$max_{\alpha} \mathbf{1}^{T} \boldsymbol{\alpha} - \frac{1}{2} \boldsymbol{\alpha}^{T} \mathbf{X}^{T} \mathbf{X} \boldsymbol{\alpha}$$

Subject to:
 $\boldsymbol{\alpha} \geq \mathbf{0}$
 $\mathbf{y}^{T} \boldsymbol{\alpha} = 0$

If we define the following:

$$-\alpha = [\alpha_{1} \quad \alpha_{2} \quad \dots \quad \alpha_{N}]^{T}$$

$$-y = [y_{1} \quad y_{2} \quad \dots \quad y_{N}]^{T}$$

$$-1_{N} = [1 \quad 1 \quad \dots \quad 1]^{T}$$

$$-X_{(d\times N)} = [x_{1}y_{1} \quad x_{2}y_{2} \quad \dots \quad x_{N}y_{N}]$$

Solving the SVM using QP

- CVXOPT is a Python package that implements a quadratic programming solver
 - http://abel.ee.ucla.edu/cvxopt/userguide/coneprog.html#quadraticprogramming
- cvxopt.solvers.qp(P, q[, R, s[, U, v[, solver[, initvals]]]])
 - Solves the following problem for z:

Programming the SVM



End of Lecture-1

We want to make a machine that will be proud of us.

- Danny Hillis