

$$O(nB)$$

↑ #items  
↑ size of bag

$$1) O(nV)$$

↑ sum of values  
 $V = \sum_{i=1}^n v[i]$

2) Hε approximation

$$O(n^2/\epsilon)$$

Input:  $S[1..n]$

$S[i]$  = size of  $i$ th item

$v[1..n]$

$v[i]$  = value of  $i$ th item

$B$

size of bag

Find  $S \subseteq \{1..n\}$  where  $\sum_{i \in S} s[i] \leq B$

maximize  $\sum_{i \in S} v[i]$

$$O(nV)$$

$$V := \sum_{i=1}^n v[i]$$

fast if values are small

vs

$$O(nB) \text{ fast if bag is small}$$

last time

$T[i, b]$  = max value if we have first  $i$  items available as option  
 $b$  is bag size

today

$T[i, v]$  = min bag size needed to pack  $v$  amount of value  
if we have first  $i$  items available as option to pack.

base case

$$T[i, 0] = 0 \quad // \text{no value} \rightarrow \text{no bag}$$

$$T[0, w] = \infty \quad \forall w \quad // \text{no items available, so store worst possible size of bag}$$

recursion

$$T[i, w] = \min \left( \underline{T[i-1, w]}, \underline{T[i-1, w - v[i]]} + s[i] \right)$$

**█** if we do not pack  $i$ -th item      **█** if we do pack  $i$ -th item

**H** if we do not pack  $i$ -th item      **I** if we do pack  $i$ -th item

result:

return largest  $W \leq \sum_{i=1}^n v[i]$  such that  $T[n, W] \leq B$

$LW = 0$   
 for  $w = 0 \dots \sum v[i]$   
 if  $T[n, w] \leq B$   
 $LW = w$   
 return  $LW$

Complexity  $O(n \cdot \sum v[i])$  to fill the table

Hence  $O(\sum_{i=1}^n v[i])$  to find value to return

$$\Rightarrow O\left(n \sum_{i=1}^n v[i]\right)$$

Next  $(1-\epsilon)$ -approximation in  $O(n^2/\epsilon)$  time.

$OPT :=$  maximum value that can be packed in a bag of size  $B$

$\tilde{W} :=$  value returned by algorithm

We want  $OPT \geq \tilde{W} \geq (1-\epsilon) \cdot OPT$

eg for  $\epsilon = 0.01$   
 we get a solution that is at most 1% off

Idea: make values  $v[1] \dots v[n]$  smaller

$$O\left(n \cdot \sum \tilde{v}[i]\right)$$

Input:  $S[1 \dots n]$   
 $v[1 \dots n]$   
 $B, \epsilon$

$$= O\left(n \sum_i \left(\frac{v[i]}{v_{max}} \cdot nk\right)\right)$$

$$v_{max} = \max_{1 \leq i \leq n} v[i]$$

$$\tilde{v}[i] = \left\lfloor \frac{v[i]}{k} \right\rfloor \quad \text{where } k = \frac{v_{max}}{n} \cdot \epsilon$$

return PrevAlgo( $S[1 \dots n], \tilde{v}[1 \dots n], B$ )  $\cdot k$  //  $\tilde{W}$

$\tilde{W} \leq OPT$  because of division and multiplication by  $k$  and rounding down

Let  $\tilde{S} \subseteq \{1 \dots n\}$  is that was used by PrevAlgo to get  $\sum_{i \in \tilde{S}} \tilde{v}[i] \cdot k = \tilde{W}$

Let  $S \subseteq \{1 \dots n\}$  be the optimal solution:  $\sum_{i \in S} v[i] = OPT$

Let  $S \subseteq \{1 \dots n\}$  be the optimal solution:  $\sum_{i \in S} v[i] = \text{OPT}$

Claim:  $\sum_{i \in \tilde{S}} v[i] \geq (1-\epsilon) \cdot \sum_{i \in S} v[i]$

$\sum_{i \in \tilde{S}} \tilde{v}[i] \cdot k \geq (1-\epsilon) \cdot \sum_{i \in S} v[i]$

$\sum_{i \in \tilde{S}} v[i] \geq \sum_{i \in \tilde{S}} \tilde{v}[i] \cdot k \geq k \cdot \sum_{i \in \tilde{S}} \tilde{v}[i] \geq k \cdot \sum_{i \in S} \tilde{v}[i]$

$= k \cdot \sum_{i \in S} \left\lfloor \frac{v[i]}{k} \right\rfloor$

$\geq k \cdot \sum_{i \in S} \left( \frac{v[i]}{k} - 1 \right)$

$= \left( \sum_{i \in S} v[i] \right) - \sum_{i \in S} k$

$= \text{OPT} - |S| \cdot k$

$= \text{OPT} - |S| \cdot \frac{v_{\max}}{n} \cdot \epsilon$

$\geq \text{OPT} - v_{\max} \cdot \epsilon$

$\geq \text{OPT} - \text{OPT} \cdot \epsilon$

$= (1-\epsilon) \cdot \text{OPT}$

$\geq \text{OPT} - \frac{n \cdot v_{\max}}{n} \cdot \epsilon$   
 $\Rightarrow v_{\max} \leq \text{OPT}$

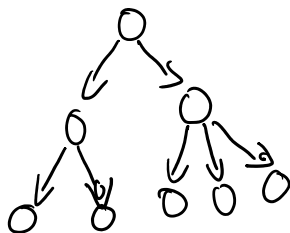
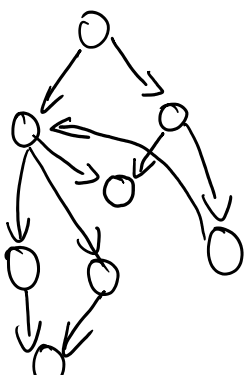
By assumption  
 $|S[i]| \leq B \forall i$

otherwise there is  
 no point in having that  
 item as option.

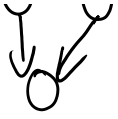
$\Rightarrow \text{OPT} \geq v[i] \forall i$

$\text{OPT} \geq v_{\max}$

DAG directed acyclic graph



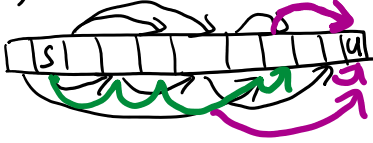
For Dyn. Prog. we often cut off  
 first or last piece of input to argue some



first or last piece of input to argue some recursion.

For DAGs

1) compute topological order



$$D[v] = \text{distance from } s \text{ to } v$$

$$D[u] = \min_{(v,u) \in E} (D[v] + c_{vu})$$

$\Rightarrow O(|E|)$  time to fill table

for  $u$  in topological order

$$D[u] = \min_{(v,u) \in E} (D[v] + c_{vu})$$