

Introduction to XV6

CS202 Lab

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Presentation outline

- About me (Sina)
- Logistics
- What is XV6
- Hello World in XV6
- System calls in XV6

About me

- I have two names, but almost everybody calls me Sina
- I am one of Prof. Yin's PHD students
- I work on system security
 - A cool way of saying the same thing is that I am trying to hack into OSes 😊
- I have one MS in security and privacy and one MS in Entrepreneurship and Management
- My hobbies are:
 - Playing pool
 - Dancing
 - And hanging out with friends

Logistics

- The demo will be uploaded as a recorded video
 - You just need to follow the same steps later to get the tasks running
- In addition to this presentation, a few other tutorials will be uploaded
- During the class, I suggest you just listen and ask questions (don't try the commands)
- Start playing with XV6 ASAP!
 - It's fun, you'll enjoy it
- Don't wait until last minute (for the entire quarter) to raise your questions

What is XV6?

- XV6 is a lightweight operating system
- It was designed in MIT for educational purposes
- It has an easy-to-understand structure

The bottom line is:

Understanding high level OS concepts using XV6 is straightforward

How can one run XV6?

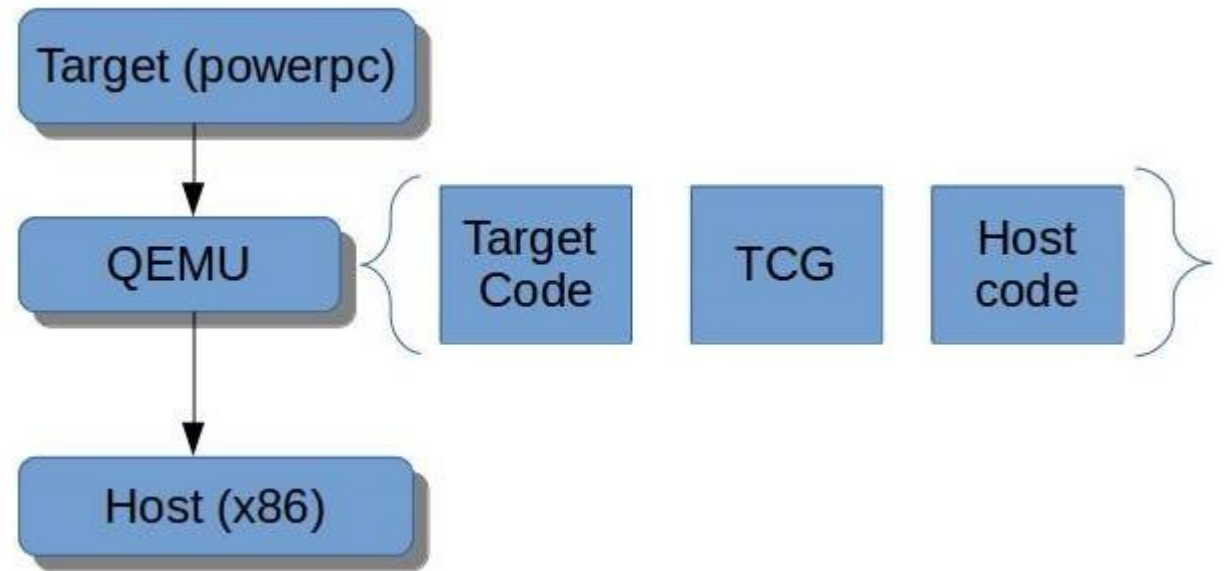
- XV6 can be installed as a standalone OS (not recommended)
- XV6 can run in an emulated environment (recommended)
- ***QEMU*** is the emulator we use to run XV6

How can one run XV6?

- QEMU is a user program/system emulator

Examples:

- Running Arm on your Home PC
- Running Windows on Linux
- Running XV6 on your Ubuntu



Write a hello world program in XV6

High level steps

- Download XV6 source code
- Write a hello world program
- Include the program in the XV6 source code
 - A way of uploading the program to XV6
- Compile and run XV6 with QEMU
- Run the hello world program inside XV6

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Make a “hello world” system call

mkdir system call in XV6

Let's see how system calls are already defined in xv6

Definition of a system call in the kernel land

- SYSCALL([NAME]) in usys.S:
 - SYSCALL(mkdir)
- This line translates to the following assembly:

```
.globl mkdir;
```

```
mkdir:
```

```
movl $SYS_mkdir, %eax; //putting the system call number in eax
```

```
int $T_SYSCALL; //calling the system call handler in interrupt mode
```



We have to define this constant

Definition of a system call in the kernel land

- \$T_SYSCALL is a pointer to “syscall” function in syscall.c:

```
void
syscall(void)
[ {
    int num;
    struct proc *curproc = myproc();

    num = curproc->tf->eax;
    if(num > 0 && num < NELEM(syscalls) && syscalls[num]) {
        curproc->tf->eax = syscalls[num](); ← syscalls[SYS_mkdir]
    } else {
        cprintf("%d %s: unknown sys call %d\n",
            curproc->pid, curproc->name, num);
        curproc->tf->eax = -1;
    }
}
```

Definition of a system call in the kernel land

- To make the call to `syscalls[SYS_mkdir]` working, we need two things:
 - define `SYS_mkdir`

```
#define SYS_mkdir 20
```

in `syscall.h`

- put the pointer to our system call in `syscalls[SYS_mkdir]` array element

```
106
107 static int (*syscalls[])(void) = {
108     [SYS_fork]    sys_fork,
109     [SYS_exit]    sys_exit,
110     [SYS_wait]    sys_wait,
111     [SYS_pipe]    sys_pipe,
112     [SYS_read]    sys_read,
113     [SYS_kill]    sys_kill,
114     [SYS_exec]    sys_exec,
115     [SYS_fstat]   sys_fstat,
116     [SYS_chdir]   sys_chdir,
117     [SYS_dup]     sys_dup,
118     [SYS_getpid]  sys_getpid,
119     [SYS_sbrk]    sys_sbrk,
120     [SYS_sleep]   sys_sleep,
121     [SYS_uptime]  sys_uptime,
122     [SYS_open]    sys_open,
123     [SYS_write]   sys_write,
124     [SYS_mknod]   sys_mknod,
125     [SYS_unlink]  sys_unlink,
126     [SYS_link]    sys_link,
127     [SYS_mkdir]   sys_mkdir,
128     [SYS_close]   sys_close,
129 };
130
```

in `syscall.c`

Definition of a system call in the kernel land

- So now `syscalls[SYS_mkdir]` points to *sys_mkdir*
- We need to define *sys_mkdir* function in the kernel land
- We put the function definition in “`sysproc.c`” file
- Since we define *sys_mkdir* outside *syscall.c*, we need this line:

```
| 95 extern int sys_mkdir(void);
```

in `syscall.c`

Definition of a system call in the kernel land

- *sys_mkdir skeleton in the kernel land (sysproc.c):*

```
int
sys_mkdir(void)
{
    char *path;
    struct inode *ip;

    begin_op();
    if(argstr(0, &path) < 0 || (ip = create(path, T_DIR, 0, 0)) == 0){
        end_op();
        return -1;
    }
    iunlockout(ip);
    end_op();
    return 0;
}
```

Define the system call in the kernel land

- What if we want to put the function definition in “proc.c” file because we can access many variables and kernel functions in proc.c? [you need to put your code there for your assignment ;-)]
 - We define a function in proc.c and call it in the sysproc.c definition

Defining “hello” system call in the kernel land

In “sysproc.c”

```
92
93 // BR
94 int
95 sys_hello(void)
96 {
97     hello(); ←
98     return 0;
99 }
100 // BR
101
```

In “proc.c”

```
483
484
485
486
487
488 //BR
489 void
490 hello(void)
491 {
492     cprintf("\n\n Hello from the kernel space! \n\n");
493 }
494 //BR
```

Since hello is in a different file we need to mention this in “defs.h” header file

In “defs.h”

```
104 //PAGEBREAK: 16
105 // proc.c
106 void exit(void);
107 int fork(void);
108 int growproc(int);
109 int kill(int);
110 void pinit(void);
111 void procdump(void);
112 void scheduler(void) __attribute__((noreturn));
113 void sched(void);
114 void sleep(void*, struct spinlock*);
115 void userinit(void);
116 int wait(void);
117 void wakeup(void*);
118 void yield(void);
119 void hello(void); //BR
```

Defining “hello” system call in the kernel land

- Finally...
- We need to mention that “hello” is a library function

In “user.h”

```
3
4 // system calls
5 int fork(void);
6 int exit(void) __attribute__((noreturn));
7 int wait(void);
8 int pipe(int*);
9 int write(int, void*, int);
10 int read(int, void*, int);
11 int close(int);
12 int kill(int);
13 int exec(char*, char**);
14 int open(char*, int);
15 int mknod(char*, short, short);
16 int unlink(char*);
17 int fstat(int fd, struct stat*);
18 int link(char*, char*);
19 int mkdir(char*);
20 int chdir(char*);
21 int dup(int);
22 int getpid(void);
23 char* sbrk(int);
24 int sleep(int);
25 int uptime(void);
26 int hello(void); //BR
27
```

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