



Language Technologies Institute



Multimodal Machine Learning

Lecture 4.2: Coordinated Representations Louis-Philippe Morency

* Original version co-developed with Tadas Baltrusaitis

Administrative Stuff



Language Technologies Institute

Piazza Live Q&A – Reminder







Lecture Schedule

Classes	Tuesday Lectures	Thursday Lectures
Week 1	Course introduction	Multimodal applications and datasets
9/1 & 9/3	 Research and technical challenges 	Research tasks and datasets
	 Course syllabus and requirements 	Team projects
Week 2	Basic concepts: neural networks	Basic concepts: network optimization
9/8 & 9/10	 Language, visual and acoustic 	 Gradients and backpropagation
	 Loss functions and neural networks 	 Practical deep model optimization
Week 3	Visual unimodal representations	Language unimodal representations
9/15 & 9/17	 Convolutional kernels and CNNs 	Gated networks and LSTM
	 Residual network and skip connection 	 Backpropagation Through Time
Week 4	Multimodal representation learning	Coordinated representations
9/22 & 9/24	 Multimodal auto-encoders 	 Deep canonical correlation analysis
	 Multimodal joint representations 	 Non-negative matrix factorization
Week 5	Multimodal alignment	Alignment and representation
9/29 & 10/1	 Explicit - dynamic time warping 	Self-attention models
	Implicit - attention models	Multimodal transformers
Week 6	First project assignment (live working session	s i <u>nstead of lectures)</u>
10/6 & 10/8		First project assignment
		Presentations due Friday 10/9
		Reports due Sunday 10/11

Peer feedback due Friday 10/16

Lecture Schedule

Tuesday Lectures	Thursday Lectures
 Alignment and translation Module networks Connectionist temporal classification 	 Probabilistic graphical models Dynamic Bayesian networks Coupled and factor HMMs
 Discriminative graphical models Conditional random fields Continuous and fully-connected CRFs 	 Neural Generative Models Variational auto-encoder Generative adversarial networks
 Reinforcement learning Markov decision process Q learning and policy gradients 	 Multimodal RL Deep Q learning Multimodal applications
 Fusion and co-learning Multi-kernel learning and fusion Few shot learning and co-learning 	 New research directions Recent approaches in multimodal ML
Mid-term project assignment (live working se	essions instead of lectures) Midterm project assignment
	 Alignment and translation Module networks Connectionist temporal classification Discriminative graphical models Conditional random fields Continuous and fully-connected CRFs Reinforcement learning Markov decision process Q learning and policy gradients Fusion and co-learning Multi-kernel learning and fusion

Midterm project assignment Presentations due Friday 11/13 Reports due Sunday 11/15 Peer feedback due Friday 11/20



Lecture Schedule

Classes	Tuesday Lectures	Thursday Lectures
Week 12 11/17 & 11/19	 Embodied Language Grounding Connecting Language to Action Guest lecture: Yonatan Bisk 	 Multi-lingual representations Tentative topic Guest lecture: To be confirmed
Week 13 11/24 & 11/26	Thanksgiving week (no lectures)	
Week 14 12/1 & 12/3	 Learning to connect text and images Discourse approaches, text & images Guest lecture: Malihe Alikhani 	 Bias and fairness Computational ethics Guest lecture: Yulia Tsvetkov
Week 15 12/8 & 12/10	Final project assignment (live working sessions instead of lectures)	
		Final project assignment Presentations due Friday 12/11 Reports due Sunday 12/13





- First, create an account on AWS Educate portal: <u>https://aws.amazon.com/education/awseducate/</u>
- > Your account will need to be backed by your credit card
- Be sure to setup billing alarms and monitor your spending!
- Refrain from including AWS credential in code/github
- To get your coupon, use your AndrewID and the URL posted on Piazza





Coupons can be redeemed at this address: <u>https://console.cloud.google.com/education</u>

Be sure to setup billing alarms and monitor your spending!

Refrain from including GCP credential in code/github

To get your coupon, use your AndrewID and the URL posted on Piazza









Multimodal Machine Learning

Lecture 4.2: Coordinated Representations Louis-Philippe Morency

* Original version co-developed with Tadas Baltrusaitis

Lecture Objectives

- Quick recap
- Coordinated multimodal representations
- Multivariate statistical analysis
 - Basic concepts (multivariate, covariance,...)
- Canonical Correlation Analysis
 - Deep Correlation Networks
 - Deep CCA, DCCA-AutoEncoder
- Multi-view clustering
 - Nonnegative Matrix Factorization
- Multi-view latent intact space
 - Autoencoder in Autoencoder networkds



Quick Recap



Language Technologies Institute



Learn (unsupervised) a joint representation between multiple modalities where similar unimodal concepts are closely projected.

> Deep Multimodal Boltzmann machines





Learn (unsupervised) a joint representation between multiple modalities where similar unimodal concepts are closely projected.

- Deep Multimodal Boltzmann machines
- Stacked Autoencoder





Learn (unsupervised) a joint representation between multiple modalities where similar unimodal concepts are closely projected.

- Deep Multimodal Boltzmann machines
- Stacked Autoencoder
- Encoder-Decoder





Learn (unsupervised) a joint representation between multiple modalities where similar unimodal concepts are closely projected.

- Deep Multimodal Boltzmann machines
- Stacked Autoencoder
- Encoder-Decoder
- Tensor Fusion representation



How Can We Learn Better Representations?

Coordinated Multimodal Representations

Coordinated multimodal embeddings

 Instead of projecting to a joint space enforce the similarity between unimodal embeddings







Coordinated Multimodal Representations

Learn (unsupervised) two or more coordinated representations from multiple modalities. A loss function is defined to bring closer these multiple representations.



Coordinated Multimodal Embeddings



[Huang et al., Learning Deep Structured Semantic Models for Web Search using Clickthrough Data, 2013]





Multimodal Vector Space Arithmetic

Nearest images



[Kiros et al., Unifying Visual-Semantic Embeddings with Multimodal Neural Language Models, 2014]





Multimodal Vector Space Arithmetic

Nearest images



[Kiros et al., Unifying Visual-Semantic Embeddings with Multimodal Neural Language Models, 2014]



Structured coordinated embeddings

Instead of or in addition to similarity add alternative structure





[Vendrov et al., Order-Embeddings of Images and Language, 2016] [Jiang and Li, Deep Cross-Modal Hashing]



Multivariate Statistical Analysis



Language Technologies Institute

"Statistical approaches to understand the relationships in high dimensional data"

- Example of multivariate analysis approaches:
 - Multivariate analysis of variance (MANOVA)
 - Principal components analysis (PCA)
 - Factor analysis
 - Linear discriminant analysis (LDA)
 - Canonical correlation analysis (CCA)



Definition: A variable whose possible values are numerical outcomes of a random phenomenon.

- □ **Discrete** random variable is one which may take on only a countable number of distinct values such as 0,1,2,3,4,...
- Continuous random variable is one which takes an infinite number of possible values.

Examples of random variables:

- Someone's age
- Someone's height
- Someone's weight

Discrete or continuous?

Correlated?



Definitions

Given two random variables *X* and *Y*:

Expected value probability-weighted average of all possible values

$$\mu = E[X] = \sum_{i} x_i P(x_i)$$

> If same probability for all observations x_i , then same as arithmetic mean **Variance** measures the spread of the observations

$$\sigma^{2} = Var(X) = E[(X - \mu)(X - \mu)] = E[\overline{X}\overline{X}]$$
 If data is centered

 \succ Variance is equal to the square of the standard deviation σ

Covariance measures how much two random variables change together

$$cov(X,Y) = E[(X - \mu_X)(Y - \mu_y)] = E[\overline{X}\overline{Y}]$$



Definitions

Pearson Correlation measures the extent to which two variables have a linear relationship with each other

$$\rho_{X,Y} = corr(X,Y) = \frac{cov(X,Y)}{var(X)var(Y)}$$





Pearson Correlation Examples





Definitions

Multivariate (multidimensional) random variables

(aka random vector)

 $\boldsymbol{X} = [X^{1}, X^{2}, X^{3}, \dots, X^{M}]$ $\boldsymbol{Y} = [Y^{1}, Y^{2}, Y^{3}, \dots, Y^{N}]$

Covariance matrix generalizes the notion of variance

$$\Sigma_{\mathbf{X}} = \Sigma_{\mathbf{X},\mathbf{X}} = var(\mathbf{X}) = E[(\mathbf{X} - E[\mathbf{X}])(\mathbf{X} - E[\mathbf{X}])^T] = E[\overline{\mathbf{X}}\overline{\mathbf{X}}^T]$$

Cross-covariance matrix generalizes the notion of covariance

$$\Sigma_{\boldsymbol{X},\boldsymbol{Y}} = cov(\boldsymbol{X},\boldsymbol{Y}) = E[(\boldsymbol{X} - E[\boldsymbol{X}])(\boldsymbol{Y} - E[\boldsymbol{Y}])^T] = E[\overline{\boldsymbol{X}}\overline{\boldsymbol{Y}}^T]$$



Definitions

Multivariate (multidimensional) random variables

(aka random vector)

$$\boldsymbol{X} = [X^{1}, X^{2}, X^{3}, \dots, X^{M}]$$
$$\boldsymbol{Y} = [Y^{1}, Y^{2}, Y^{3}, \dots, Y^{N}]$$

Covariance matrix generalizes the notion of variance

$$\Sigma_{\mathbf{X}} = \Sigma_{\mathbf{X},\mathbf{X}} = var(\mathbf{X}) = E[(\mathbf{X} - E[\mathbf{X}])(\mathbf{X} - E[\mathbf{X}])^T] = E[\overline{\mathbf{X}}\overline{\mathbf{X}}^T]$$

Cross-covariance matrix generalizes the notion of covariance

$$\Sigma_{\boldsymbol{X},\boldsymbol{Y}} = cov(\boldsymbol{X},\boldsymbol{Y}) = \begin{bmatrix} cov(X_1,Y_1) & cov(X_2,Y_1) & \cdots & cov(X_M,Y_1) \\ cov(X_1,Y_2) & cov(X_2,Y_2) & \cdots & cov(X_M,Y_2) \\ \vdots & \vdots & \ddots & \vdots \\ cov(X_1,Y_N) & cov(X_2,Y_N) & \cdots & cov(X_M,Y_N) \end{bmatrix}$$



Definitions – Matrix Operations

Trace is defined as the sum of the elements on the main diagonal of any matrix *X*

$$tr(\boldsymbol{X}) = \sum_{i=1}^{n} x_{ii}$$





Principal component analysis

PCA converts a set of observations of possibly correlated variables into a set of values of linearly uncorrelated variables called *principal components*

- Eigenvectors are orthogonal towards each other and have length one
- The first couple of eigenvectors explain the most of the variance observed in the data
- Low eigenvalues indicate little loss of information if omitted







Eigenvalues and Eigenvectors

Eigenvalue decomposition

If A is an $n \times n$ matrix, do there exist nonzero vectors **x** in \mathbb{R}^n such that $A\mathbf{x}$ is a scalar multiple of **x**?

 (The term eigenvalue is from the German word *Eigenwert*, meaning "proper value")

Eigenvalue equation:



 λ : a scalar (could be **zero**)

x: a **nonzero** vector in R^n







Singular Value Decomposition (SVD)

SVD expresses any matrix A as

$$\mathbf{A} = \mathbf{U}\mathbf{S}\mathbf{V}^T$$

 The columns of U are eigenvectors of AA^T, and the columns of V are eigenvectors of A^TA.

$$\mathbf{A}\mathbf{A}^{T}\mathbf{u}_{i} = s_{i}^{2}\mathbf{u}_{i}$$
$$\mathbf{A}^{T}\mathbf{A}\mathbf{v}_{i} = s_{i}^{2}\mathbf{v}_{i}$$



Canonical Correlation Analysis



Language Technologies Institute

Multi-view Learning





demographic properties



responses to survey



audio features at time i



video features at time i


"canonical": reduced to the simplest or clearest schema possible

1 Learn two linear projections, one for each view, that are maximally correlated:

$$(\boldsymbol{u}^*, \boldsymbol{v}^*) = \operatorname*{argmax}_{\boldsymbol{u}, \boldsymbol{v}} corr(\boldsymbol{H}_{\boldsymbol{x}}, \boldsymbol{H}_{\boldsymbol{y}})$$

$$= \operatorname*{argmax}_{u,v} corr(u^T X, v^T Y)$$





Correlated Projection

1 Learn two linear projections, one for each view, that are maximally correlated:

 $(\boldsymbol{u}^*, \boldsymbol{v}^*) = \operatorname*{argmax}_{\boldsymbol{u}, \boldsymbol{v}} corr(\boldsymbol{u}^T \boldsymbol{X}, \boldsymbol{v}^T \boldsymbol{Y})$



Two views X, Y where same instances have the same color



1 Learn two linear projections, one for each view, that are maximally correlated:

$$(\boldsymbol{u}^{*}, \boldsymbol{v}^{*}) = \operatorname*{argmax}_{\boldsymbol{u}, \boldsymbol{v}} corr(\boldsymbol{u}^{T}\boldsymbol{X}, \boldsymbol{v}^{T}\boldsymbol{Y})$$

$$= \operatorname*{argmax}_{\boldsymbol{u}, \boldsymbol{v}} \frac{cov(\boldsymbol{u}^{T}\boldsymbol{X}, \boldsymbol{v}^{T}\boldsymbol{Y})}{var(\boldsymbol{u}^{T}\boldsymbol{X})var(\boldsymbol{v}^{T}\boldsymbol{Y})}$$

$$= \operatorname*{argmax}_{\boldsymbol{u}, \boldsymbol{v}} \frac{\boldsymbol{u}^{T}\boldsymbol{X}\boldsymbol{Y}^{T}\boldsymbol{v}}{\sqrt{\boldsymbol{u}^{T}\boldsymbol{X}\boldsymbol{X}^{T}\boldsymbol{u}}\sqrt{\boldsymbol{v}^{T}\boldsymbol{Y}\boldsymbol{Y}^{T}\boldsymbol{v}}}$$

$$= \operatorname*{argmax}_{\boldsymbol{u}, \boldsymbol{v}} \frac{\boldsymbol{u}^{T}\boldsymbol{\Sigma}_{\boldsymbol{X}\boldsymbol{Y}}\boldsymbol{v}}{\sqrt{\boldsymbol{u}^{T}\boldsymbol{\Sigma}_{\boldsymbol{X}\boldsymbol{X}}\boldsymbol{u}}\sqrt{\boldsymbol{v}^{T}\boldsymbol{\Sigma}_{\boldsymbol{Y}\boldsymbol{Y}}\boldsymbol{v}}}$$
where

$$\Sigma_{XY} = cov(X,Y) = XY^{T}$$
if both X, Y have 0 mean

$$\mu_{X} = \mathbf{0} \quad \mu_{Y} = \mathbf{0}$$



We want to learn multiple projection pairs $(u_{(i)}X, v_{(i)}Y)$:

$$(\boldsymbol{u}_{(i)}^{*}, \boldsymbol{v}_{(i)}^{*}) = \underset{\boldsymbol{u}_{(i)}, \boldsymbol{v}_{(i)}}{\operatorname{argmax}} \frac{\boldsymbol{u}_{(i)}^{T} \boldsymbol{\Sigma}_{\boldsymbol{X}\boldsymbol{Y}} \boldsymbol{v}_{(i)}}{\sqrt{\boldsymbol{u}_{(i)}^{T} \boldsymbol{\Sigma}_{\boldsymbol{X}\boldsymbol{X}} \boldsymbol{u}_{(i)}} \sqrt{\boldsymbol{v}_{(i)}^{T} \boldsymbol{\Sigma}_{\boldsymbol{Y}\boldsymbol{Y}} \boldsymbol{v}_{(i)}}}$$

2

We want these multiple projection pairs to be orthogonal ("canonical") to each other:

$$\begin{aligned} u_{(i)}^{T} \Sigma_{XY} v_{(j)} &= u_{(j)}^{T} \Sigma_{XY} v_{(i)} = 0 & \text{for } i \neq j \\ |U \Sigma_{XY} V| &= tr(U \Sigma_{XY} V) & \text{where } U = [u_{(1)}, u_{(2)}, \dots, u_{(k)}] \\ & \text{and } V = [v_{(1)}, v_{(2)}, \dots, v_{(k)}] \end{aligned}$$



$$(\boldsymbol{U}^*, \boldsymbol{V}^*) = \underset{\boldsymbol{U}, \boldsymbol{V}}{\operatorname{argmax}} \frac{tr(\boldsymbol{U}^T \boldsymbol{\Sigma}_{XY} \boldsymbol{V})}{\sqrt{\boldsymbol{U}^T \boldsymbol{\Sigma}_{XX} \boldsymbol{U}} \sqrt{\boldsymbol{V}^T \boldsymbol{\Sigma}_{YY} \boldsymbol{V}}}$$

Since this objective function is invariant to scaling, we can constraint the projections to have unit variance:

$$U^T \Sigma_{XX} U = I \qquad V^T \Sigma_{YY} V = I$$

Canonical Correlation Analysis:

maximize:
$$tr(U^T \Sigma_{XY} V)$$

subject to: $U^T \Sigma_{XX} U = V^T \Sigma_{YY} V = I, u^T_{(j)} \Sigma_{XY} v_{(i)} = 0$



3

maximize: $tr(\boldsymbol{U}^T\boldsymbol{\Sigma}_{\boldsymbol{X}\boldsymbol{Y}}\boldsymbol{V})$ subject to: $U^T \Sigma_{XX} U = V^T \Sigma_{YY} V = I, u^T_{(j)} \Sigma_{XY} v_{(i)} = 0$ $\Sigma = \begin{bmatrix} \Sigma_{XX} & \Sigma_{YX} \\ \hline & & \\ \Sigma_{XY} & & \\ & & \\ \end{bmatrix} \stackrel{U,V}{\Rightarrow} \begin{bmatrix} 1 & 0 & 0 & \lambda_1 & 0 & 0 \\ 0 & 1 & 0 & 0 & \lambda_2 & 0 \\ 0 & 0 & 1 & 0 & 0 & \lambda_3 \\ \hline \lambda_1 & 0 & 0 & 1 & 0 & 0 \\ 0 & \lambda_2 & 0 & 0 & 1 & 0 \\ 0 & 0 & \lambda_3 & 0 & 0 & 1 \end{bmatrix}$



maximize:
$$tr(U^T \Sigma_{XY} V)$$

subject to: $U^T \Sigma_{XX} U = V^T \Sigma_{YY} V = I$, $u_{(j)}^T \Sigma_{XY} v_{(i)} = 0$
for $i \neq j$
How to solve it?
Lagrange Multipliers!
agrange function
 $L = tr(U^T \Sigma_{XY} V) + \alpha (U^T \Sigma_{YY} U - I) + \beta (V^T \Sigma_{YY} V - I)$
> And then find stationary points of L : $\frac{\partial L}{\partial U} = 0$ $\frac{\partial L}{\partial V} = 0$
 $\Sigma_{XX}^{-1} \Sigma_{XY} \Sigma_{YY}^{-1} \Sigma_{XY}^T U = \lambda U$
 $\Sigma_{YY}^{-1} \Sigma_{XY}^T \Sigma_{XX}^{-1} \Sigma_{XY} V = \lambda V$ where $\lambda = 4\alpha\beta$





Language Technologies Institute

maximize:
$$tr(U^T \Sigma_{XY} V)$$

subject to: $U^T \Sigma_{XX} U = V^T \Sigma_{YY} V = I, u_{(j)}^T \Sigma_{XY} v_{(i)} = 0$
for $i \neq j$
1 Linear projections
maximizing correlation
2 Orthogonal projections
3 Unit variance of the
projection vectors
 $U_1 = 0$
 H_x
 H_y
 $U_1 = 0$
 $U_1 = 0$

Text

X

Image

Y



Exploring Deep Correlation Networks



Language Technologies Institute

Same objective function as CCA:



47

Andrew et al., ICML 2013



Training procedure:

 Pre-train the models parameters using denoising autoencoders



Andrew et al., ICML 2013



Training procedure:

- Pre-train the models parameters using denoising autoencoders
- Optimize the CCA objective functions using large mini-batches or full-batch (L-BFGS)



Andrew et al., ICML 2013



Deep Canonically Correlated Autoencoders (DCCAE)

50

Jointly optimize for DCCA and autoencoders loss functions

A trade-off between multi-view correlation and reconstruction error from individual views



Wang et al., ICML 2015



Deep Correlational Neural Network

- 1. Learn a shallow CCA autoencoder (similar to 1 layer DCCAE model)
- 2. Use the learned weights for initializing the autoencoder layer
- 3. Repeat procedure



Chandar et al., Neural Computation, 2015



Multivariate Statistics

- Multivariate analysis of variance (MANOVA)
- Principal components analysis (PCA)
- Factor analysis
- Linear discriminant analysis (LDA)
- Canonical correlation analysis (CCA)
- Correspondence analysis
- Canonical correspondence analysis
- Multidimensional scaling
- Multivariate regression
- Discriminant analysis



Multi-View Clustering



Language Technologies Institute



Clustering definition: partition a set of data samples such that similar samples are grouped, and dissimilar samples are divided

How to discover groups in your data?

K-mean is a simple clustering algorithm based on competitive learning

- Iterative approach
 - Assign each data point to one cluster (based on distance metric)
 - Update cluster centers
 - Until convergence
- "Winner takes all"







Language Technologies Institute

"Soft" Clustering: Nonnegative Matrix Factorization

Given: Nonnegative n x m matrix M (all entries ≥ 0)



Want: Nonnegative matrices F (n x r) and G (r x m), s.t. X = FG.

- > easier to interpret
- > provide better results in information retrieval, clustering



Semi-NMF and Other Extensions

SVD:	$X_{\pm} \approx F_{\pm} G_{\pm}^T$
NMF:	$X_+ \approx F_+ G_+^T$
Semi-NMF:	$X_{\pm} \approx F_{\pm} G_{\pm}^T$
Convex-NMF:	$X_{\pm} \approx X_{\pm} W_{+} G_{+}^{T}$





Ding et al., TPAMI2015



Deep Semi-NMF Model



Trigerous et al., TPAMI 2015





Learn data partitioning from multiple views (modalities)

Views: different sources in diverse domains or obtained from various feature collectors or modalities

Example: Multiple views in computer vision - LBP, SIFT, HOG



Yan Yang and Hao Wang, Multi-view Clustering: A Survey, Big data mining and analytics, Volume 1, Number 2, June 2018



Principles of Multi-View Clustering

Two important principles:



Consensus principle: maximize consistency across multiple distinct views

2 **Complementarity principle:** multiple views needed to get more comprehensive and accurate descriptions



Yan Yang and Hao Wang, Multi-view Clustering: A Survey, Big data mining and analytics, Volume 1, Number 2, June 2018



Multi-view subspace clustering

Definition: learns a unified feature representation from all the view subspaces by assuming that all views share this representation





Enforcing Data Clustering in Deep Networks

How to enforce data clustering in our (multimodal) deep learning algorithms?





Deep Matrix Factorization



Li and Tang, MMML 2015





Other Multi-View Clustering Approaches

Graph-based clustering: search for a fusion graph (or network) across all views and then perform clustering



Yan Yang and Hao Wang, Multi-view Clustering: A Survey, Big data mining and analytics, Volume 1, Number 2, June 2018



Other Multi-View Clustering Approaches

Co-training: bootstraps the clustering of different views by using the learning knowledge from other views



Yan Yang and Hao Wang, Multi-view Clustering: A Survey, Big data mining and analytics, Volume 1, Number 2, June 2018





Auto-Encoder in Auto-Encoder Network



Language Technologies Institute





Given multiple views z_i from the same "object":



1) There is an "intact" representation which is *complete* and *not damaged*

2) The views z_i are partial (and possibly degenerated) representations of the intact representation



Auto-Encoder in Auto-Encoder Network

Zhang et al., CVPR 2019

