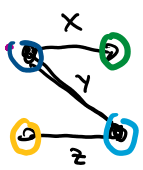
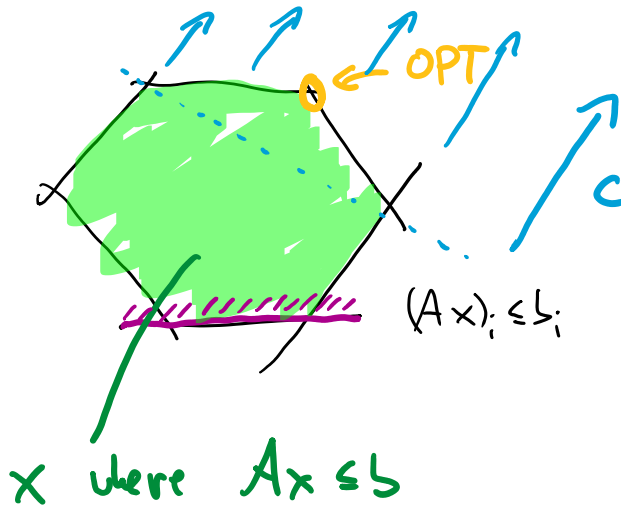
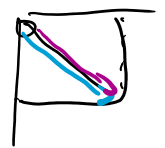
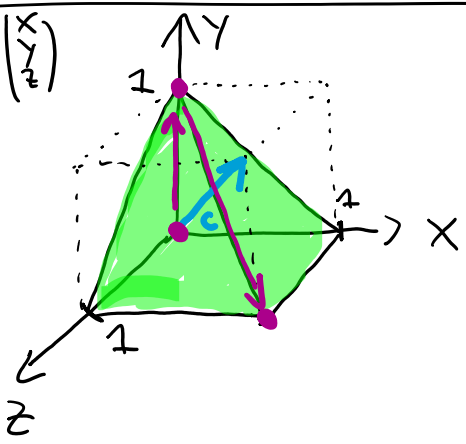


$$\begin{aligned} \max \quad & c^T x \\ \text{s.t.} \quad & Ax \leq b \\ & (Ax)_i \leq b_i \quad \forall i \end{aligned}$$



$$\begin{aligned} \max \quad & x+y+z = (1 \ 1 \ 1) \begin{pmatrix} x \\ y \\ z \end{pmatrix} \\ \text{s.t.} \quad & x \geq 0 \\ & y \geq 0 \\ & z \geq 0 \\ & x+y \leq 1 \\ & z+y \leq 1 \\ & x \leq 1 \\ & z \leq 1 \end{aligned}$$



$$\begin{aligned} \max \quad & \sum_{u,v \in E} w_{uv} \\ \text{s.t.} \quad & w \in \mathbb{R}^E \\ & w \geq 0 \\ & \sum_{u,v \in E} w_{uv} \leq 1 \quad \forall v \in V \end{aligned}$$

$$\begin{aligned} \sum (xyz) &= (000) \\ c^T(xyz) &= 0 \\ \sum (010) &= 1 \\ \sum (101) &= 2 \end{aligned}$$

$+(1 \ 1 \ 1)$

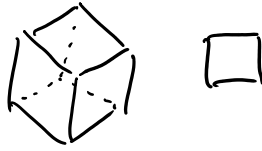
$$c^T(1 \ 1 \ 1) = 1$$

Idea: Start at some vertex of polytope  
 Go along edges from one vertex to another, always increasing the cost  
 of the polytope

Given  $2n$  constraints  
 how many vertices can there be?  
 $x \in \mathbb{R}^n \quad 0 \leq x_i \leq 1 \quad i=1 \dots n$

$$x \in \mathbb{R}^n \quad 0 \leq x_i \leq 1 \quad i=1 \dots n$$

Hypercube vertices are  $\{0,1\}^n$



Def: Given a polytope via  $Ax \leq b$

the polytope graph is  $G=(V,E)$

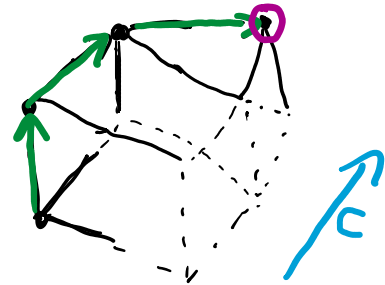
$V$  = vertices of the polytope  
 $E$  = edges of the polytope

Task: Find path from start vertex to optimal vertex.

Cannot simply create graph because it can be exponential size, see hypercube.

Input:  $A, b, c$  ( $\max c^T x \quad Ax \leq b$ )

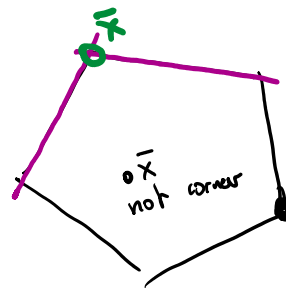
- Start at vertex
- Compute edges for this vertex
- Pick one edge that increases the cost
- go along that edge until we hit another vertex
- terminate if no edge improves the cost



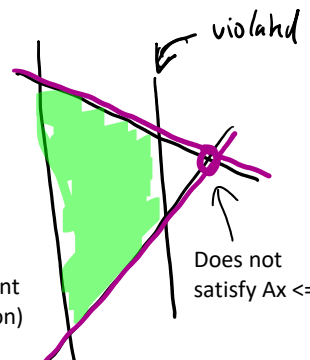
Def: Given  $Ax \leq b, A \in \mathbb{R}^{m \times d}$

then some  $\bar{x} \in \mathbb{R}^d$  is a corner/vertex of the polytope if and only if

- $A\bar{x} \leq b$
- $(A\bar{x})_i = b_i$  for  $d$  many linear independent constraints



$\bar{x}$  not a corner



Observation:

A set  $B \subseteq \{1 \dots n\}$

not a corner because the constraints are linearly dependent (Linear system  $A_B x = b_B$  does not have a unique solution)

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(Linear system  $A_B x = b_B$  does not have a unique solution)



satisfy  $Ax \leq b$

A set  $B \subseteq \{1, \dots, n\}$

is an alternative description of a corner

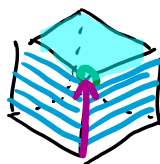
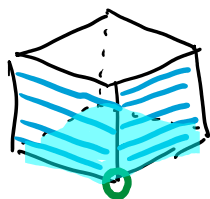
if  $A_B :=$  subset of rows of  $A$ , with index in  $B$

$$\bar{x} = A_B^{-1} b_B, \quad A_B \bar{x} = b_B$$

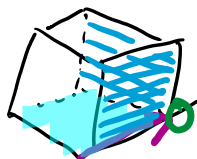
and  $\bar{x}$  is a corner (ie  $A \bar{x} \leq b$ )

Given  $A, b \quad \{x \in \mathbb{R}^d \mid Ax \leq b\} \leftarrow$  polytope

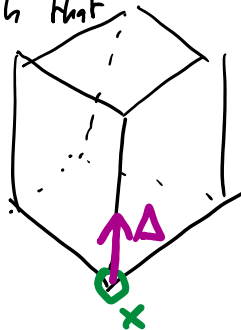
What are edges?



Going from vertex to vertex  
means to replace one index  $i \in B$   
by another index  $j$



Each  $i \in B$  we can remove corresponds to an edge  
How to decide which  $i \in B$ /edge to pick such that  
moving along edge improves  $c^T x$ ?



$$x^{new} \leftarrow x + \lambda \cdot \Delta$$

$\uparrow$   
 $\lambda \in \mathbb{R}$   
 $\lambda \geq 0$

$\Delta \in \mathbb{R}^d$  direction of edge

We need that  $c^T x^{new} > c^T x$

$$c^T (x + \lambda \cdot \Delta) = c^T x + \lambda \cdot \underbrace{c^T \Delta}_{> 0}$$

$$\Leftrightarrow c^T \Delta > 0$$

Given  $B, i \in B$  what is the direction  $\Delta$  of the edge represented by  $B, i \in B$ ?

Algorithm so far

Input:  $A, b, x$      $A \in \mathbb{R}^{n \times d}, b \in \mathbb{R}^n, x \in \mathbb{R}^d$ ,  $x$  is vertex

$B \subseteq \{1 \dots n\}$  such that  $A_B$  is full rank and  $A_B x = b_B$

compute  $\Delta_i$  for  $i \in B$  direction of edges (TODO)

pick  $i$  such that  $c^T \Delta_i > 0$

pick largest  $\lambda$  such that  $A(x + \lambda \cdot \Delta_i) \leq b$

$x \leftarrow x + \lambda \cdot \Delta_i$

$B \leftarrow (B \setminus \{i\}) \cup \{j\}$  where  $j$  is such that  $(A(x + \lambda \Delta_i))_j = b_j$   
but  $(Ax)_j < b_j$

