

Many fast algorithms are already implemented and available via libraries

Easier to use these compared to developing new algorithms.

Examples from HW:

- pattern matching / vector distances

$O(n \log n)$ algo by using polynomial multiplication

- Inequalities with 2 variables $x_i - x_j \leq c_{ij}$

Using LP algorithm would have been difficult

Instead we just run Bellman Ford (finding neg. cycle in graph)

These are reductions

Solve Problem A via algorithm for Problem B

Pattern Matching reduces to polynomial multiplication

2 var per inequality LP reduces to negative weight shortest path/cycle

Benefits:

1) Makes algorithm design easier. Use existing algos.

2) Allows us to argue how easy/hard problems are relative to each other.

If we believe that $O(n \log n)$ time is the best possible for pattern matching

then we must also believe that $O(n \log n)$ for polynomial multiplication is the best.

Reason: (if there was faster (eg $O(n)$ time) algo for poly multiplication

then we could solve pattern matching in $O(n)$

but that would contradict our belief.

Referred to as "conditional lower bound" because the lower bound

Referred to as "conditional lower bound" because the lower bound of $\Omega(n \log n)$ for poly. mult. depends on the condition that pattern matching needs $\Omega(n \log n)$

You came up with algo

but it is slow.

Should we spend more effort/time finding something faster?

Can we explain why it's hard?

Can we find some necessary condition/relaxation (eg approximate output) that is needed for a faster algorithm?

Example: Nearest Neighbor Data Structure

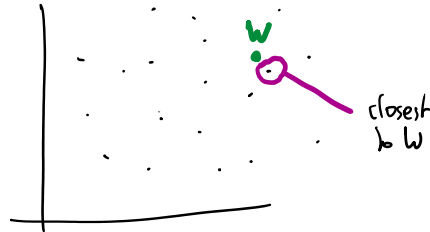
store each v_i $(v_1, v_2, \dots, v_n \in \mathbb{R}^d)$

$O(nd)$ v_i
 \rightarrow Query $(w \in \mathbb{R}^d)$

Return v_i
 that is closest
 to w

$$\min_i \|w - v_i\|_2$$

$$\|u - v\|_2 = \sqrt{\sum_{i=1}^d (u_i - v_i)^2}$$

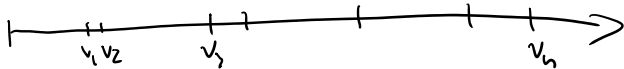


for-loop
 by each v_i

$O(nd)$

Compare to $d=1$ case

v_1, \dots, v_n are $\in \mathbb{R}$ so can sort them



then binary search during query

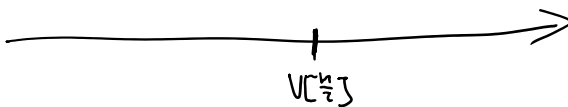
Search $(V[1..n], w)$

if $V[\frac{n}{2}] > w$

recurse on $V[1.. \frac{n}{2}]$

else

recurse on $V[\frac{n}{2}..n]$



init $O(n \log n)$

Query $O(\log n)$

Next: Argue that we cannot do better than $O(nd)$ search/query.

Def: OV-Problem (orthogonal vector)

Input $v_1, v_2, \dots, v_n \in \{0, 1\}^d$
 $w_1, w_2, \dots, w_n \in \{0, 1\}^d$

Output Yes/No if there exists $w_i^T v_j = 0$
 ie pair of orthogonal vectors

Naive algo, try all n^2 pairs
 $O(n^2 d)$ time.

Question is this optimal? Could we do $O(n^{1.999} \text{poly}(d))$?

Def: OV-conjecture

there exists no algorithm for the OV-Problem
 with $O(n^{2-\epsilon} \text{poly}(d))$ time.

Remark $O(\frac{n^2}{\log n} \text{poly}(d))$ exists

$$\frac{n^2}{\log n} = n^2 - \frac{\log \log n}{\log n} \rightarrow \text{goes to } 0 \text{ for large inputs}$$

Conjecture basically says that no better than \log improvements
 are possible.

Reduction from OV to NN data structure

Use NN data str. to solve OV problem.

OV $(v_1, v_2, \dots, v_n \in \{0, 1\}^d, w_1, \dots, w_n \in \{0, 1\}^d)$

$$\text{for } i=1 \dots n$$

$$\tilde{v}_i = \begin{pmatrix} v_i \\ \mathbb{1} - v_i \\ \vdots \\ 0 \end{pmatrix} \in \{0, 1\}^{3d}$$

$$\tilde{w}_i = \begin{pmatrix} -w_i \\ \vdots \\ 0 \end{pmatrix} \in \{-1, 0, 1\}^{3d}$$

// $\mathbb{1} - v_i$ is vector v_i
 but we flip the
 0 s and 1 s

$$= d + d - 2 \tilde{v}_i^T \tilde{w}_i$$

$$\bar{w}_i = \begin{pmatrix} -w_i \\ \vdots \\ 0 \\ \vdots \\ 1-w_i \end{pmatrix} \in \mathbb{R}^{2d}$$

$$= d + d - 2\bar{v}_j^T \bar{w}_i$$

$$\| \bar{v}_j - \bar{w}_i \|_2^2 = \| \bar{v}_j \|_2^2 + \| \bar{w}_i \|_2^2 - 2\bar{v}_j^T \bar{w}_i$$

$$\sum_{k=1}^d (\bar{v}_j)_k^2 = \# \text{ of } 1\text{s in } \bar{v}_j = d$$

NN. Init ($\bar{v}_1, \bar{v}_2, \dots, \bar{v}_n$)

for $i=1 \dots n$

$\bar{v}_j =$ NN. Query (\bar{w}_i)

if $\| \bar{v}_j - \bar{w}_i \|_2 = \sqrt{2d}$

return True // $v_i^T u_i = 0$

return false // no orthogonal pair exists.

$$\| \bar{v}_j - \bar{w}_i \|_2^2 = 2d \iff \bar{v}_j^T \bar{w}_i = 0 \iff v_j^T w_i = 0$$

$$\bar{v}_j^T \bar{w}_i \leq 0 \quad \forall i, j, \quad v_j^T w_i \geq 0$$

$$\| \bar{v}_j - \bar{w}_i \|_2^2 = 2d - 2\bar{v}_j^T \bar{w}_i = 2d + 2v_j^T w_i \geq 2d$$

If there exists $v_j^T u_i = 0$

$$\text{Then } \| \bar{v}_j - \bar{w}_i \|_2^2 = 2d \leq \| \bar{v}_{j'} - \bar{w}_{i'} \|_2^2 \quad \forall i', j'$$

so also returns true

If there is no $v_j^T u_i = 0 \Rightarrow v_j^T u_i \geq 1$

$$\Rightarrow \| \bar{v}_j - \bar{w}_i \|_2^2 = 2d + 2v_j^T u_i \geq 2d + 2 \quad \forall i, j$$

\Rightarrow so also must return false

Time complexity

$P(n, d)$ time for init of NN

$Q(n, d)$ time for query of NN

Then OV can be solved in time $O(nd + P(n, d) + nQ(n, d))$

If $P(n, d) = n^{2-\epsilon} \text{poly}(d)$ then OV can be solved in $O(nd + n^{2-\epsilon} \text{poly}(d) + n \cdot n^{1-\epsilon} \text{poly}(d))$
 $= O(n^{2-\epsilon} \text{poly}(d))$

Assuming the OV-conjecture

then there is no NN data structure with subquadratic initialization time
and sublinear query time.