

CS450

# Structure of Higher Level Languages

Lecture 14: Mutable environment semantics and frames

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# A quick recap...

- We introduced  $\lambda_D$ -Racket, to capture the semantics of `define`
- We realized  $\lambda_D$ -Racket could not represent out-of-order definitions.
- We encoded a shared mutable heap

# Today we will...

- Introduce the semantics of  $\lambda$ -calculus with environments
- Study mutation as a side-effect
- Introduce mutable environments, composed of frames
- Implement frames

Section 3.2 of the SICP book. [The interactive version of Section 3.2.](#)

# Introducing the $\lambda_D^*$ -calculus

# $\lambda_D^*$ -calculus: $\lambda$ -calculus with definitions

We highlight in red an operation that produces a side effect: *mutating an environment*.

$$\frac{e \Downarrow_E v \quad E \leftarrow [x := v]}{(\text{define } x \ e) \Downarrow_E \text{ void}} \text{ (E-def)}$$

$$\frac{t_1 \Downarrow_E v_1 \quad t_2 \Downarrow_E v_2}{t_1; t_2 \Downarrow_E v_2} \text{ (E-seq)}$$

# $\lambda_D^*$ -calculus: $\lambda$ -calculus with definitions

Because we have side-effects, the order in which we evaluate each sub-expression is important.

$$v \Downarrow_E v \quad (\text{E-val})$$

$$x \Downarrow_E E(x) \quad (\text{E-var})$$

$$\lambda x.t \Downarrow_E (E, \lambda x.t) \quad (\text{E-lam})$$

$$\frac{e_f \Downarrow_E (E_f, \lambda x.t_b) \quad e_a \Downarrow_E v_a \quad \color{red}{E_b \leftarrow E_f + [x := v_a]} \quad t_b \Downarrow_{E_b} v_b}{(e_f e_a) \Downarrow_E v_b} \quad (\text{E-app})$$

Can you explain why the order is important?

# $\lambda_D^*$ -calculus: $\lambda$ -calculus with definitions

Because we have side-effects, the order in which we evaluate each sub-expression is important.

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Can you explain why the order is important? Otherwise, we might evaluate the body of the function  $e_b$  without observing the assignment  $x := v_a$  in  $E_b$ .

# Mutable operations on environments

# Mutable operations on environments

Put

$$E \leftarrow [x := v]$$

Take a reference to an environment  $E$  and mutate its contents, by adding a new binding.

Push

$$E \leftarrow E' + [x := v]$$

Create a new environment referenced by  $E$  which copies the elements of  $E'$  and also adds a new binding.

# Making side-effects explicit

# Mutation as a side-effect

Let us use a triangle  $\blacktriangleright$  to represent the order of side-effects.

$$\frac{e \Downarrow_E v \quad \blacktriangleright \quad E \leftarrow [x := v]}{(\text{define } x \ e) \Downarrow_E \text{ void}} \text{ (E-def)}$$

$$\frac{t_1 \Downarrow_E v_1 \quad \blacktriangleright \quad t_2 \Downarrow_E v_2}{t_1; t_2 \Downarrow_E v_2} \text{ (E-seq)}$$

$$\frac{e_f \Downarrow_E (E_f, \lambda x. t_b) \blacktriangleright e_a \Downarrow_E v_a \blacktriangleright E_b \leftarrow E_f + [x := v_a] \blacktriangleright t_b \Downarrow_{E_b} v_b}{(e_f \ e_a) \Downarrow_E v_b} \text{ (E-app)}$$

# Implementing side-effect mutation

## Making the heap explicit

We can annotate each triangle with a heap, to make explicit which how the global heap should be passed from one operation to the next. In this example, defining a variable takes an input global heap  $H$  and produces an output global heap  $H_2$ .

$$\frac{\blacktriangleright_H e \Downarrow_E v \quad \blacktriangleright_{H_1} E \leftarrow [x := v] \quad \blacktriangleright_{H_2}}{\blacktriangleright_H (\mathbf{define}\ x\ e) \Downarrow_E \mathbf{void} \blacktriangleright_{H_2}} \text{ (E-def)}$$

# Let us use our rule sheet!

$$\frac{e \Downarrow_E v \quad \blacktriangleright \quad E \leftarrow [x := v]}{(\text{define } x \ e) \Downarrow_E \text{ void}} \text{ (E-def)}$$

$$\frac{t_1 \Downarrow_E v_1 \quad \blacktriangleright \quad t_2 \Downarrow_E v_2}{t_1; t_2 \Downarrow_E v_2} \text{ (E-seq)}$$

$$\frac{e_f \Downarrow_E (E_f, \lambda x. t_b) \quad \blacktriangleright \quad e_a \Downarrow_E v_a \quad \blacktriangleright \quad E_b \leftarrow E_f + [x := v_a] \quad \blacktriangleright \quad t_b \Downarrow_{E_b} v_b}{(e_f \ e_a) \Downarrow_E v_b} \text{ (E-app)}$$

$$v \Downarrow_E v \quad \text{ (E-val)}$$

$$x \Downarrow_E E(x) \quad \text{ (E-var)}$$

$$\lambda x. t \Downarrow_E (E, \lambda x. t) \quad \text{ (E-lam)}$$

# Examples

# Evaluating Example 2 of Lecture 13

```
(define b (lambda (x) a))  
(define a 20)  
(b 1)
```

Input

```
E0: []  
Term: (define b (lambda (y) a))
```

# Evaluating Example 2 of Lecture 13

```
(define b (lambda (x) a))
(define a 20)
(b 1)
```

Input

$E_0: []$   
Term: (define b (lambda (y) a))

Output

$E_0: [$   
     $(b . (\text{closure } E_0 (\lambda y. a)))$   
 $]$   
Expression: #<void>

$$\frac{\overline{\lambda y.a \Downarrow_{E_0} (E_0, \lambda y.a)} \quad \overline{E_0 \leftarrow [b := (E_1, \lambda y.a)]}}{(\text{define } b \lambda y.a) \Downarrow_{E_0} \text{void}}$$

# Example 2: step 2

Input

```
E0: [
  (b . (closure E0 (lambda (y) a)))
]
Term: (define a 20)
```

# Example 2: step 2

Input

```
E0: [
  (b . (closure E0 (lambda (y) a)))
]
Term: (define a 20)
```

Output

```
E0: [
  (a . 20)
  (b . (closure E0 (lambda (y) a)))
]
Expression: #<void>
```

$$\frac{20 \downarrow_{E_0} 20}{(\text{define } a 20) \downarrow_{E_0} \text{void}} \quad \blacktriangleright \quad \frac{E_0 \leftarrow [a := 20]}{\text{Expression: } \#<\text{void}>}$$

# Example 2: step 3

Input

```
E0: [  
  (a . 20)  
  (b . (closure E0 (lambda (y) a)))  
]  
Term: (b 1)
```

# Example 2: step 3

Input

```
E0: [
  (a . 20)
  (b . (closure E0 (lambda (y) a)))
]
Term: (b 1)
```

Output

```
E0: [
  (a . 20)
  (b . (closure E0 (lambda (y) a)))
]
E1: [ E0
      (y . 1)
    ]
Expression: 20
```

$$\frac{b \Downarrow_{E_0} (E_0, \lambda y. a) \blacktriangleright 1 \Downarrow_{E_0} 1 \blacktriangleright E_1 \leftarrow E_0 + [y := 1] \blacktriangleright a \Downarrow_{E_1} 20}{(b 1) \Downarrow_{E_0} 20}$$

# Example 3

```
(define (f x) (lambda (y) x))  
(f 10)
```

Input

```
E0: []  
Term: (define (f x) (lambda (y) x))
```

# Example 3

```
(define (f x) (lambda (y) x))  
(f 10)
```

Input

```
E0: []  
Term: (define (f x) (lambda (y) x))
```

Output

```
E0: [  
      (f . (closure E0  
                    (lambda (x) (lambda (y) x))))  
    ]  
Value: void
```

# Example 3

```
(define (f x) (lambda (y) x))
(f 10)
```

Input

$E_0: []$   
 Term: (define (f x) (lambda (y) x))

Output

$E_0: [$   
 $\quad (f . (\text{closure } E_0$   
 $\quad \quad (\lambda (x) (\lambda (y) x))))$   
 $]$   
 Value: void

$$\lambda x. \lambda y. x \Downarrow_{E_0} (E_0, \lambda x. \lambda y. x)$$

---


$$(\mathbf{define} \ f \ \lambda x. \lambda y. x) \Downarrow_{E_0} \mathbf{void}$$

# Example 3

```
(define (f x) (lambda (y) x))
(f 10)
```

Input

$E_0: []$   
 Term: (define (f x) (lambda (y) x))

Output

$E_0: [$   
 $\quad (f . (\text{closure } E_0$   
 $\quad \quad (\lambda (x) (\lambda (y) x))))$   
 $]$   
 Value: void

$$\frac{\lambda x. \lambda y. x \downarrow_{E_0} (E_0, \lambda x. \lambda y. x) \quad \blacktriangleright \quad E_0 \leftarrow [f := (E_0, \lambda x. \lambda y. x)]}{(\text{define } f \lambda x. \lambda y. x) \downarrow_{E_0} \text{void}}$$

# Example 3

Input

```
E0: [  
  (f . (closure E0  
    (lambda (x) (lambda (y) x))))]  
Term: (f 10)
```

# Example 3

Input

```
E0: [
  (f . (closure E0
    (lambda (x) (lambda (y) x))))
]
Term: (f 10)
```

Output

```
E0: [
  (f . (closure E0
    (lambda (x) (lambda (y) x))))
]
E1: [ E0 (x . 10) ]
Value: (closure E1 (lambda (y) x))
```

# Example 3

Input

```
E0: [
  (f . (closure E0
    (lambda (x) (lambda (y) x))))
]
Term: (f 10)
```

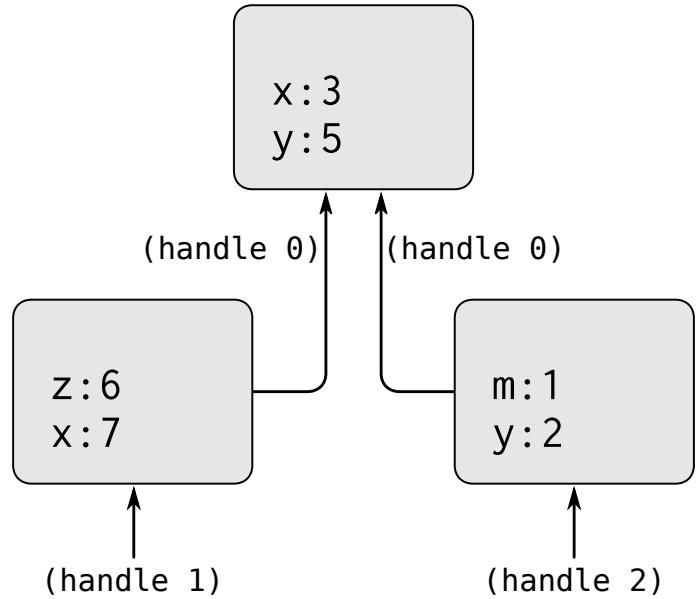
Output

```
E0: [
  (f . (closure E0
    (lambda (x) (lambda (y) x))))
]
E1: [ E0 (x . 10) ]
Value: (closure E1 (lambda (y) x))
```

$$\frac{E_0(f) = (E_0, \lambda x. \lambda y. x)}{f \Downarrow_{E_0} (E_0, \lambda x. \lambda y. x)} \quad \frac{10 \Downarrow_{E_0} 10}{\overline{E_1 \leftarrow E_0 + [x := 10]}} \quad \frac{\overline{\lambda y. x \Downarrow_{E_1} (E_1, \lambda y. x)}}{(f 10) \Downarrow_{E_0} (E_1, \lambda y. x)}$$

# Visualizing the environment

# Environment visualization



**Figure 3.1:** A simple environment structure.

Source: SICP book Section 3.2

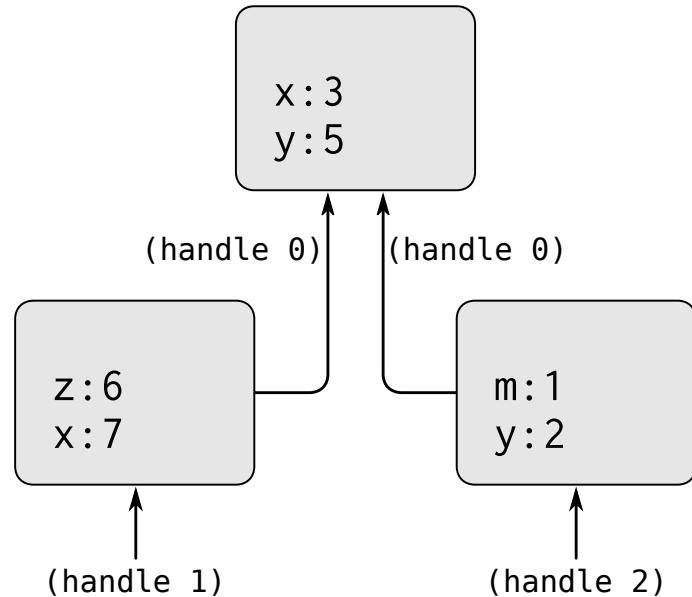
```

; E0 = (handle 0)
E0: [
  (x . 3)
  (y . 5)
]

; E1 = (handle 1)
E1: [ E0
  (z . 6)
  (x . 7) ; shadows E0.x
  ; (y . 5)
]

; E2 = (handle 2)
E2: [ E0
  (m . 1)
  (y . 2) ; shadows E0.y
  ; (x . 3)
]
  
```

# Environment visualization



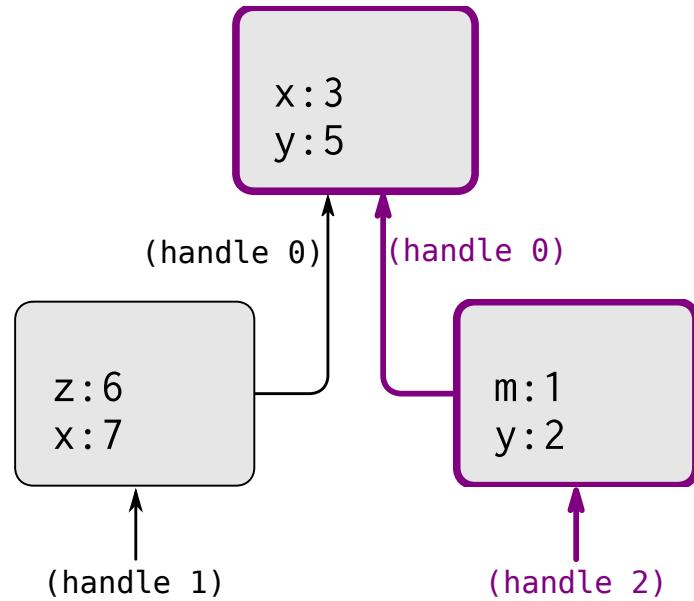
## The heap at runtime

- arrows are *references*, or heap handles:
- boxes are *frames*: labelled by their handles
- each frame has local variable bindings (eg, `m:1`, and `y:2`)

**Figure 3.1:** A simple environment structure.

Source: SICP book Section 3.2

# Environment visualization



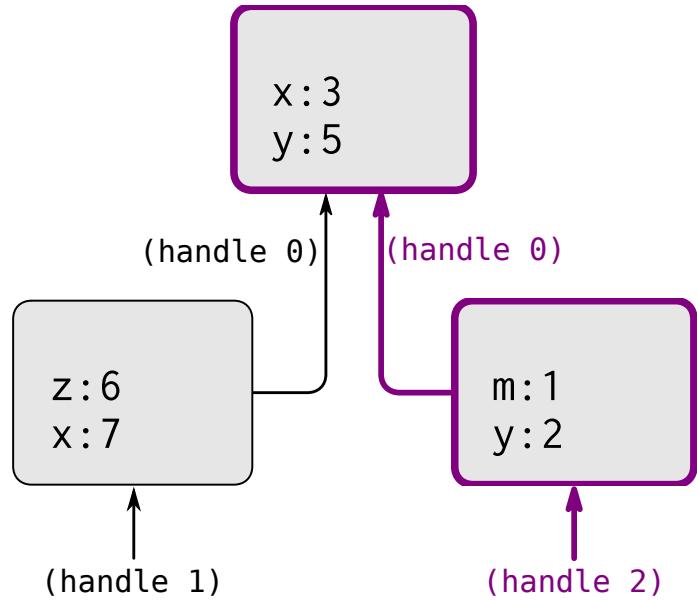
**Figure 3.1:** A simple environment structure.

Source: SICP book Section 3.2

## The heap at runtime

- arrows are *references*, or heap handles:
- boxes are *frames*: labelled by their handles
- each frame has local variable bindings (eg, `m:1`, and `y:2`)
- an *environment* represents a *sequence of frames*, connected via references. For instance, the environment that consists of frame 3 linked to frame 1.
- variable lookup follows the reference order. For instance, lookup a variable in frame 3 and then in frame 1.

# Quiz



**Figure 3.1:** A simple environment structure.

Source: SICP book Section 3.2

List all variable bindings  
in environment (handle 1)

Please, write down your answer, your email address, and leave your paper in my desk before you leave.

| This quiz counts toward your attendance grade.

# Implementing mutable environments

# Implementing mutable environments

## Heap

- A heap contains *frames*

## Frame

- a reference to its parent frame (except for the root frame which does not refer any other frame)
- a map of local bindings

```
E0: [  
  (a . 20)  
  (b . (closure E0 (lambda (y) a)))  
]  
E1: [ E0  
  (y . 1)  
]
```

Example of a frame: [ E0 (y . 1) ]

Example of a root frame: [ (a . 20) (b . (closure E0 (lambda (y) a))) ]

# Let us implement frames...

(demo time)

# Usage examples

```

; (closure E0 (lambda (y) a)
(define c (s:closure (handle 0) (s:lambda (list (s:variable 'y)) (s:variable 'a))))
;E0: [
;  (a . 20)
;  (b . (closure E0 (lambda (y) a)))
;]
(define f1
  (frame-put
    (frame-put root-frame (s:variable 'a) (s:number 10))
    (s:variable 'b) c))
(check-equal? f1 (frame #f (hash (s:variable 'a) (s:number 10) (s:variable 'b) c)))
; Lookup a
(check-equal? (s:number 10) (frame-get f1 (s:variable 'a)))
; Lookup b
(check-equal? c (frame-get f1 (s:variable 'b)))
; Lookup c that does not exist
(check-equal? #f (frame-get f1 (s:variable 'c)))

```

# More usage examples

```

; E1: [ E0
; (y . 1)
; ]
(define f2 (frame-push (handle 0) (s:variable 'y) (s:number 1)))
(check-equal? f2 (frame (handle 0) (hash (s:variable 'y) (s:number 1))))
(check-equal? (s:number 1) (frame-get f2 (s:variable 'y)))
(check-equal? #f (frame-get f2 (s:variable 'a)))
;; We can use frame-parse to build frames
(check-equal? (parse-frame '[' (a . 10) (b . (closure E0 (lambda (y) a))))]) f1)
(check-equal? (parse-frame '[' E0 (y . 1) ]) f2))

```

# Frames

`(struct frame (parent locals))`

- `parent` is either `#f` or is a reference to the parent frame
- `locals` is a hash-table with the local variables of this frame

## Constructors

```
(struct frame (parent locals) #:transparent)
(define root-frame (frame #f (hash)))
(define (frame-push parent var val)
  (frame parent (hash var val)))
(define (frame-put frm var val)
  (frame (frame-parent frm)
         (hash-set (frame-locals frm) var val)))
(define (frame-get frm var)
  (hash-ref (frame-locals frm) var #f))
```

## Description

- `root-frame` creates an orphan empty frame (hence `#f`). This function is needed to represent the top-level environment.
- `frame-push` takes a reference that points to the parent frame, and initializes a hash-table with one entry `(var, val)`. This function is needed for  $E \leftarrow E' + [x := v]$
- `frame-put` updates the current frame with a new binding. This function is needed for  $E \leftarrow [x := v]$